

# 30<sup>th</sup> EWGLAM and 15<sup>th</sup> SRNWP meetings

6<sup>th</sup> -9<sup>th</sup> October 2008

Madrid, SPAIN

**TIGGE-LAM:**

**Multi-model short-range probabilistic forecasting –  
scientific objectives and practical possibilities**

*Tiziana Paccagnella*

*ARPA-SIM*

*Italy*



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EWGLAM SRNWP 2008 Madrid 6-8 October

# Ensemble Prediction

- ❑ Ensemble prediction is based on the knowledge of the chaotic behaviour of the atmosphere and on the awareness of the limitation (errors, approximations) in our Forecasting Systems (analysis/assimilation & models).

These limitations induce uncertainty in our forecasts.

- ❑ Ensemble prediction is aimed to quantify this uncertainty by producing a sample of alternative/possible future atmospheric states obtained by mimic our possible errors.
- ❑ Uncertainty derives from errors both in the analysed initial conditions (analysis errors) and in the forecast evolution (model errors).

# Ensemble Prediction

## □ Deterministic thinking

- ↳ To obtain EPS products which are better than deterministic products (e.g. 500 hPa ensemble mean)
- ↳ To obtain a forecast of the forecast skill

## □ Probabilistic thinking

- ↳ To have alternative evolution scenarios
- ↳ To have probabilities associated to the occurrence of events

# Ensemble Prediction

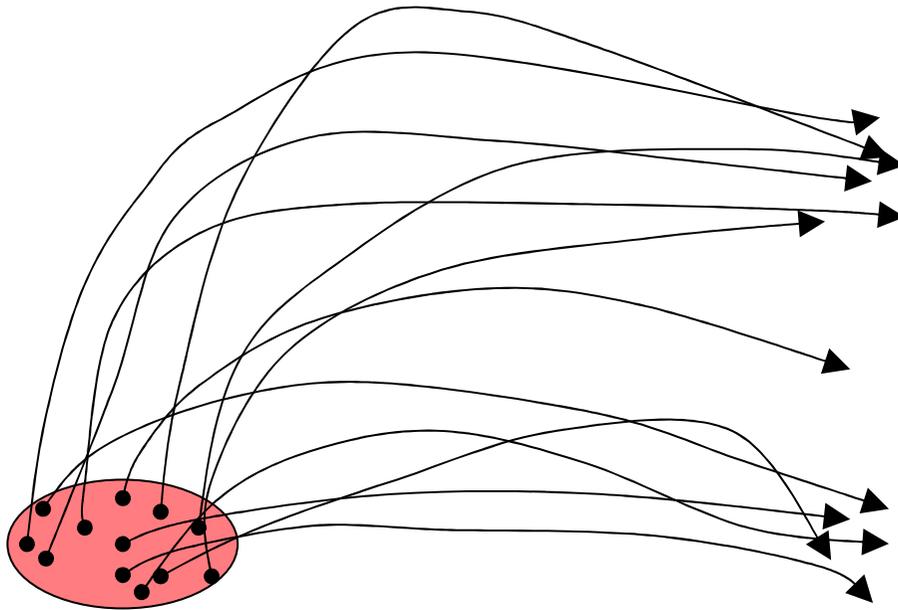
## □ Deterministic thinking

- ↳ To obtain EPS products which are better than deterministic products (e.g. 500 hPa ensemble mean)
- ↳ To obtain a forecast of the forecast skill

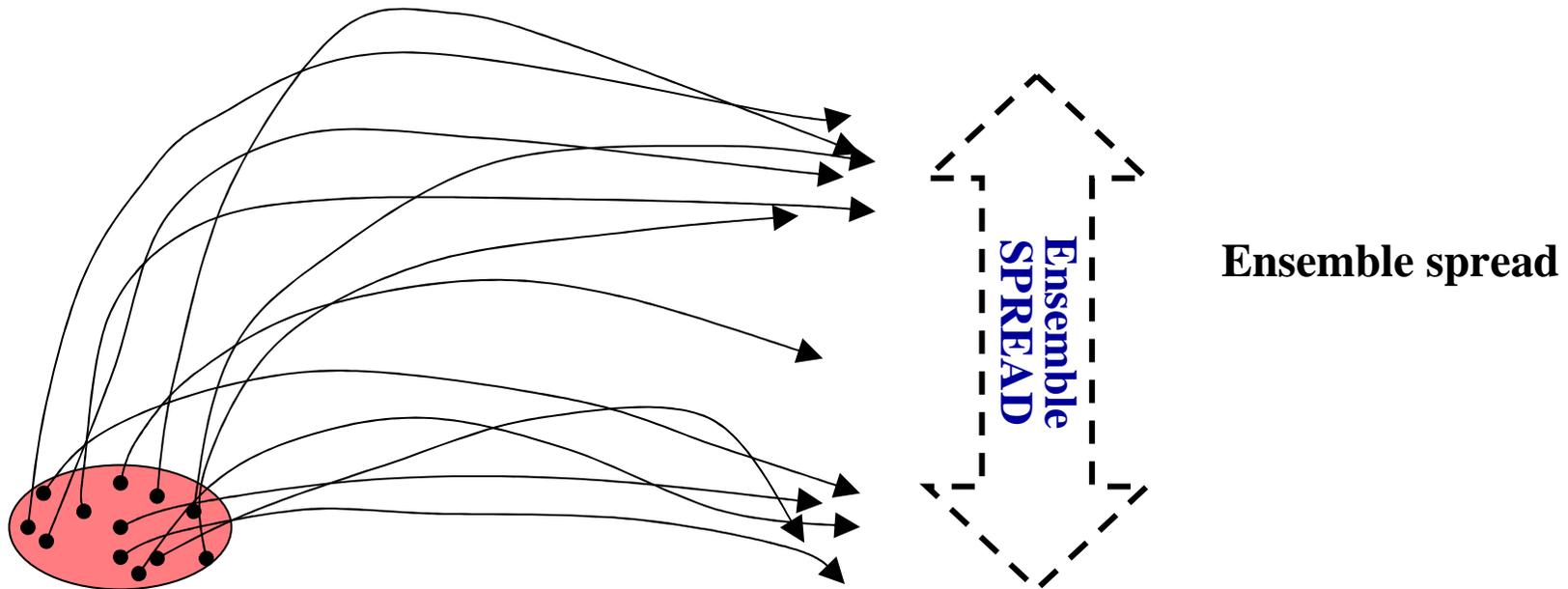
## □ Probabilistic thinking

- ↳ To have alternative evolution scenarios
- ↳ To have probabilities associated to the occurrence of specific events

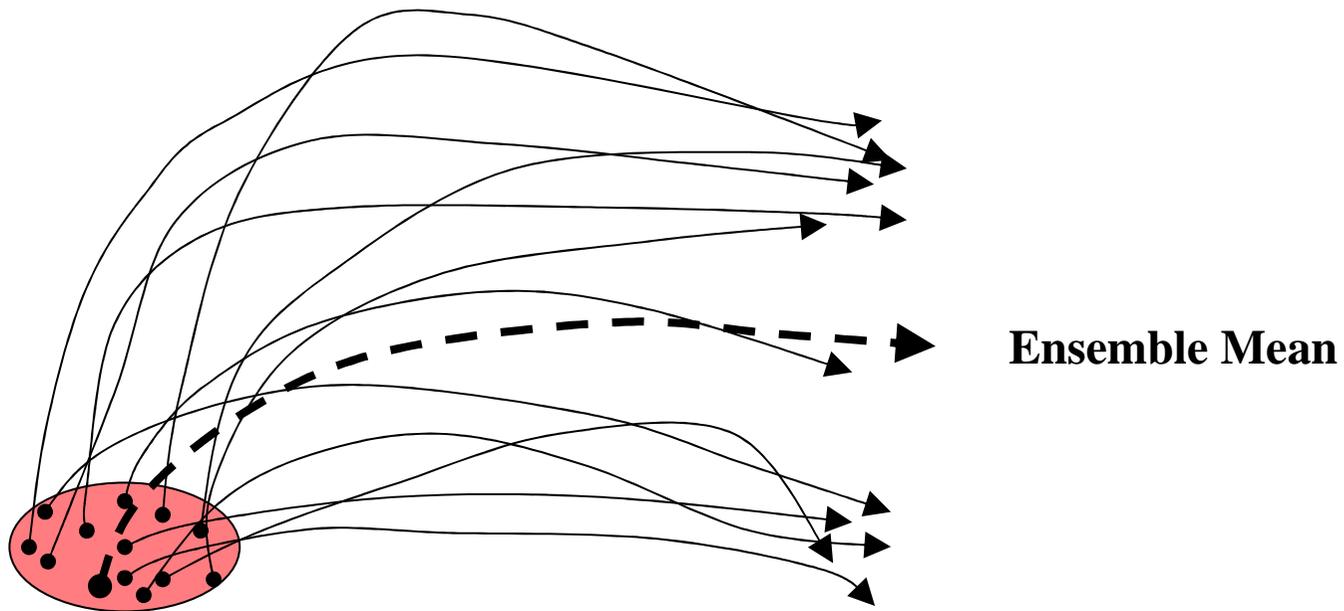
# Ensemble System Characteristics



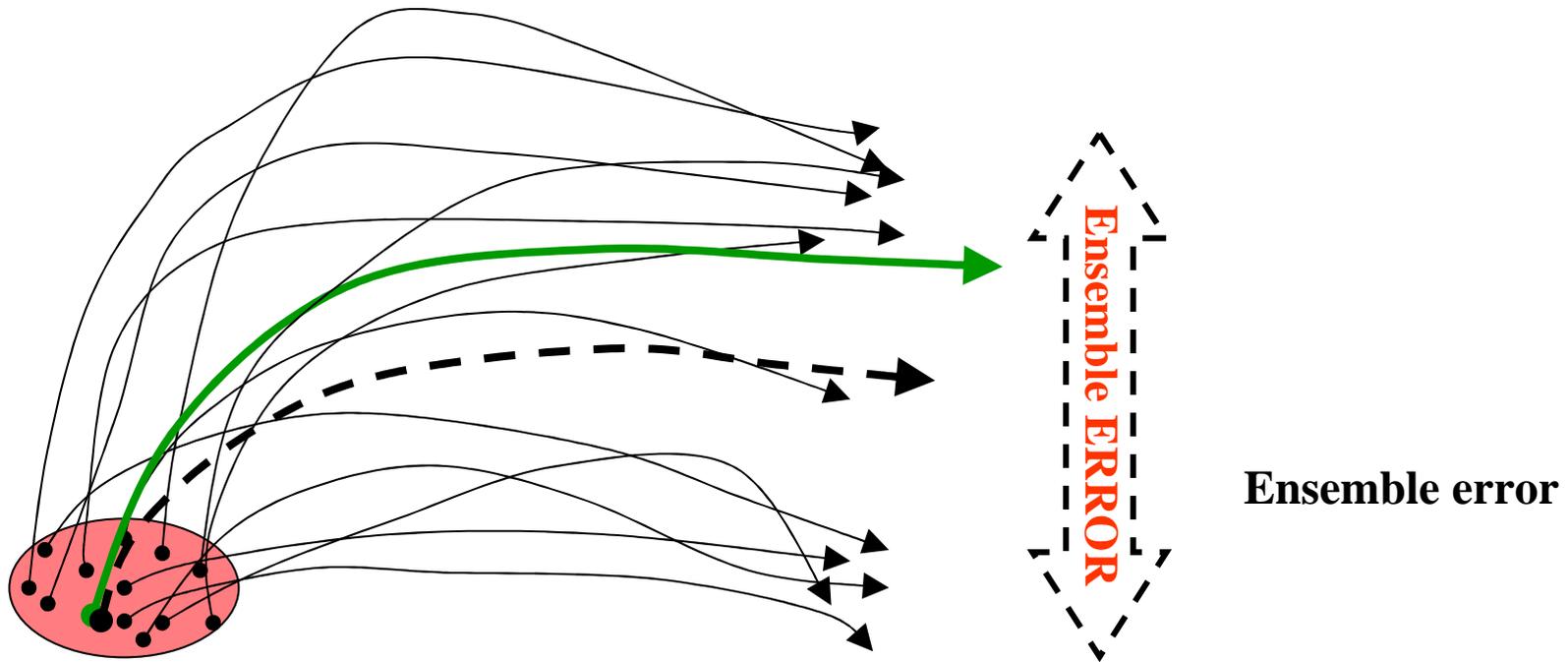
# Ensemble System Characteristics

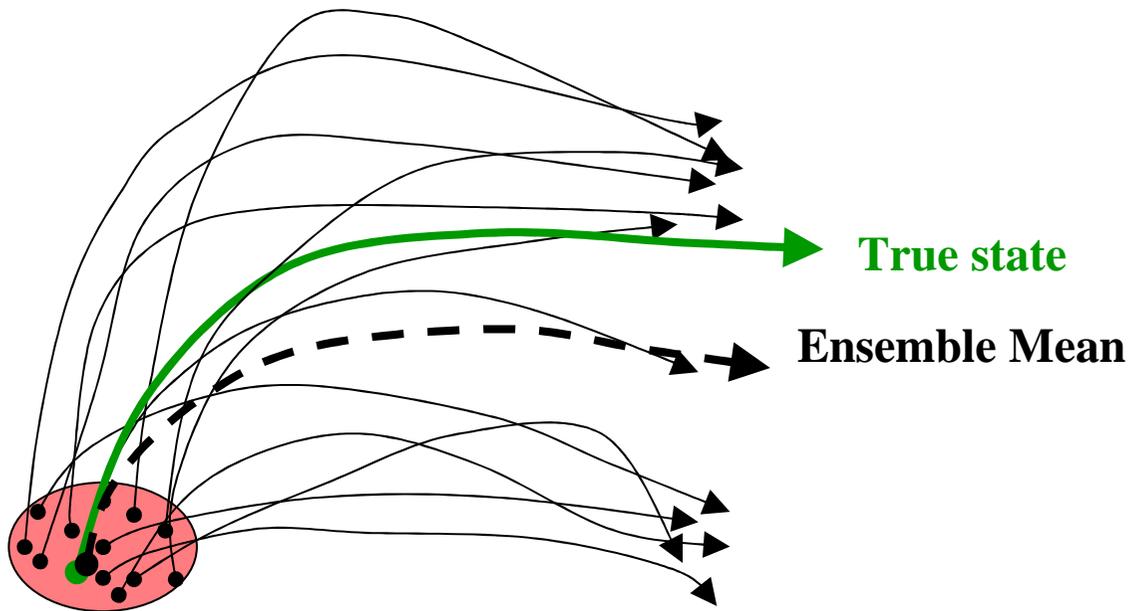


# Ensemble System Characteristics



# Ensemble System Characteristics



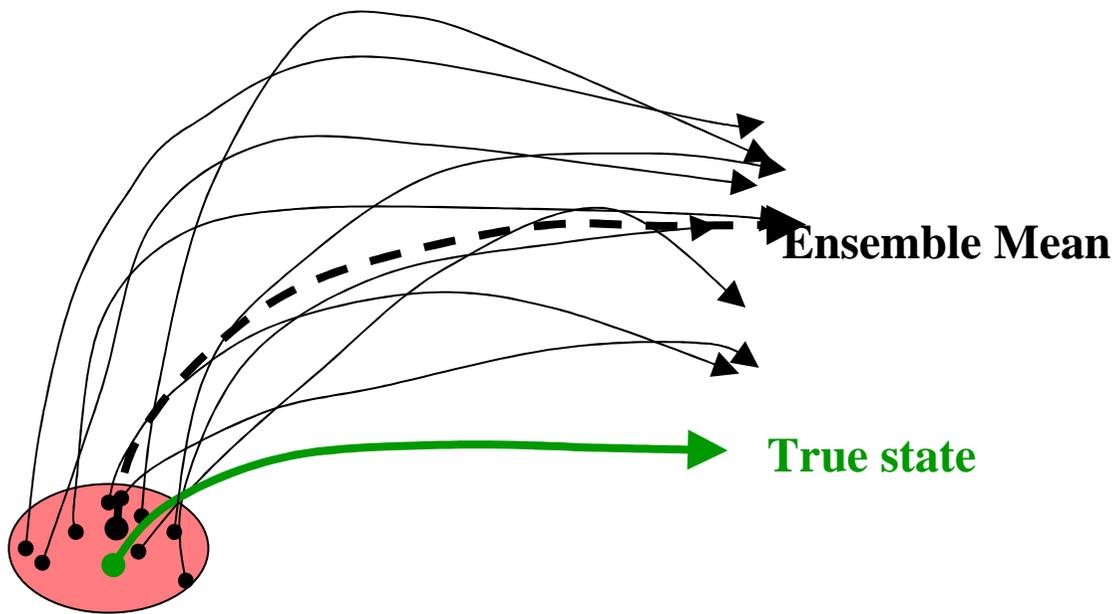


Ensemble ERROR

Ensemble SPREAD

Climatology

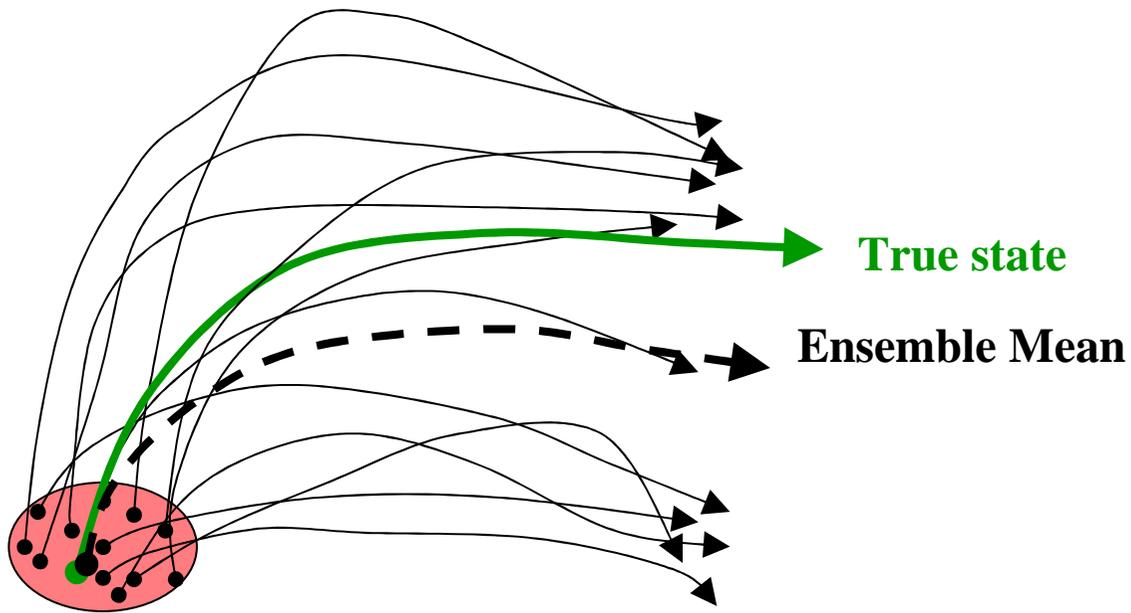
GOOD !!!



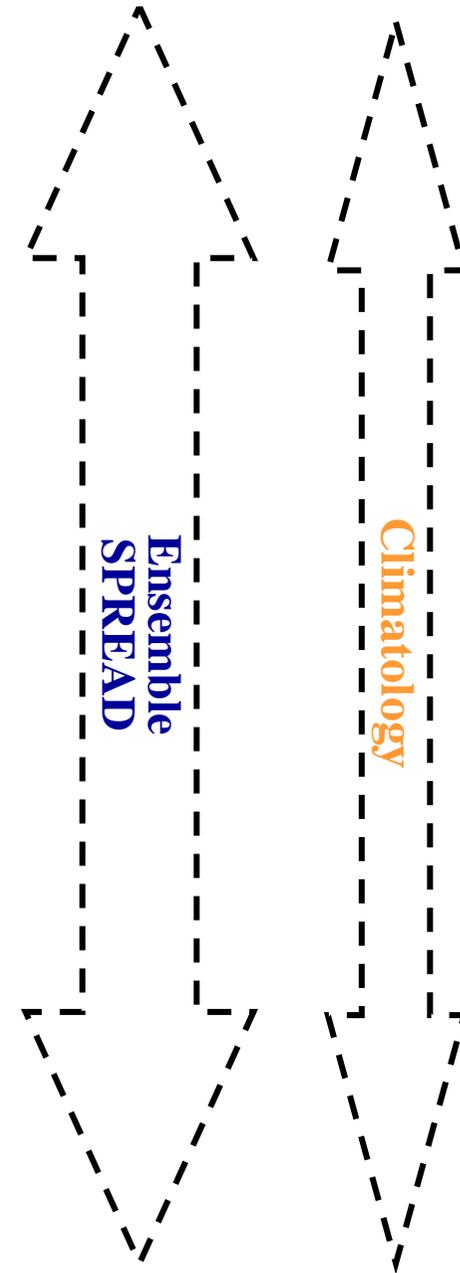
Ensemble ERROR

Ensemble SPREAD

**BAD !!!**



**BAD !!!**



**Model Errors**

**Accounting for uncertainties in  
Numerical forecast**

**Analysis Errors**

## Model Errors

**Perturbations/changes  
Model parameters  
Stochastic Physics**

**Changes of model  
modules**

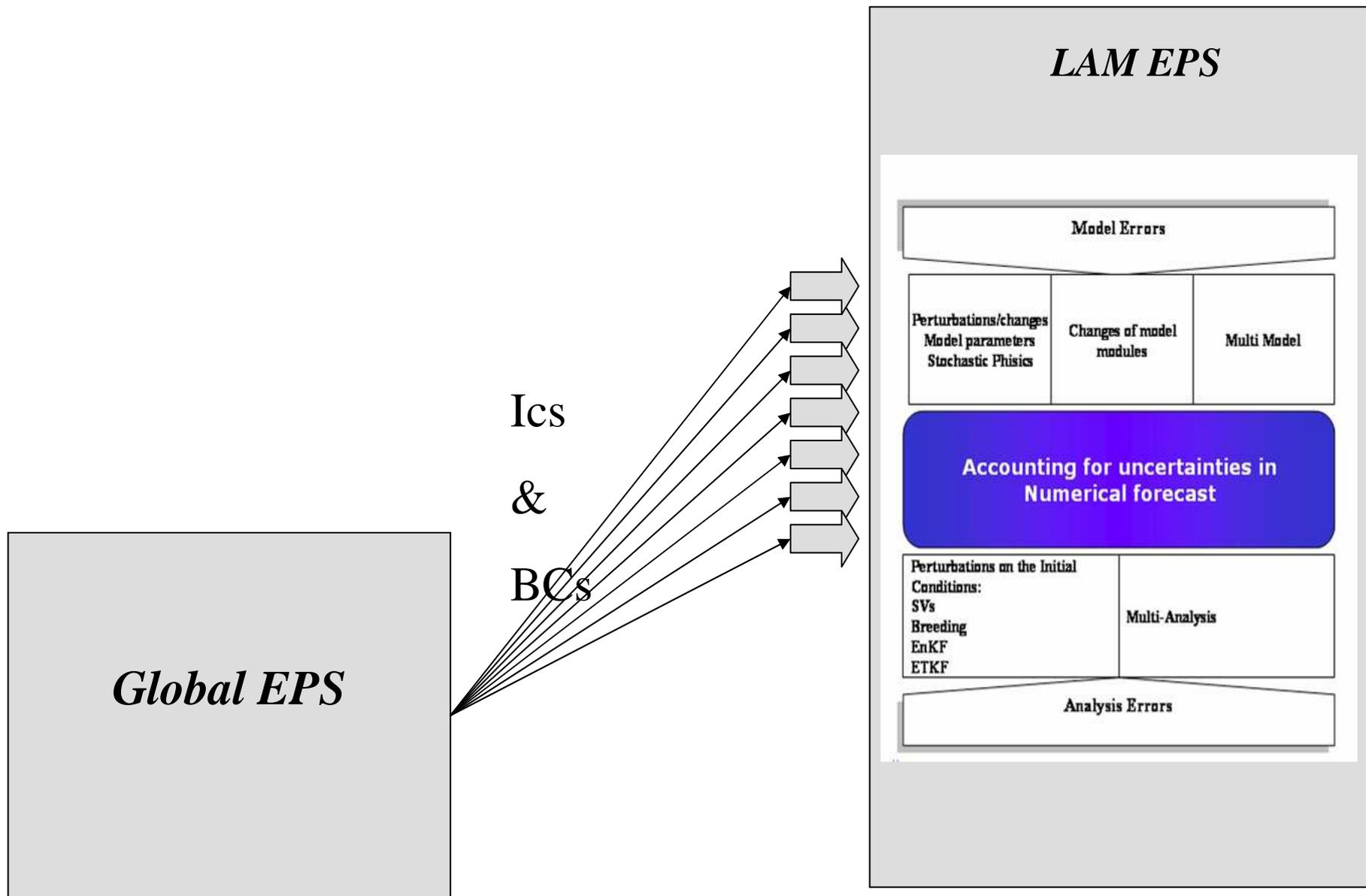
**Multi Model**

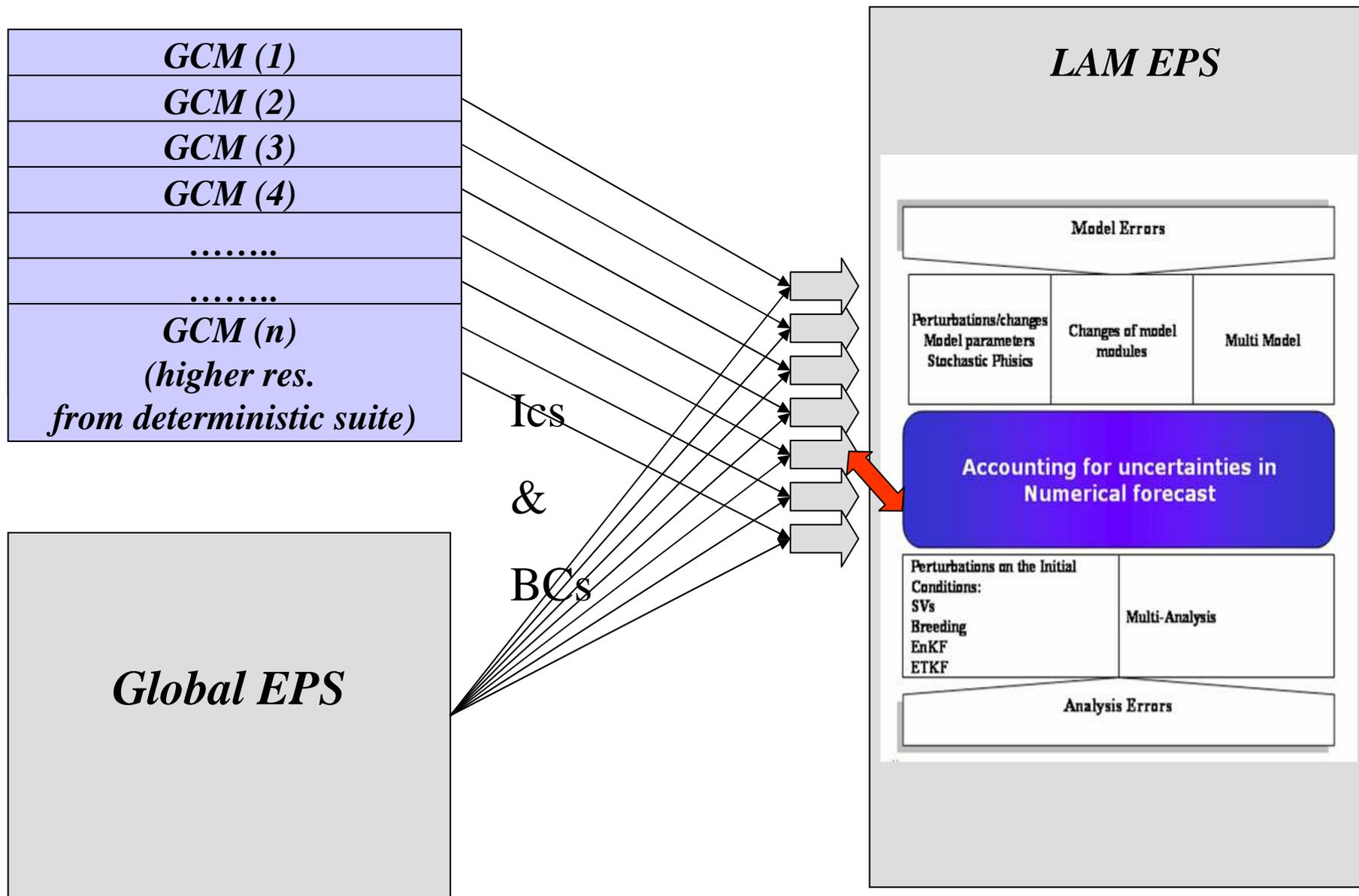
## Accounting for uncertainties in Numerical forecast

**Perturbations on the Initial  
Conditions:  
SVs  
Breeding  
EnKF  
ETKF**

**Multi-Analysis**

## Analysis Errors





- ❑ **Intuitively, a practical and efficient way to account for our possible errors is to initialize models with**
  - ↳ analyses obtained by independent systems (MA)
  - ↳ and to use different forecast models (MM)
  
- ❑ **Quality and efficiency come from: the same quality but different genetics**
  
- ❑ **This approach requires a lot of interoperability among the different systems**

# Multi-Model

Nowadays the concept of multi-model must be articulated:

## Global EPS

- ↳ Multi Model
- ↳ MultiModel & Multi Analysis (MumMa)
- ↳ Grand Ensemble

## LAM Systems

- ↳ Multi Model
- ↳ Multi Model ICs&BCs
- ↳ Grand Ensemble
- ↳ Grand Ensemble ICs & BCs

Some work has been done in the last ten years to assess the advantage of a Multi-Model Ensemble-Grand Ensemble approaches but a systematic and comprehensive evaluation requires an extensive cooperation



Science

Operations

**TIGGE**

**The THORPEX Interactive  
Grand Global Ensemble**

**Status in September 2008**

Philippe Bougeault, ECMWF

Zoltan Toth, NCEP

(Co-chairs of the GIFS-TIGGE WG)

**Recent research  
results based on  
TIGGE**

*Acknowledgments to*

EMS 2008

Slide 1



Young-Youn Park, KMA

Renate Hagedorn, ECMWF

Florian Pappenberger, ECMWF

Richard Swinbank et al., UK Met Office

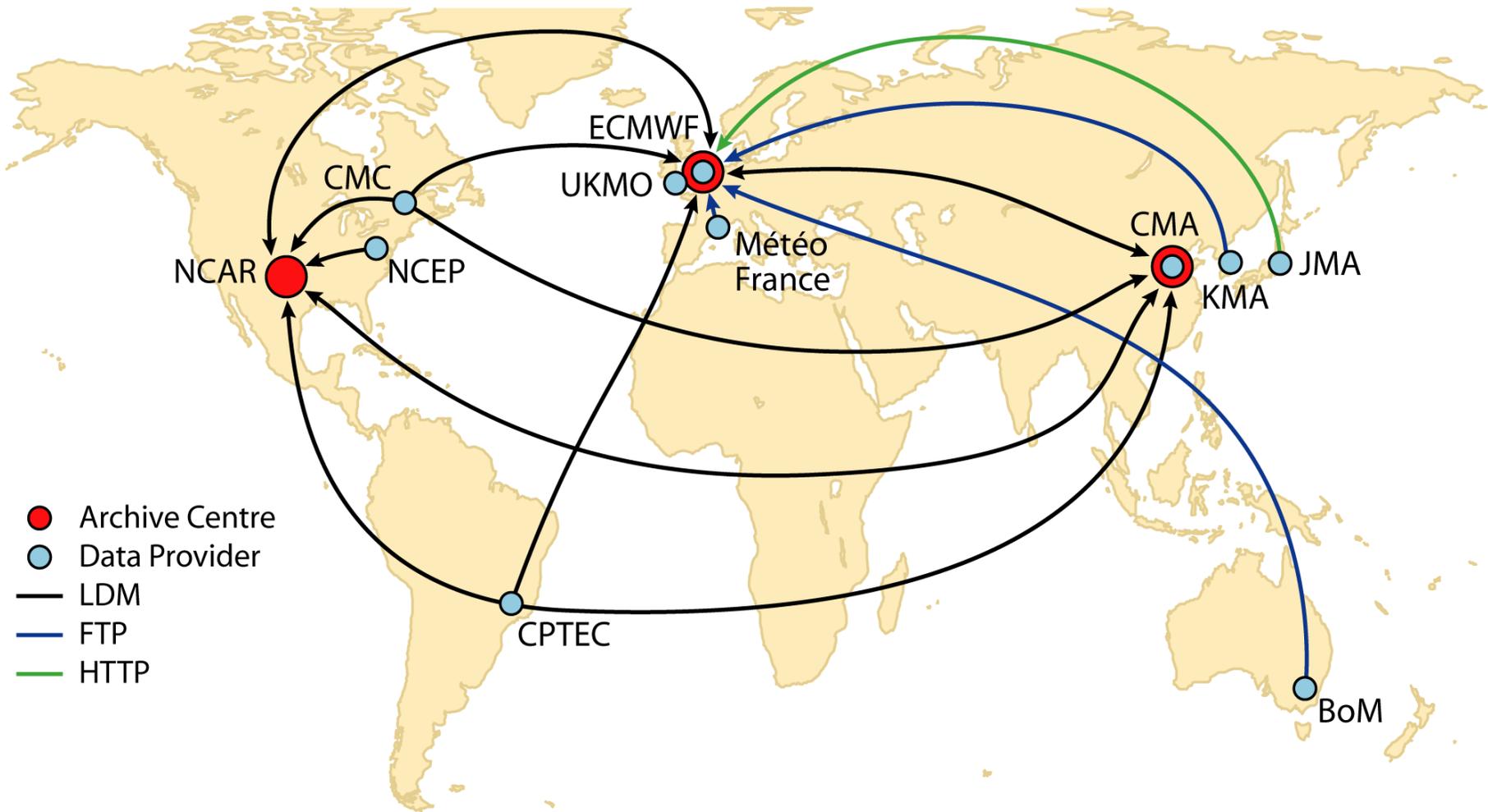
Courtesy of P. Bougeault and Z. Toth



# **TIGGE objectives (agreed in March 2005)**

- **Enhance international collaboration on ensemble prediction for severe weather**
  - **Collaboration between operational centres and universities**
- **Develop theory and practice of multi-model ensembles**
- **Examine the feasibility of interactive ensembles responding dynamically to changing uncertainty**
- **Develop the concept of a Global Interactive Forecasting System (GIFS)**

# TIGGE data exchanges (6 to 30h after real time)



Courtesy of P. Bougeault and Z. Toth

# TIGGE Database contents by provider

	BOM	CMA	CMC	CPTEC	ECMWF	JMA	KMA	MF	NCEP	UKMO
<b>Standard Fields (Out of 73)</b>	<b>55</b>	<b>60</b>	<b>56</b>	<b>55</b>	<b>70</b>	<b>61</b>	<b>46</b>	<b>62</b>	<b>59</b>	<b>70</b>
<b>Ensemble Members</b>	<b>33</b>	<b>15</b>	<b>21</b>	<b>15</b>	<b>51</b>	<b>51</b>	<b>17</b>	<b>11</b>	<b>21</b>	<b>24</b>
<b>Forecast Length (Day)</b>	<b>10</b>	<b>10</b>	<b>16</b>	<b>15</b>	<b>15</b>	<b>9</b>	<b>10</b>	<b>3</b>	<b>16</b>	<b>15</b>
<b>Forecast cycles per Day</b>	<b>2</b>	<b>2</b>	<b>2</b>	<b>2</b>	<b>2</b>	<b>1</b>	<b>2</b>	<b>1</b>	<b>4</b>	<b>2</b>

*(As of May 1, 2008)*

Courtesy of P. Bougeault and Z. Toth

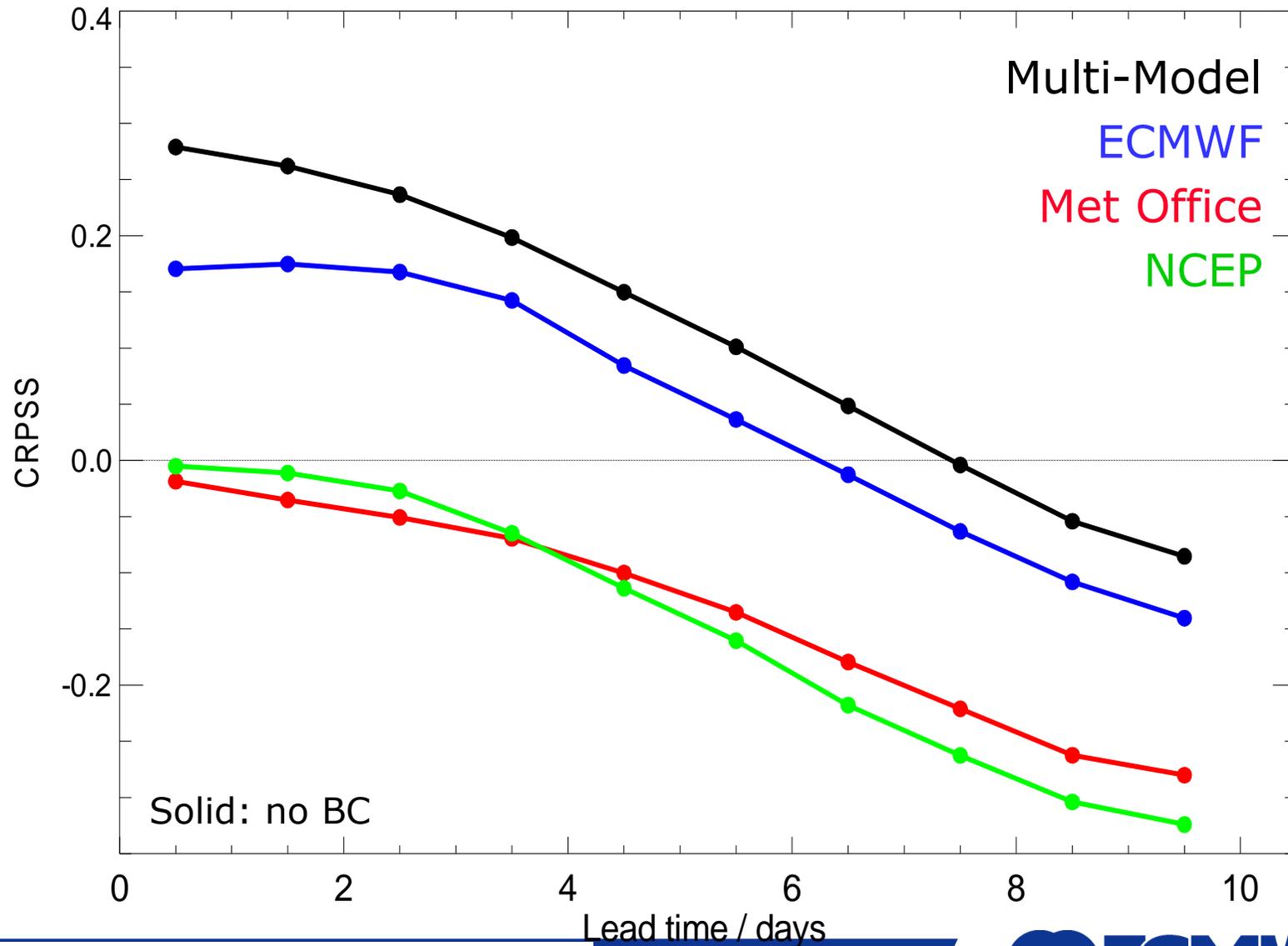


# **Upper air variables (preliminary conclusions from last year talk, broadly confirmed by more recent studies)**

- **Significant differences in quality between the systems**
  - Up to 3 days differences in probabilistic forecast skill
  - Agreement between spread and skill is the most variable aspect and has a strong impact on probabilistic skill scores
  - In the Tropics the spread is underestimated by almost all systems
- **Impact of the verification analysis**
  - Relatively little impact in the extra-Tropics (as long as the analysis comes from one of the best systems)
  - Large impact in the Tropics (and difficult to decide which is the best analysis)
- **Skill of multi-model system versus single-model systems**
  - Only marginal improvement in the extra-Tropics
  - Significant improvement in the Tropics (subject to significant bias corrections)

# Verification of T2m against observations

T-2m, 250 European stations  
2008060100 - 2008073000 (60 cases)

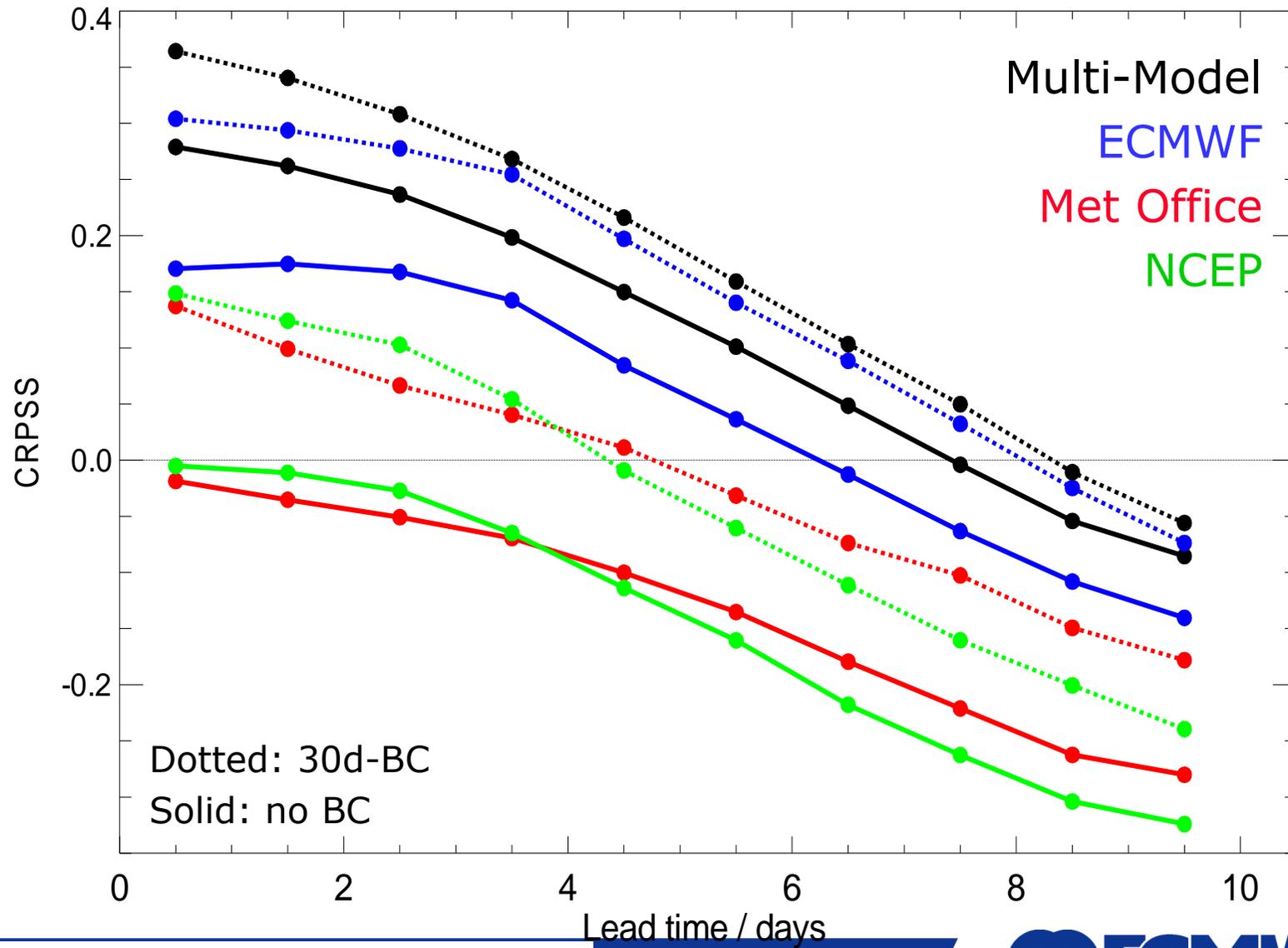


Courtesy of P. Bougeault and Z. Toth



# Verification of T2m against observations

T-2m, 250 European stations  
2008060100 - 2008073000 (60 cases)



Courtesy of P. Bougeault and Z. Toth



# **Preliminary conclusions for T2m (very tentative!)**

- **Results are sensitive to the choice of verifying analysis**
- **Generally speaking, MM is better than any single model**
- **Generally speaking, MM superiority comes from ECMWF, and ECMWF alone is better than any MM without ECMWF**
- **Calibration using recent forecasts reduces the superiority of the MM but does not change the above conclusions**
- **Calibration using a special set of re-forecasts may offset completely the superiority of the MM (?)**
- **The superiority of the MM may also be challenged if uncertainty in soil moisture is added in the single systems**

Courtesy of P. Bougeault and Z. Toth

**TIGGE: preliminary results on  
comparing and combining  
ensembles**

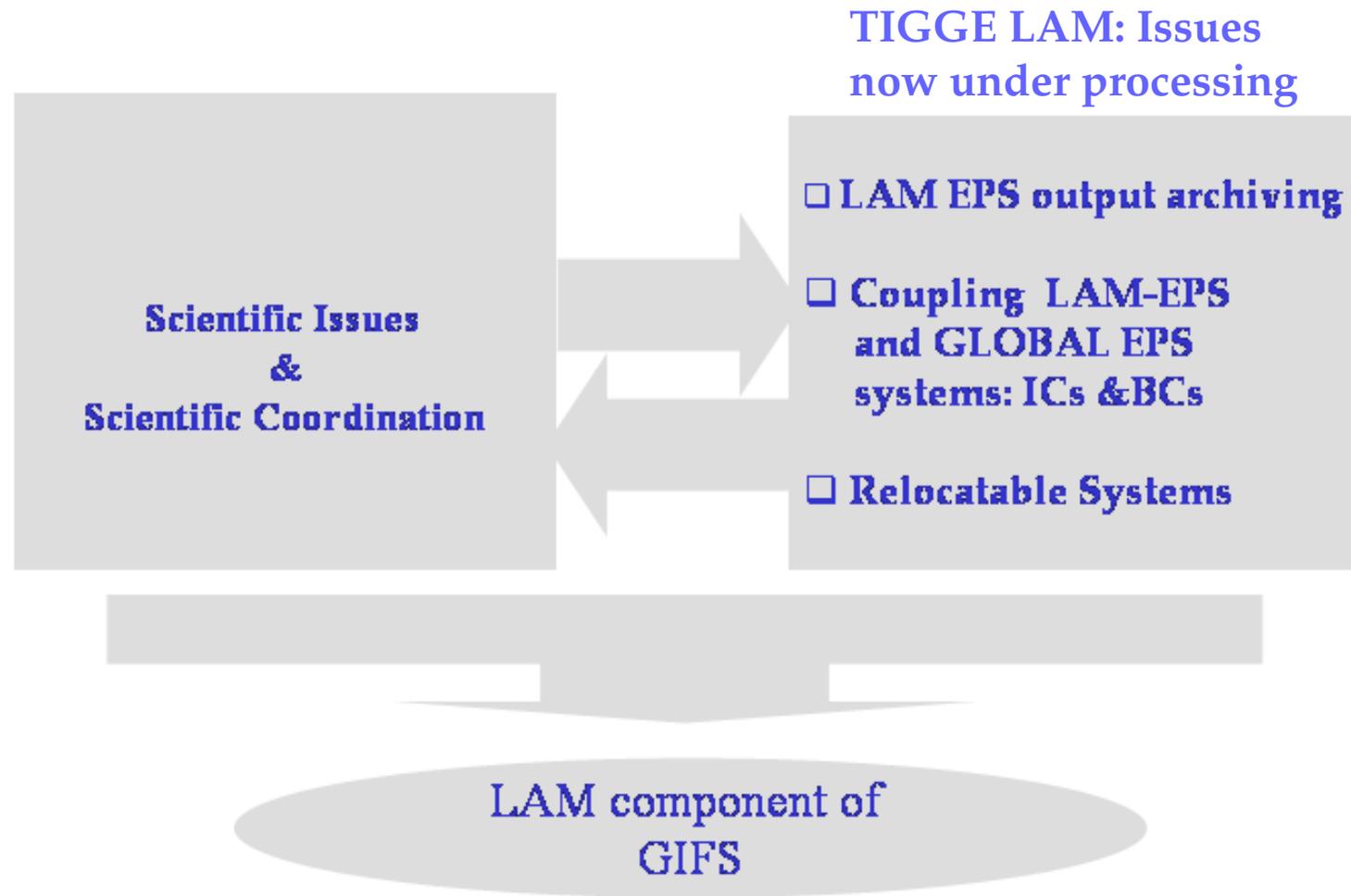
Young-Youn Park<sup>1</sup>, Roberto Buizza  
and Martin Leutbecher

Research Department

## **Additional work**

- **Confirm results on longer time series, with more observations**
- **Examine other weather parameters**
  - Rainfall, 10m wind, clouds, etc....
- **Examine impact of multi-model on applications (end-to-end forecast systems)**
  - Obvious example is with ensemble hydrological forecasts forced by TIGGE, and initial results are supporting superiority of MM
- **Use TIGGE MM as a benchmark to improve single-model systems**
  - Real scientific progress would be to encapsulate all aspects of uncertainty in a single, optimal system: TIGGE can help us to locate and repair the deficiencies of existing operational EPSs

# LAM EPS & TIGGE LAM



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THORPEX week – Geneva 22-26 September 2008



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EWGLAM SRNWP 2008 Madrid 6-8 October

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ALADIN LAEF	ZAMG / Austria	Yong Wang	wang@zamg.ac.at
OMSZ ALADIN EPS	Hungary	Edit Hagel	hagel.e@met.hu
<b>United States</b>			
NCEP-SREF	NCEP	Jun Du	Jun.Du@noaa.gov
<b>China</b>			
CMA-WRF LEPS	CMA/China	Jiandong Gong	gongjd@cma.gov.cn
<b>Japan</b>			
JMA MRI EPS	MRI/Japan	Kazuo Saito	ksaito@mri-jma.go.jp

**TIGGE  
LAM EPS  
systems  
“registered”  
by sending  
Spreadsheet  
information file**



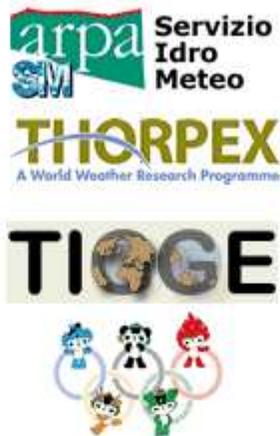
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EWGLAM SRNWP 2008 Madrid 6-8 October

LAM EPS System	Institute -Consortium	Contact person
<b>Europe</b>		
<b>COSMO DE EPS</b>	<b>DWD – Germany SRNWP</b>	<b>Susan Theis</b>
GLAMEPS	DNMI/Univ Oslo –Norway HIRLAM ALADIN	Trond Iversen
	Czech	Richard Mladek
	Croatia	Stjepan Ivatek-Sahdan
PEARCE	Meteo-France / France	Jean Nicolau
DMI - HIRLAM	DMI	Xiao Hua Yang
<b>United States</b>		
UWME	Univ Washington	Clifford Mass
	NSSL in Oklahoma	David Stensrud
EnKF	Univ Washington	Greg Hakim
<b>Canada</b>		
CMC LAM EPS	MS / Canada	Martin Charron
<b>Korea:</b>		
	Korean Met Admin.	Hee Sang Lee

LAM EPS  
systems  
“not yet  
registered”

Something is also  
growing up in Brazil.



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tigde-lam eps systems

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documents

## TIGGE LAM project description

*the Limited Area Model component of  
TIGGE  
the THORPEX Interactive Grand Global Ensemble*

TIGGE, the THORPEX Interactive Grand Global Ensemble, is a key component of THORPEX: a World Weather Research Programme to accelerate the improvements in the accuracy of 1-day to 2-week high-impact weather forecasts for the benefit of humanity.

One of the objectives of TIGGE is to develop a Global Interactive Forecasting System (GIFS), allowing forecasts from a variety of global and limited-area ensemble systems for effective prediction of the risks of severe weather.

The TIGGE project is led by the GIFS-TIGGE Working Group co-Philippe Bougeault from ECMWF and by Dr. Zoltan Toth

The GIFS-TIGGE WG has initially focused on the development of the

[www.smr.arpa.emr.it/tiggelam/](http://www.smr.arpa.emr.it/tiggelam/)

# Scientific issues

- *Initial conditions perturbations.*
  - ↪ *Breeding*
  - ↪ *EnKF,*
  - ↪ *ETKF*
  - ↪ *SVs*
- *Model perturbations*
  - ↪ *Multi-physics*
  - ↪ *Stochastic physics*
- *MultiModel / MultiBoundaries / MultiAnalysis*
- *Hybrid systems: high res deterministic combined with lower res. Ensemble*
- *Ensemble size*
- *Calibration & Reforecast*
- *Verification*
- *Use of LAM EPS products : downstream applications.*

# Scientific cooperation

**TIGGE  
& TIGGE LAM**

- SRNWP
  - ↪ Interoperability
  - ↪ EurEPS
  - ↪ Verification

- WMO
  - ↪ JGV Joint Working Group on Verification
  - ↪ WG/Mesoscale Weather Forecasting
  - ↪ SERA

Methodologies

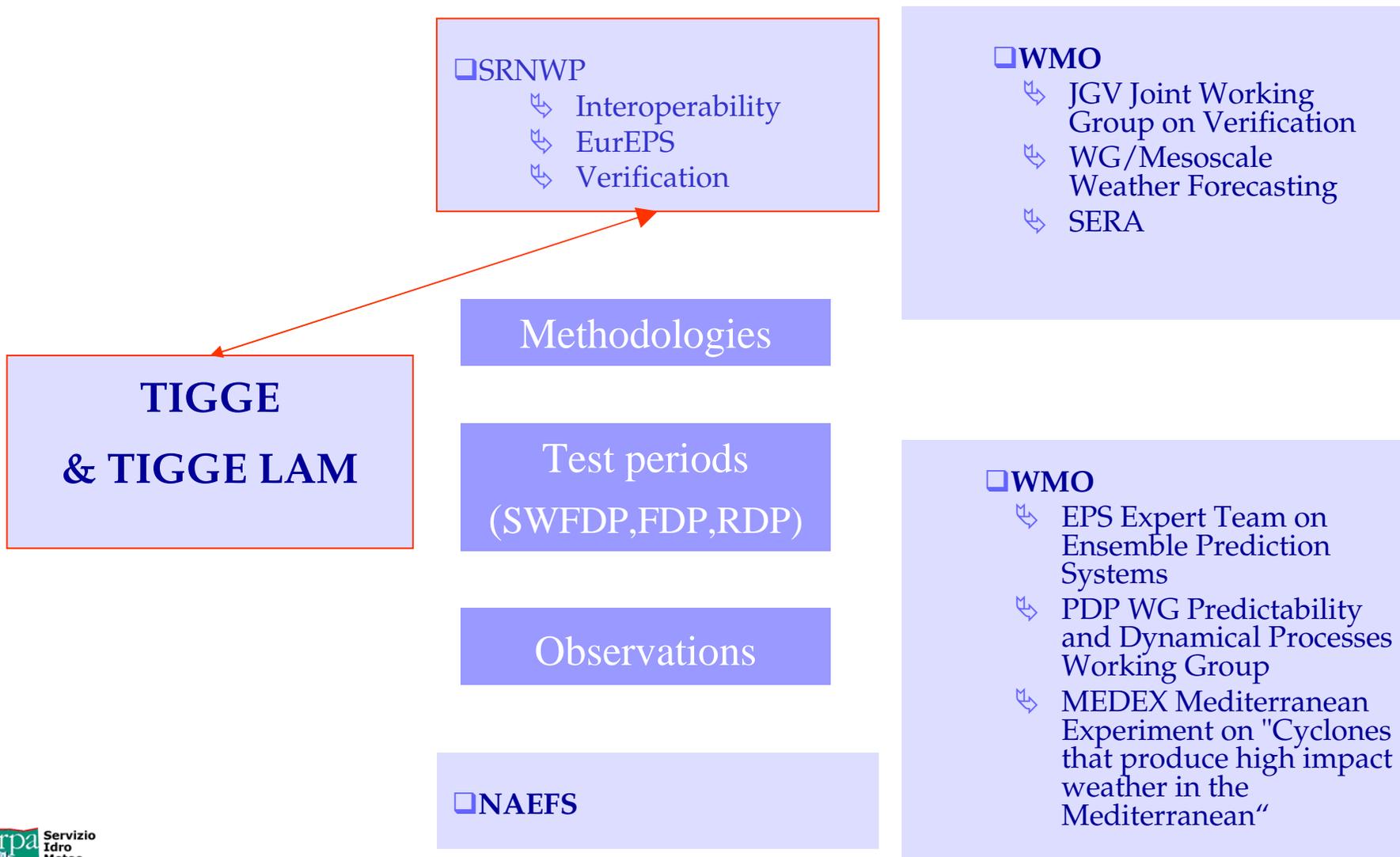
Test periods  
(SWFDP, FDP, RDP)

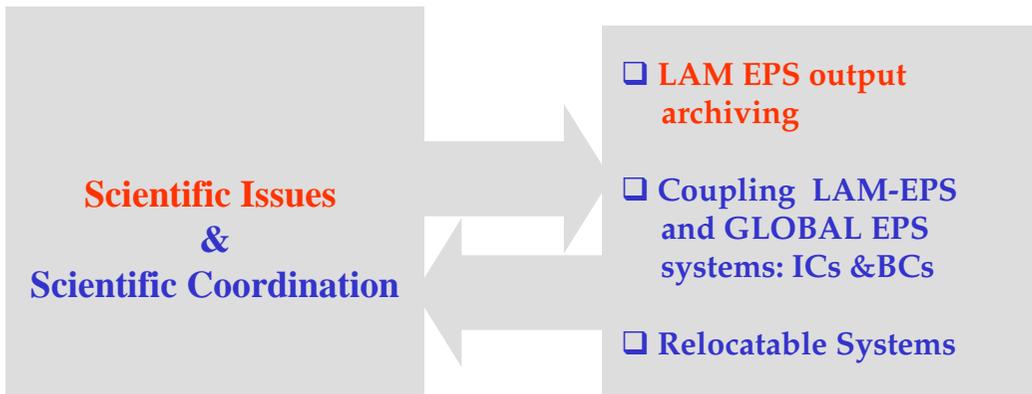
Observations

- NAEFS

- WMO
  - ↪ EPS Expert Team on Ensemble Prediction Systems
  - ↪ PDP WG Predictability and Dynamical Processes Working Group
  - ↪ MEDEX Mediterranean Experiment on "Cyclones that produce high impact weather in the Mediterranean"

# Scientific cooperation





## TIGGE LAM Output Parameters Archiving 1st phase

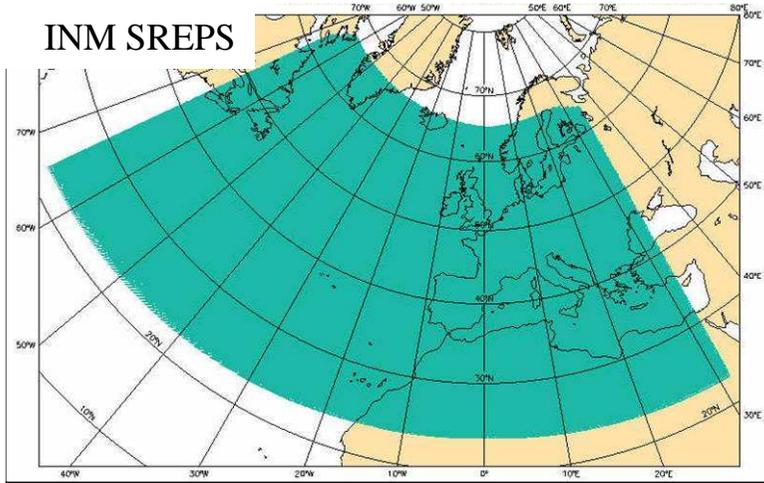


- *Initial conditions perturbations.*
  - ↔ *Breeding*
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  - ↔ *ETKF*
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- *Verification*
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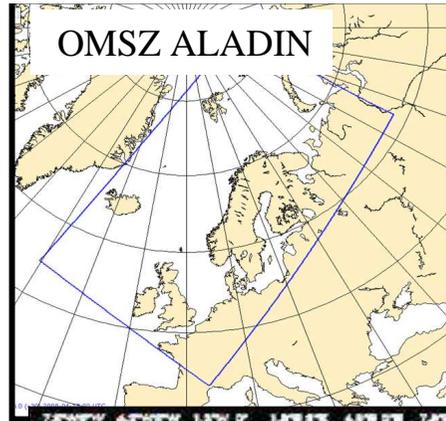
LAM EPS SYSTEMS

		“Relatively” simple to be Implemented At least in the simplest configurations	A lot of Interoperability Work			Hard both from the scientific and implementation aspects			
		Downscaling of Global EPS	Multi Physics	Perturbed Physics	Multimodel	Downscaling of different Global EPS	Downsc. of diff. det. models (incl. analyses)	Perturbed analyses	Multi Analyses
ZAMG AUSTRIA	ALADIN-LAEF	1.00							
CMA	CMA-WRF LEPS	1.00							
OMSZ ALADIN	ALADIN EPS	1.00							
JMA	MRIMESO EPS	1.00						1.00	
ARPA-SIM / COSMO	COSMO LEPS	1.00	1.00						
MET.NO	LAMEPS NORLAMEPS	1.00							
INM / HIRLAM	INM SREPS				1.00		1.00		
ARPA-SIM / COSMO	COSMO SREPS			1.00			1.00		
NCEP	SREF							1.00	
HIRLAM-AL-LACE	GLAMEPS	1.00	1.00		1.00				
UKMO	MOGREPS	1.00		1.00				1.00	
DWD/SRNWP	SRNWP PEPS								
PEARCE		1.00							
HMS	HMS LAMEPS					1.00			
	ECMWF/ALADIN LAMEPS	1.00							
WeatherSA	SASAWS								1.00
SAR	MUSE				1.00		1.00		

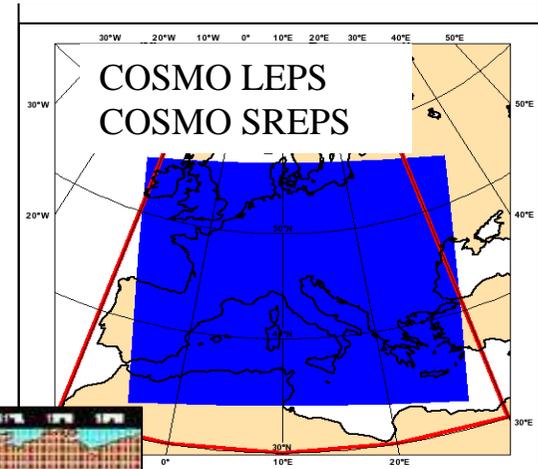
INM SREPS



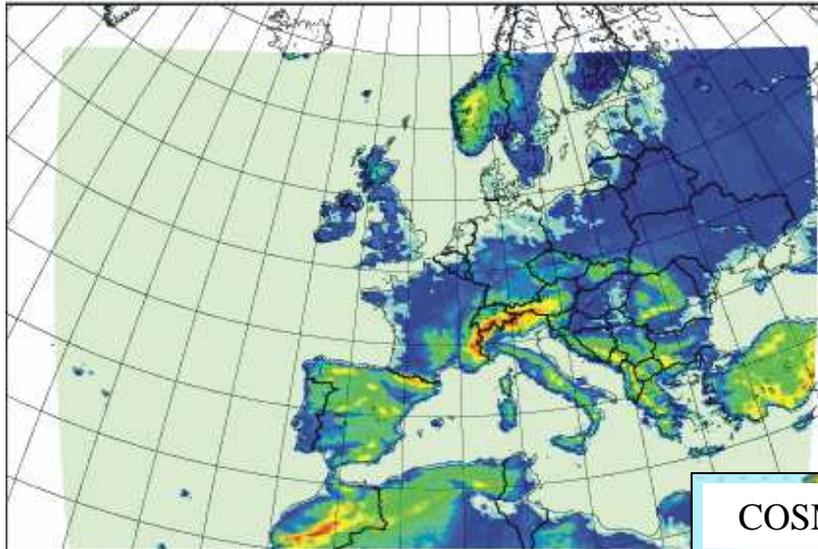
OMSZ ALADIN



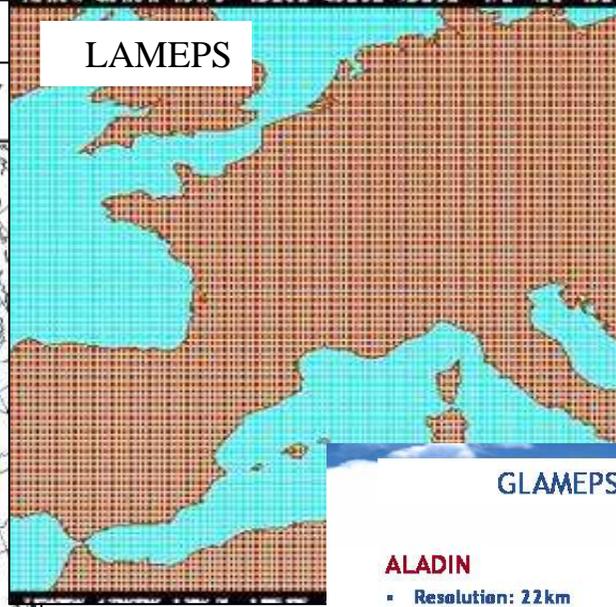
COSMO LEPS  
COSMO SREPS



# LAEF Domain & Topography



LAMEPS



MUSE



## GLAMEPS Common Domain



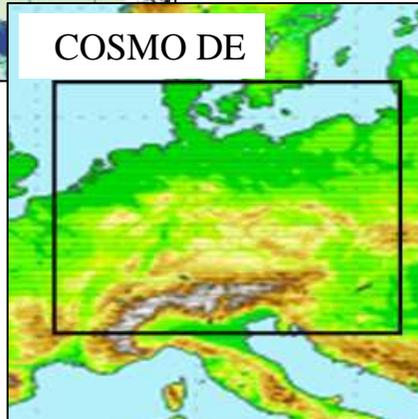
ALADIN

- Resolution: 22km
- 320 x 300 x 37

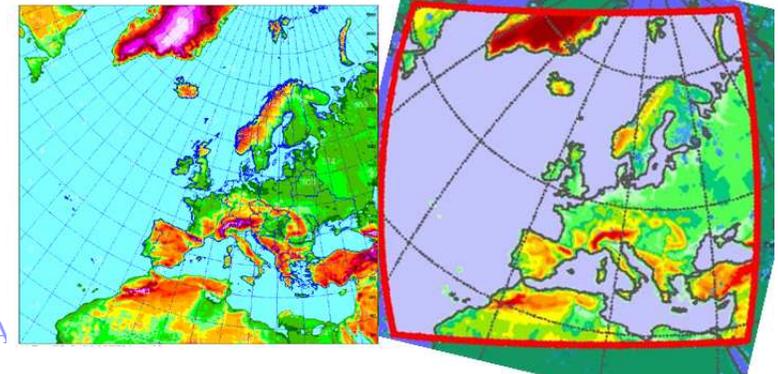
HIRLAM (EPS71)

- Resolution 0.2 deg.
- 306 x 260 x 40

COSMO DE



MOGREPS





by INM Spain

IFS – ECMWF global

COSMO at 25 km on IFS

GME – DWD global

COSMO at 25 km on GME

UM – UKMO global

COSMO at 25 km on UM

GFS – NCEP global

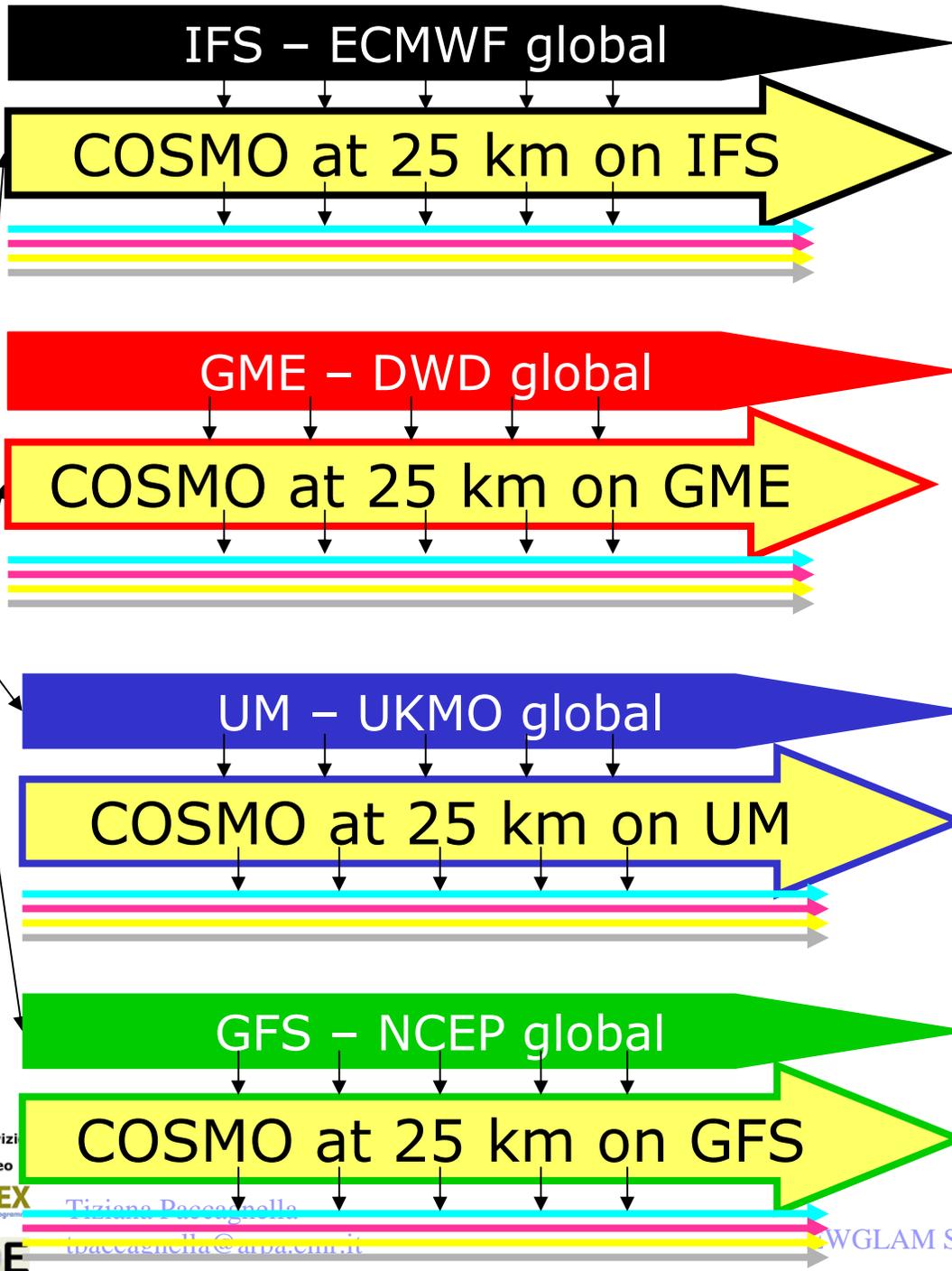
COSMO at 25 km on GFS



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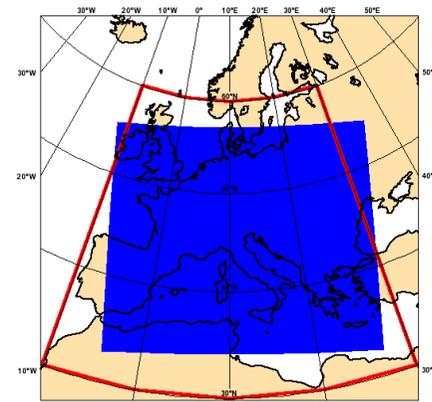
by INM Spain



System set-up

- P1: control (ope)
- P2: conv. scheme (KF)
- P3: tur\_len=1000
- P4: pat\_len=10000

**16 COSMO runs**  
10 km hor. res.  
40 vertical levels



00 UTC

JJA=53 SON=54



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testing period

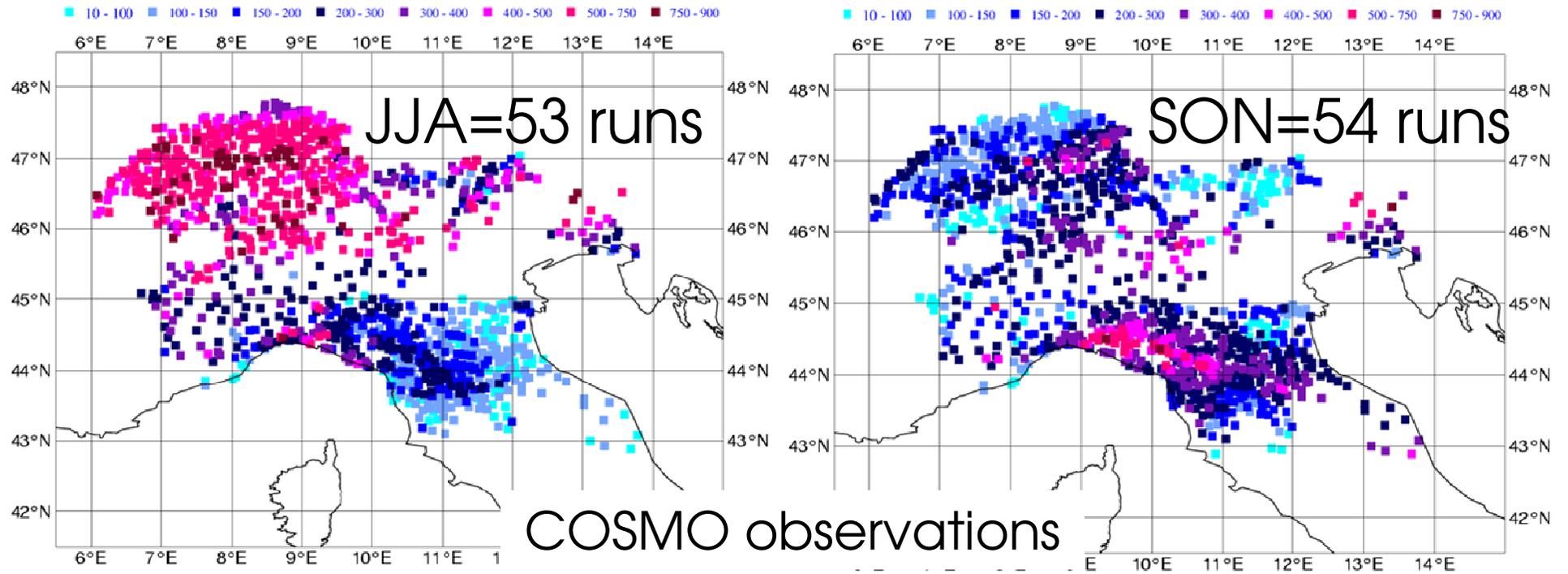
COSMO-SREPS was running regularly during the  
MAP D-PHASE DOP, at 00 UTC



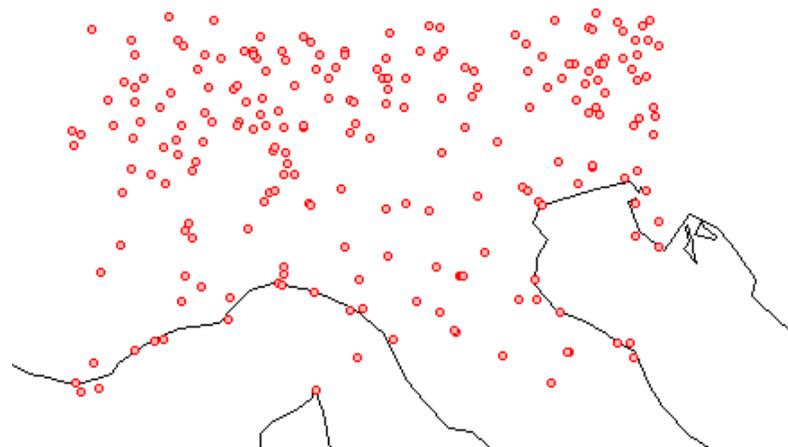
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# Obs. Network used by ARPA-SIM



218 synop stations on the Alpine area

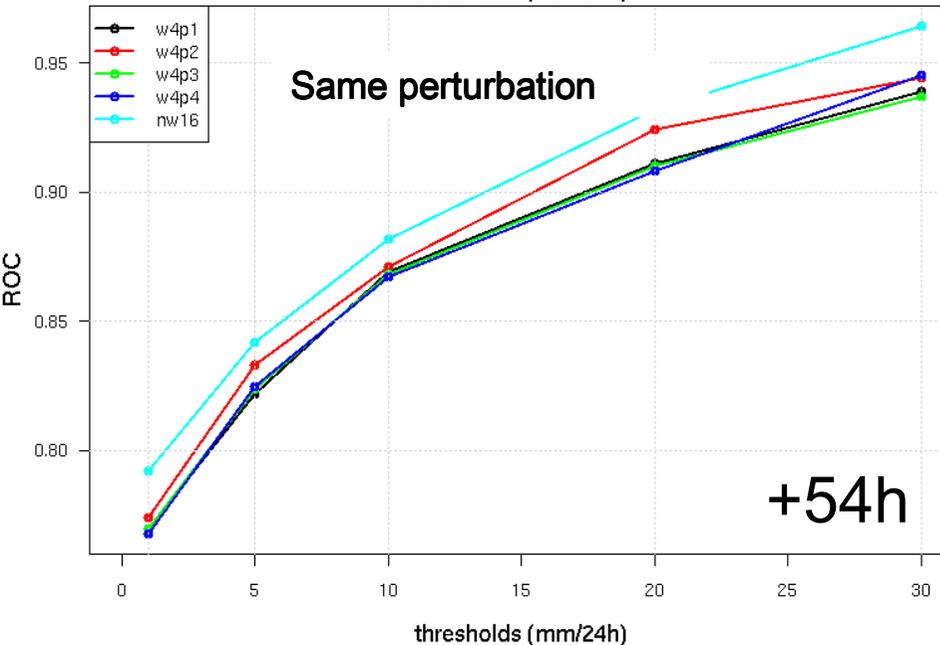
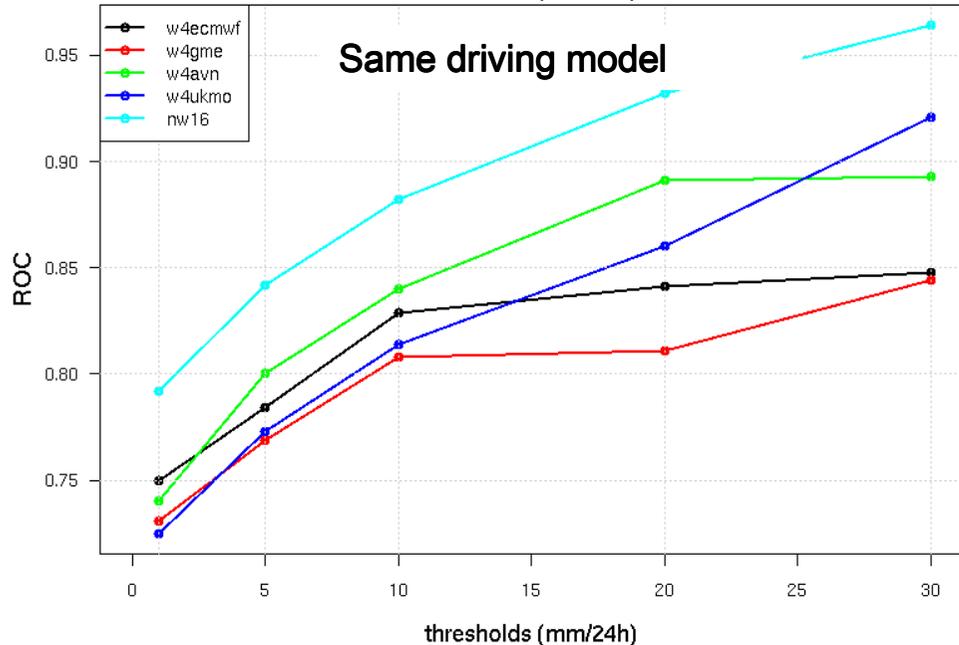
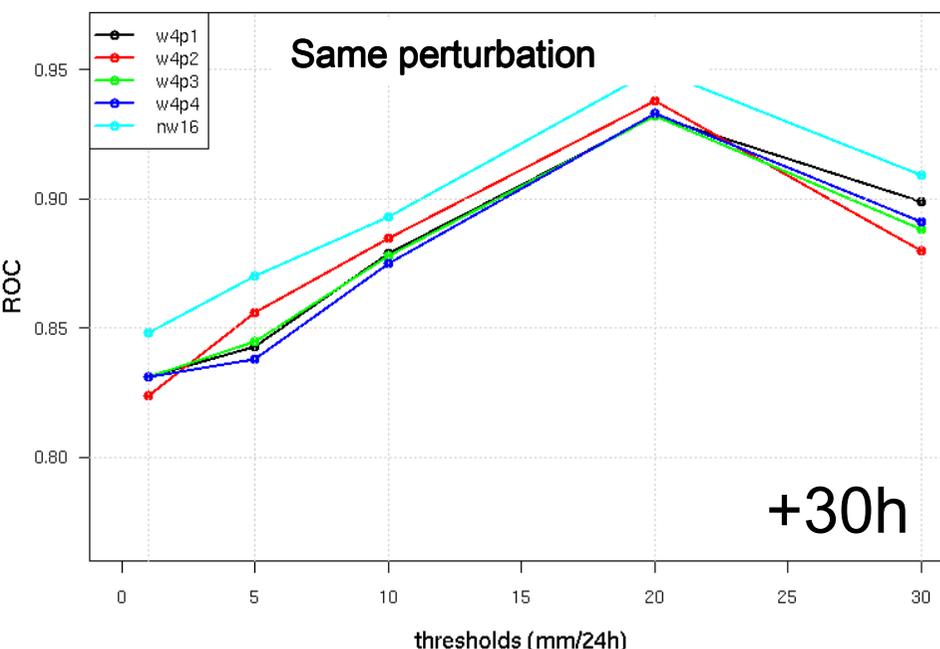
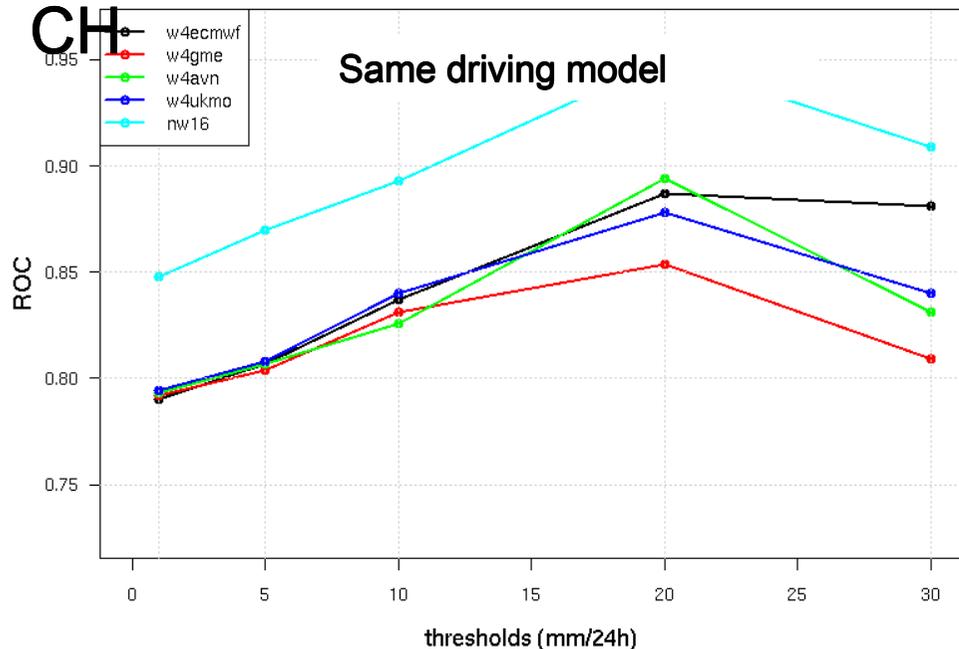


IT +

TP 24h - ave 0.5x0.5

SON07

CH



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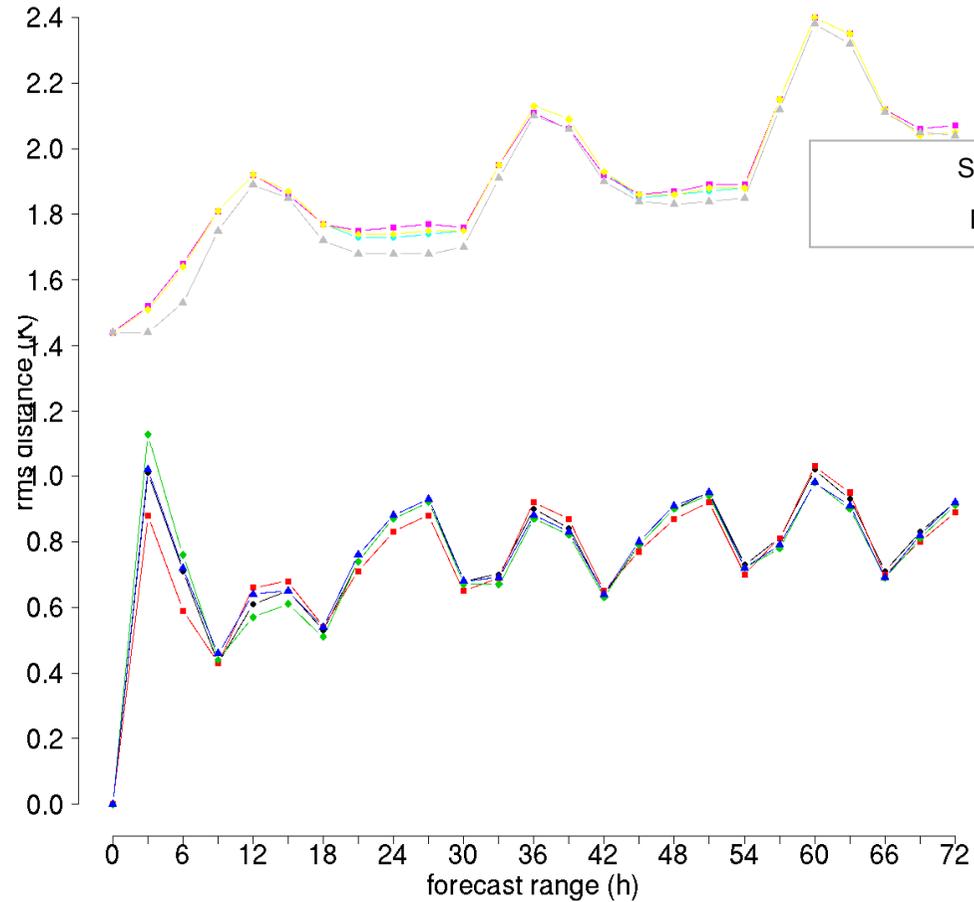
noss ~ 800 500 300 100 50

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intra-group distance

JJA 2007 - 50 days

- ecmwf    ● p1
- gme     ■ p2
- ◆ avn     ◆ p3
- ▲ ukmo    ▲ p4



Same model parameters  
Different driving model

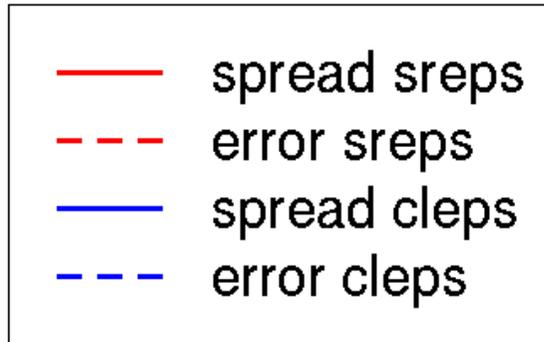
2mT Northern Italy



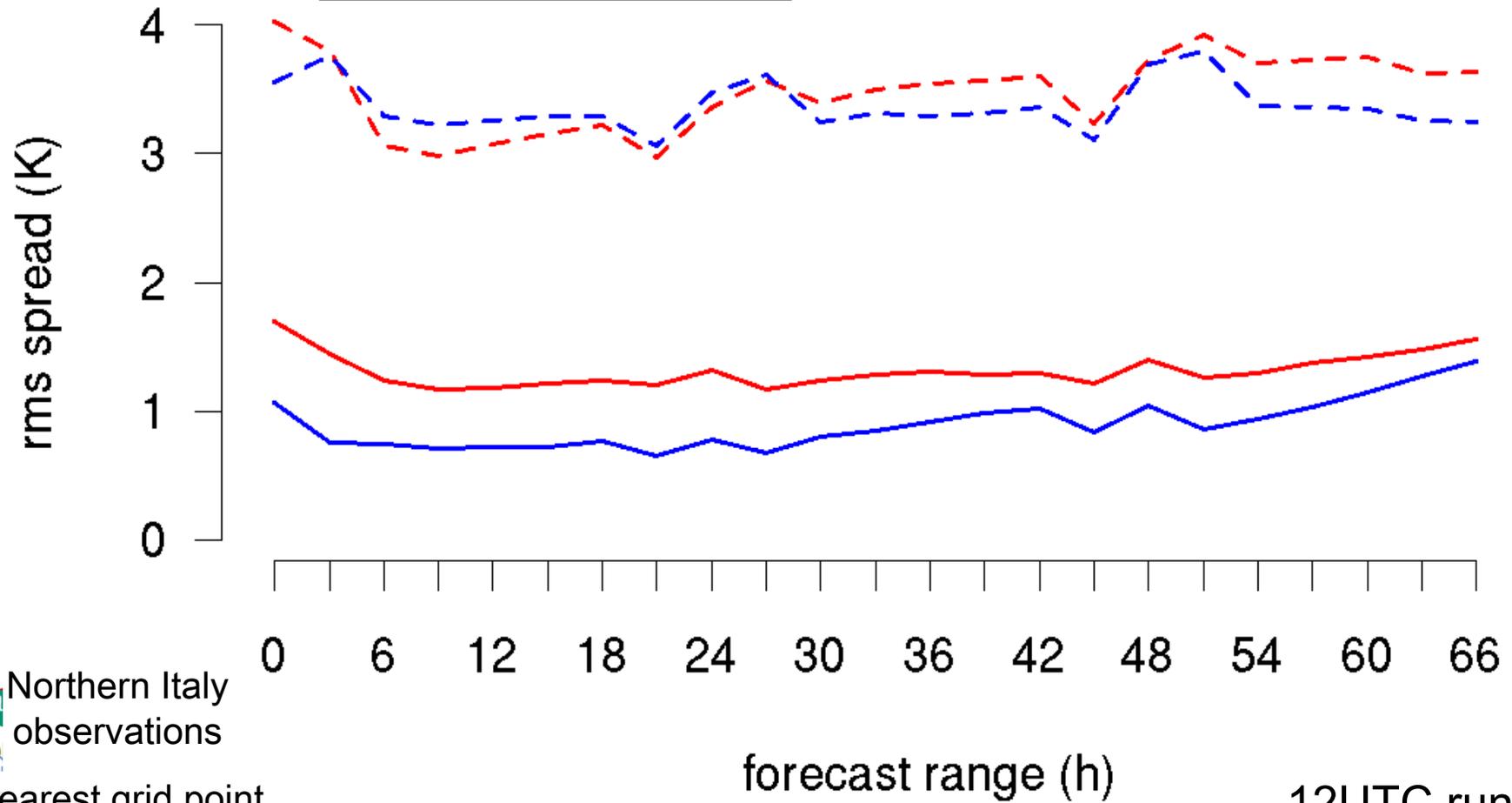
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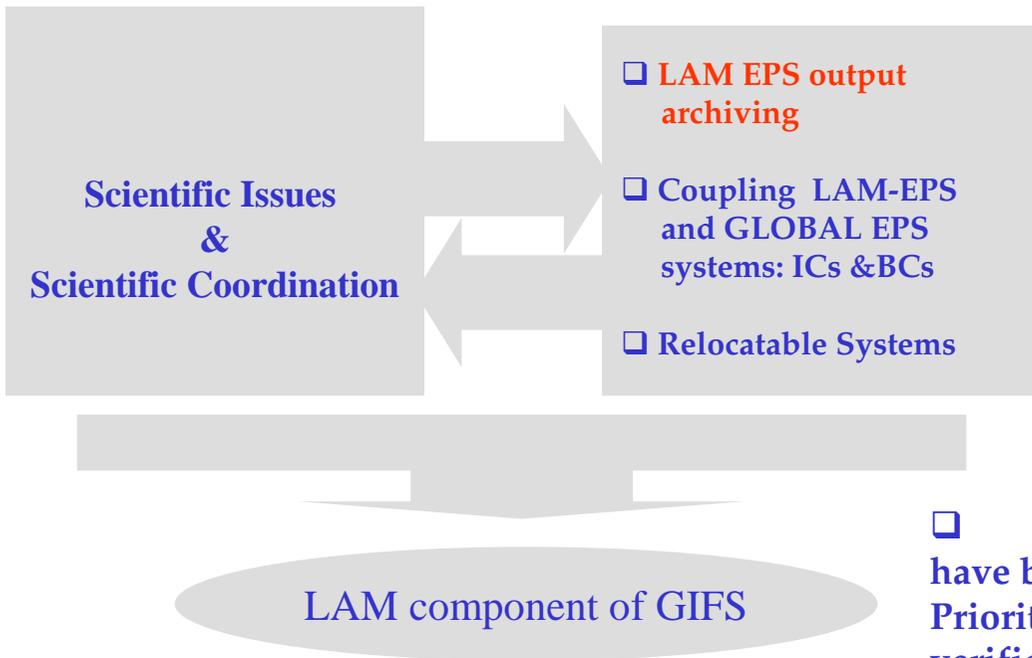
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## Relationship between error and spread



From C. Marsigli 2007  
COSMO LEPS vs  
SREPS  
7 cases autumn 2006





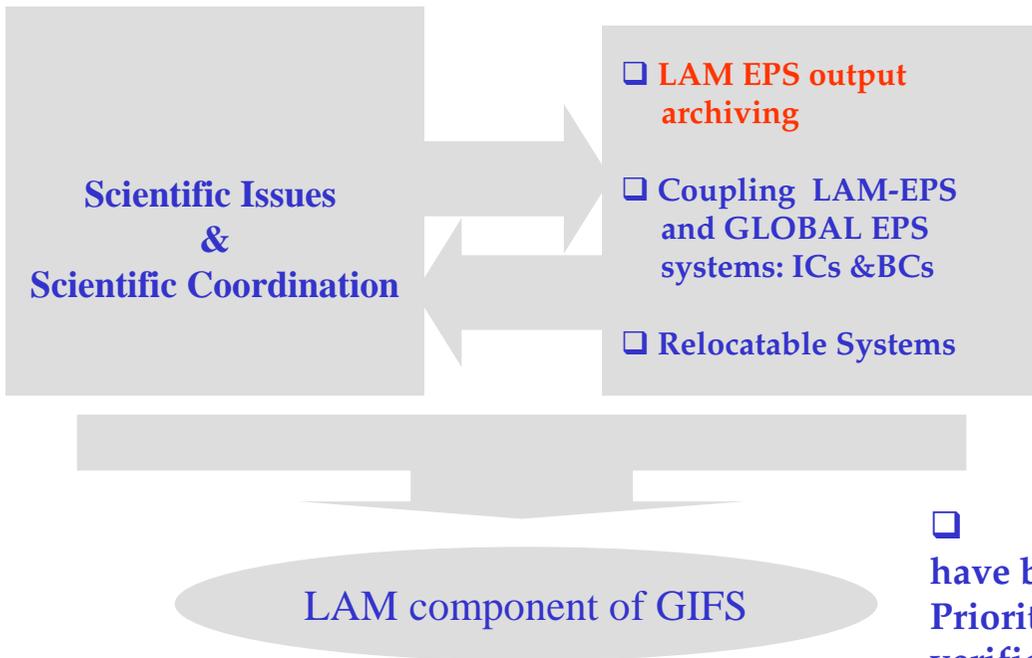
## TIGGE LAM Output Parameters Archiving 1st phase

- Based on the TIGGE list of archived parameters, a similar list has been compiled for the TIGGE LAM systems

- Some single level parameters have been labelled as HP (High Priority) since they are the easiest to be verified and the most commonly used:

- ↪ Mean sea level pressure
- ↪ 10m U-velocity
- ↪ 10m V-velocity
- ↪ Wind Gust
- ↪ Surface air temperature
- ↪ Surface air dew point temperature
- ↪ Total precipitation (liquid + frozen)
- ↪ Large scale precipitation
- ↪ Orography
- ↪ Land sea mask

These parameters will be archived with highest priority



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### ❑ Output Fields Format

↪ GRIB2

### ❑ Data policy proposal

↪ The data will be made available within the same rule of TIGGE but with a delay of 24 hours.

# TIGGE LAM output parameters

Meeting about TIGGE LAM archiving - Phase 1

High Priority Parameters archived at the three archiving centres ECMWF, NCAR, CMA

ECMWF - 4 Sept. 2008

Participants:

Manuel Fuentes

Baudouin Rault

Yong Wang

Michael Denhard

Antonio Garcia Moya

Trond Iversen

Ken Mylne

Tiziana Paccagnella

Andrea Montani

□ It is very important to make the use of TIGGE LAM data easier for the main users (e.g hydrologists ) who are not familiar with tools and methodologies to manipulate meteorological fields.

□ So, the *recommended solution* for this Phase 1, archiving of the High Priority parameters at the three TIGGE Archiving Centre, is:

↳ Standard geographical lat/lon grid at 0,1° resolution



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**TIGGE LAM Output Parameters  
Archiving  
1st phase**

To make the use and exchange of these fields easier, the TIGGE archiving Centres ECMWF, NCAR and CMA will support TIGGE LAM by including in the TIGGE archive also these HP parameters.

Due to the regional nature of LAMs, the outputs coming from the different systems will be archived in one of the three Centres following a Geographical/Regional competence principle

Archiving Centre	LAM EPS products	
<b>ECMWF</b>	MOGREPS INM SREPS SRNWP PEPS COSMO LEPS NORLAMEPS ALADIN LAEF OMSZ ALADIN EPS COSMO DE EPS GLAMEPS EPS EPS PEARCE DMI - HIRLAM	UK Met Office INM - Spain HIRLAM DWD – Germany ARPA-SIM – Italy Met.NO ZAMG / Austria Hungary DWD – Germany DNMI/Univ Oslo –Norway Czech Croatia Meteo-France / France DMI Denmark
<b>NCAR</b>	NCEP-SREF UWME NSSL EPS EnKF CMC LAM EPS	NCEP Univ Washington Oklahoma Univ Washington MS / Canada
<b>CMA</b>	CMA-WRF LEPS JMA MRI EPS KOREA EPS	CMA/China MRI/Japan Korean Met Admin.

## TIGGE LAM Output Parameters Archiving 2nd phase

**There is a general consensus about the idea to plan, for the future, a decentralized archiving systems based on Regional Centres**

**☝ This will be harmonized with the GIFS development phase**

**☝ This should be coordinated at regional level in the THORPEX geography**



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## Clear common interests and objectives: issues now under planning and discussion

### SRNWP

#### EurEPS

- A document defining a set of verification methods .....and .. a set of cases or periods for verification.
- A database of a range of ensemble forecasts and observations.....,
- A report on the benefits of a grand LAM-EPS for the prediction of high-impact weather events
- Definition of a European contribution to TIGGE-LAM.

LAM EPS output archiving

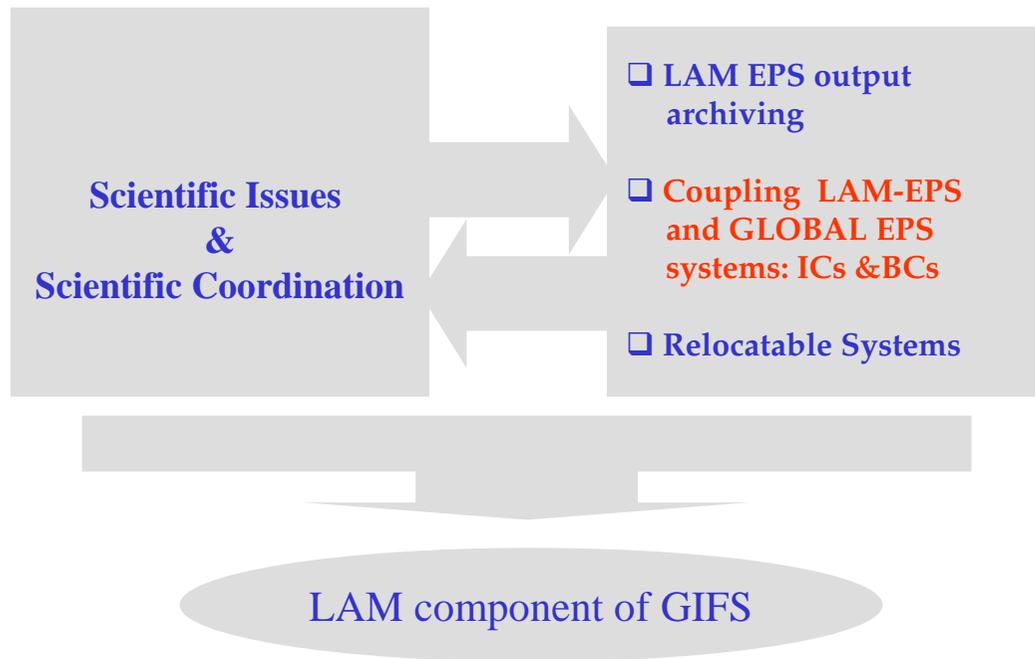
### SRNWP

#### Verification

### SRNWP

#### Interoperability

- D1: A report documenting the standard output format and including a list of parameters for which the output format is to be applied. ....
- D2: Documentation describing the requirements and specification for the adaptor software (hereafter adaptors). .....
- D3: Four 2-way adaptors that transform the output from every LAM (hereafter LAM) to the standard output format and vice versa. Documentation will also be provided. ....
- D4: Enhancements to existing software tools that enable all LAMs to process data from the four Global Model providers. .... (Refine the work plan for delivery of D4 ready for the start of Year 3 (September 2010))



## Coupling Globals and LAMs: Initial and Boundary Conditions

The concept of **GIFS** and of **Adaptive Forecasting Systems** would benefit of a **good interoperability** as regards the coupling between the different LAM and the different Global Models.

It is clear that this vision must deal with the many problems related to the huge amount of coordinated work to be devoted to this task as regards both technical and scientific aspects.

## Coupling Globals and LAMs: Initial and Boundary Conditions

**Two options were evaluated about the possible formats to provide initial and boundary conditions:**

**1. Initial and Boundary conditions provided on a standard 3D grid:**

- ↪ on a lat-lon grid at horizontal resolutions adequate to the original model resolution;
- ↪ on pressure levels with a number of vertical levels high enough to minimize the loss of information;
- ↪ in terms of standard and pre-defined physical variables.

**2. Initial and Boundary conditions provided on the global models original “computational grid”**

## Coupling Globals and LAMs: Initial and Boundary Conditions

Both options present advantages and disadvantages but there is a preference for the option 2 (original model levels)

Due to the complex interoperability aspects underlying this issue, it is really important to be well phased with similar initiatives



The coupling of Global models with LAMs will be matter of cooperation and coordination with the INTEROPERABILITY project of the Short Range Numerical Weather Prediction Programme of EUMETNET (the EUropean METeorological services NETwork).

## Clear common interests and objectives: issues now under planning and discussion

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- ❑ LAM EPS output archiving
- ❑ **Coupling LAM-EPS and GLOBAL EPS systems: ICs &BCs**
- ❑ Relocatable Systems

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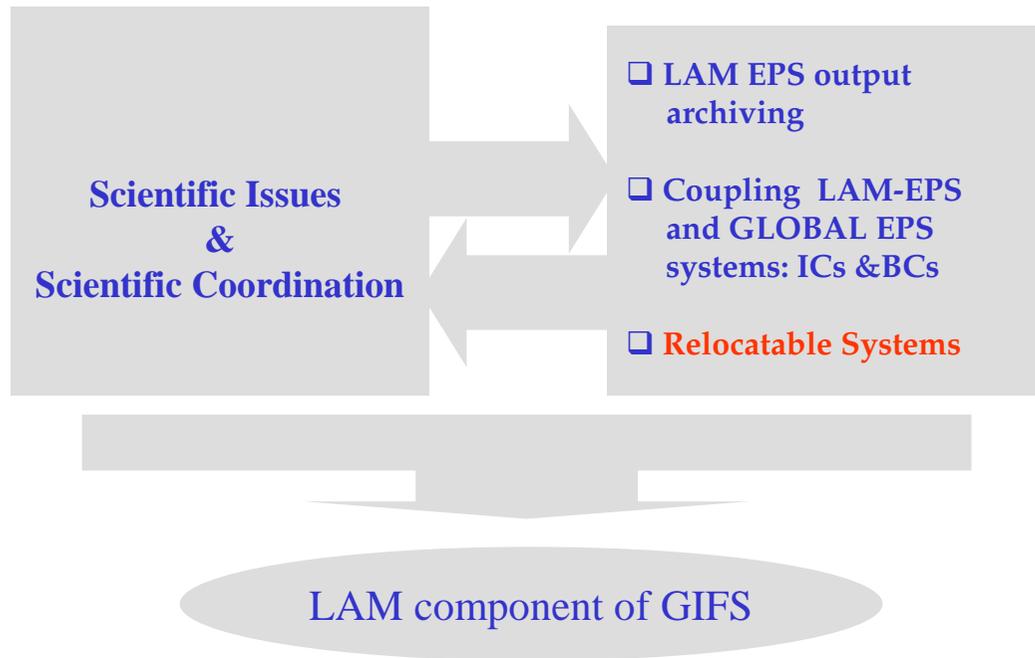
## Coupling Globals and LAMs: Initial and Boundary Conditions Archiving

- ❑ **Temporary archive of daily “real time” data.**
  - ↪ These data should be stored at the producing centres for a very short time from 3 to 10 days depending on the restrictions/possibilities of each producing centre.
  
- ❑ **Permanent archive on selected periods (e.g. during specific projects, Forecast Demonstration Projects, Research Demonstration Projects, etc.etc.).**
  - ↪ These data should be stored at the producing centres. Another option could be to include these archives in the overall TIGGE archive centres.
  
- ❑ **Permanent archive for Special Cases related to severe events.**
  - ↪ As above. These data should be stored at the producing centres. Another option could be to include these archives in the overall TIGGE archive centres.

# Relocatable systems

In TIGGE LAM two system components were foreseen:

- ↪ **A Fixed Component:** which is formed by all the LAM EPS systems running operationally over fixed geographical domains at a suitable resolution and fulfilling all the TIGGE requirements.
- ↪ **A Mobile/Relocatable Component** which should be a real interactive component to be operated on demand with the required set-up characteristics.



## Non-homogeneous LAM EPS systems distribution

- ↪ Regions with more systems covering the same area
- ↪ Regions without LAM EPS implementations

# TIGGE LAM and GIFS

LAM ensemble is a strategic component of TIGGE and of the GIFS considering the need/ambition to optimize the forecasting system in real time.

During the Phase 2, TIGGE LAM and TIGGE should progressively merge together also considering the common general infrastructure they will be based on.

The interactive nature of GIFS will require the definition of a common methodology to assess the quality of systems to be activated on demand. This issue should be strongly coordinated with the THORPEX regional committees also to

- ↪ evaluate priorities related to geographical areas and associated severe weather phenomena
- ↪ Define the test- periods by considering the inventory of severe events and the observational data set available

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Cooperation with WMO WG MWF  
(chair. Jeanette Onvlee)

Cooperation with WMO WG  
Verification (chair. Barbara Brown)

- Test period
- Data set
- Methodologies



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# TIGGE LAM and GIFS

**It should be nice to present some projects to relocate some of the European systems in other regions**

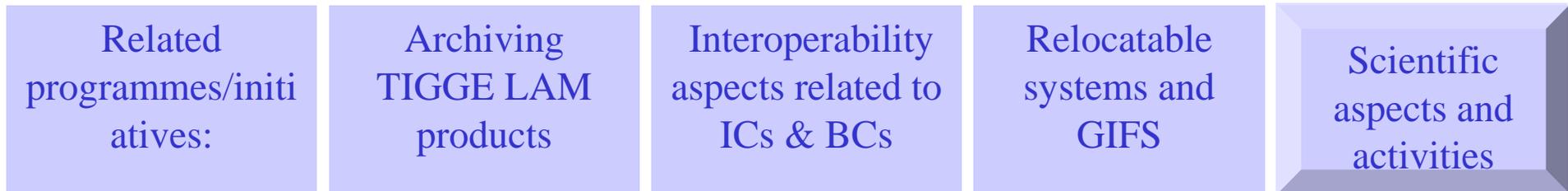


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# 1st plenary TIGGE LAM meeting

**First TIGGE LAM meeting**  
**Bologna 19-21 January 2009**



*SRNWP*  
*Programmes*  
*Presentations*

.....

Draft Program Outline

- Presentations and contributions also from
- The WWRP WG on Mesoscale Weather Forecasting
- The expert team on EPS
- The WGNE Joint Working Group on Verification)
- The Beijing RDP
- .....

## Concluding Remarks

- ❑ The Multi-model concept in its wider sense (more models, more ensembles, etc.) is one of the main issues to be investigated in TIGGE and in TIGGE LAM
- ❑ The necessary high level of interoperability implies a strong cooperation to facilitate the exchange of products both as regards the model systems output and the ICs/BCs files.
- ❑ Europe is the region with more initiatives in LAM Ensemble Predictions and this is a perfect situation to give very valuable contributions to TIGGE LAM
- ❑ The SRNWP Programmes are so close to TIGGE LAM that every effort must be done to ensure the maximum cooperation and sharing of resources.

Thank you!



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## TIGGE LAM PANEL

### Terms of reference

The Panel should:

- propose a possible structure of the TIGGE-LAM component.
- maintain the necessary liaison with already existing LAM EPS initiatives and with related new projects.
- encourage a coordinated approach to LAM EPS
- should formulate proposals to facilitate the interoperability (different LAMs driven by different GCMs) of the different modelling systems contributing to TIGGE.
- formulate proposals for the creation of a coordinated distributed archive of limited-area ensemble forecasts.
- contribute to the definition of scientific issues related to LAM EPS
- propose guidelines as regards LAM EPS validation, calibration and combination, in a close coordination with the GIFS-TIGGE WG.