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Eidgenössisches Departement des Innern EDI
Bundesamt für Meteorologie und Klimatologie MeteoSchweiz

Assimilation of Radar Rainfall in COSMO-2 and Use of Humidity Profiles from GPS Tomography

Daniel Leuenberger, MeteoSwiss

Marc Troller, ETH Zürich

Thanks for contributions of Felix Ament, MeteoSwiss



Outline

- Motivation
- Model Setup
- Radar Rainfall Assimilation
- GPS Tomography
- Summary and Outlook



Motivation

- Poor QPF performance in summer
- Partly due to initial conditions
- Need for high-resolution observations
- Radar
 - Reflectivity, wind
 - 5min temporal, 1km spatial
- GPS
 - Humidity
 - <1h temporal, ~50km spatial

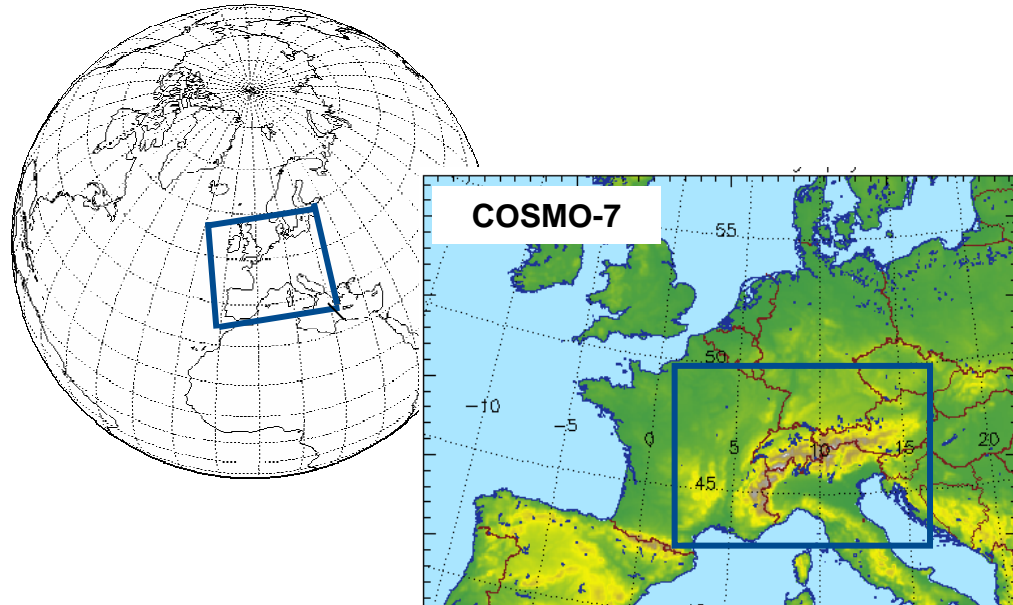


Model Setup

IFS (ECMWF)

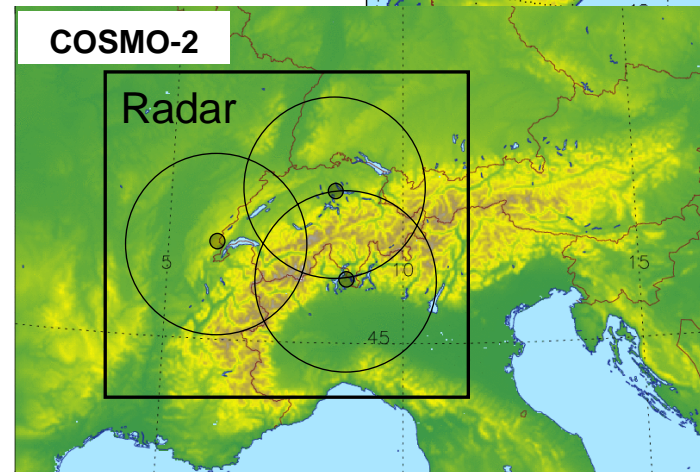
COSMO-7

- 7km, 45 levels
- Tiedke conv. scheme



COSMO-2

- 2.2km, 60 levels
- Shallow conv. scheme





Radar Rainfall Assimilation

- Latent Heat Nudging (LHN)
Jones and Macpherson, 1997, Leuenberger and Rossa, 2007
- Adjusts model temperature and moisture to match radar rainfall
- Modifications for advection of precipitation (DWD)
- More details in Klaus Stephan's presentation

Jones, C. D. and B. Macpherson, 1997: A Latent Heat Nudging Scheme for the Assimilation of Precipitation Data into an Operational Mesoscale Model, *Meteorol. Appl.*, **4**, 269-277

Leuenberger, D. and A. Rossa, 2007: Revisiting the latent heat nudging scheme for the rainfall assimilation of a simulated convective storm, *Meteorol. Atmos. Phys.*, online first, DOI 10.1007/s00703-007-0260-9



Radar Data

- High-quality rainfall information derived from Swiss radar composite (3 C-Band Radar)
- Best estimate of surface precipitation
- Clutter suppression, vertical profile correction, gauge adjustment on long time scale
- 5 min update frequency



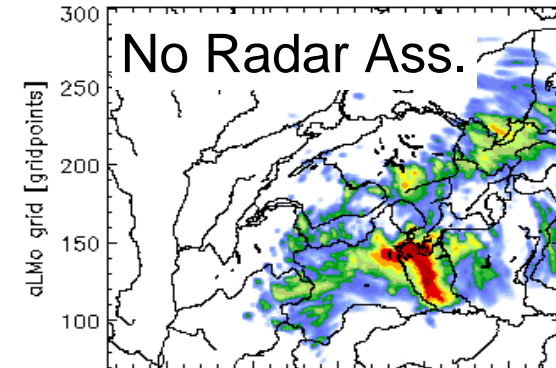
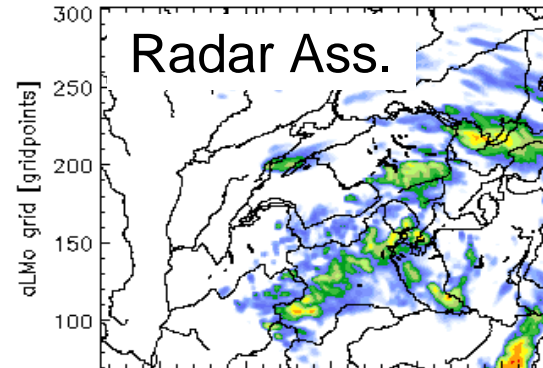
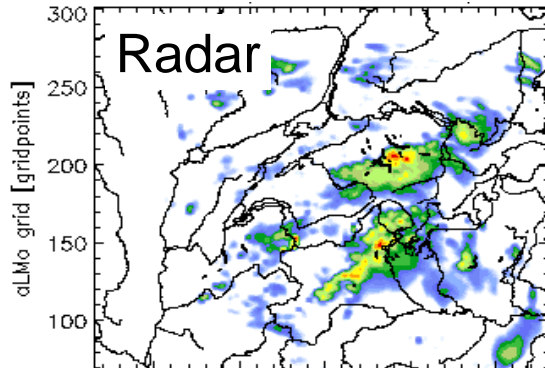
Setup of Experiments

- 2.2km assimilation cycle with/without LHN
- Forecasts out to 12h started from the analyses
- Parallel test suite running currently at MeteoSwiss
- Two summer months (11. Jun - 23. Aug 2007)
 - 8 forecasts per day
- One autumn month (15. Sep – 18. Oct 2007)
 - 3 forecasts per day (00, 12, 18 UTC)

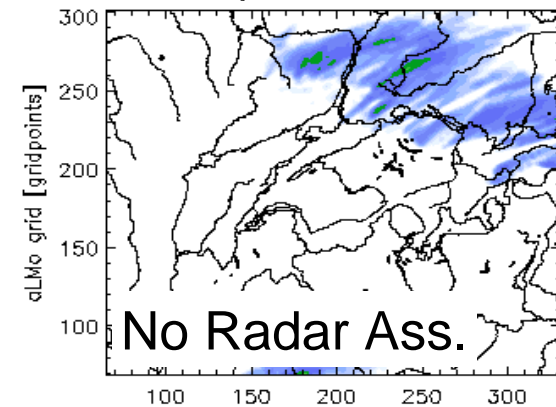
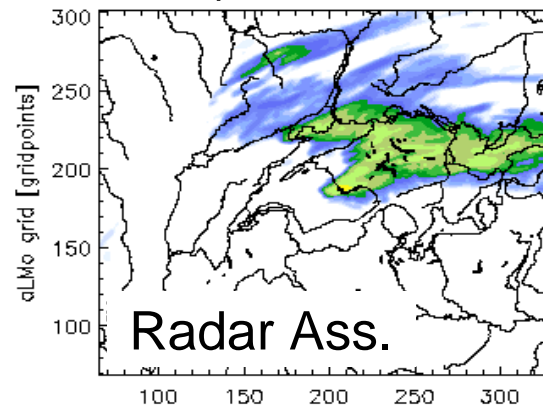
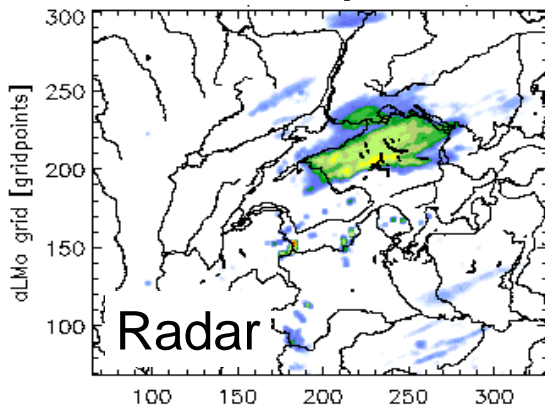


Examples of forecast improvement

0-6h Precipitation Forecast (12.06.2007, 18-24UTC)



6-12h Precipitation Forecast (19.06.2007, 00-06UTC)

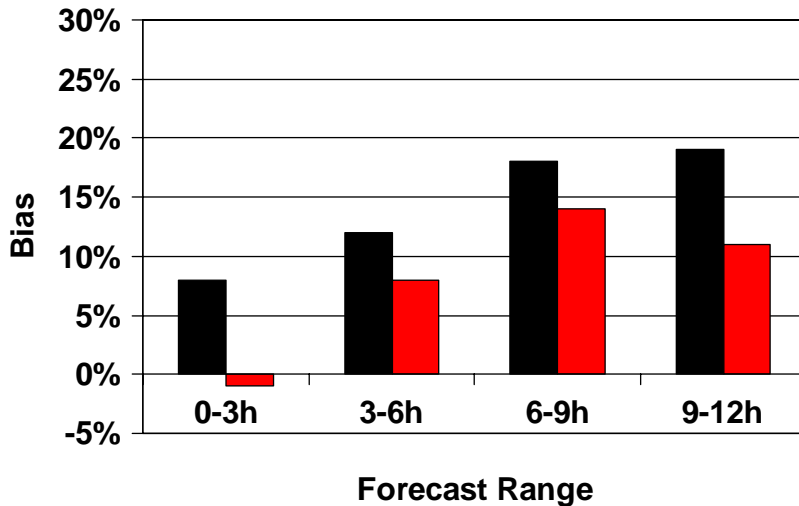




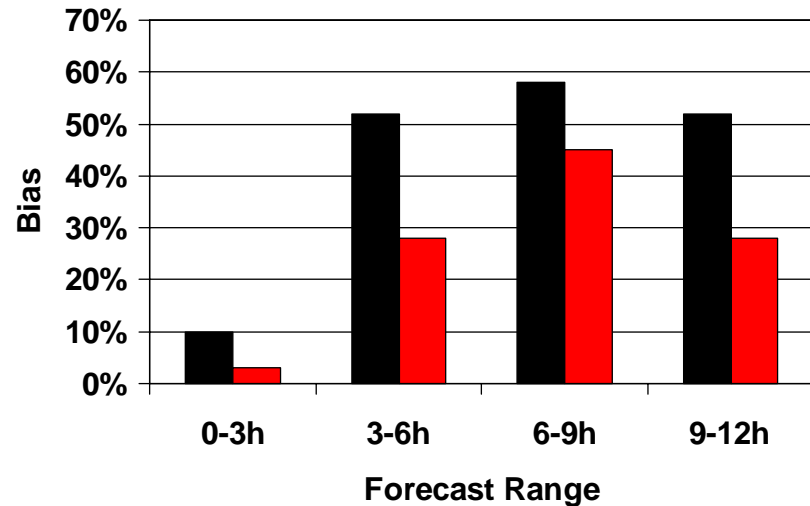
Statistical Evaluation against Radar

Precipitation forecast bias over Switzerland

Summer (344 forecasts)



Autumn (102 forecasts)

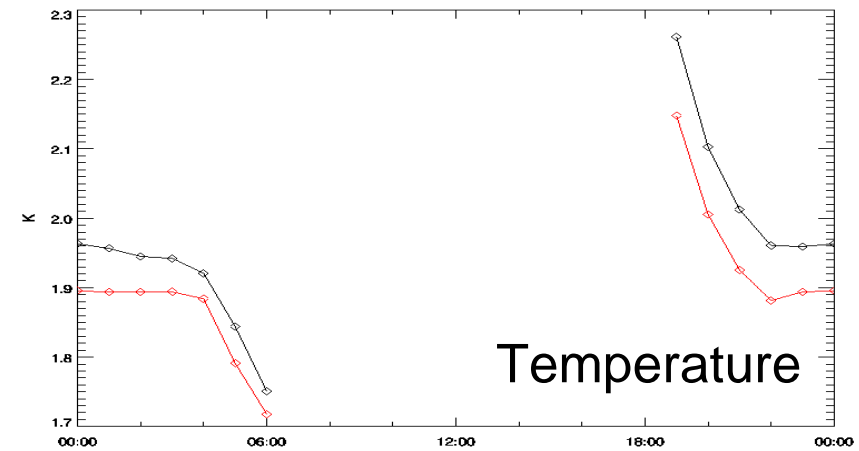
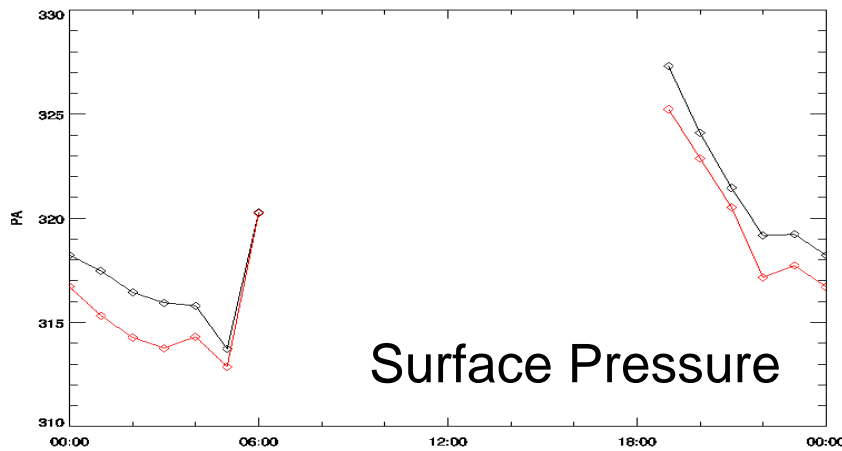
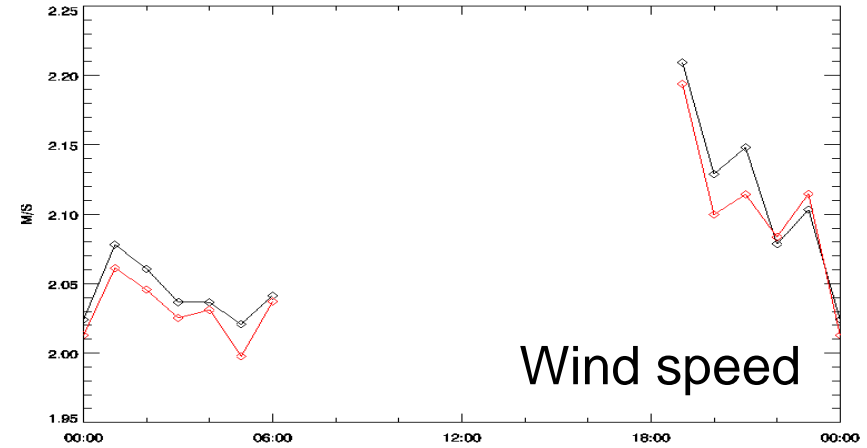
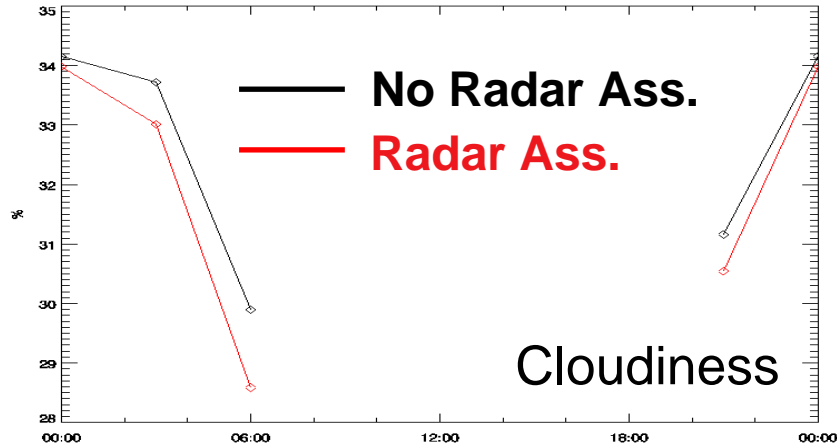


 **LHN**  **No LHN**



Summer Evaluation (Surface Obs.)

RMS of 74 18UTC Forecasts (Reference: ca. 60 Swiss Sfc. Stations)





Summary Radar Assimilation

- Improvement of precipitation bias out to 12h
- Surface obs
 - Small but consistent improvement of T, U/V, clouds and P_s out to 12h in summer (up to 3% reduction of RMSE)
 - Mixed results in autumn
- Radiosondes
 - Small impact at +6h (+ in summer, +/- in autumn)
 - Neutral impact at 12h
- Mesoscale environment important for success of radar assimilation



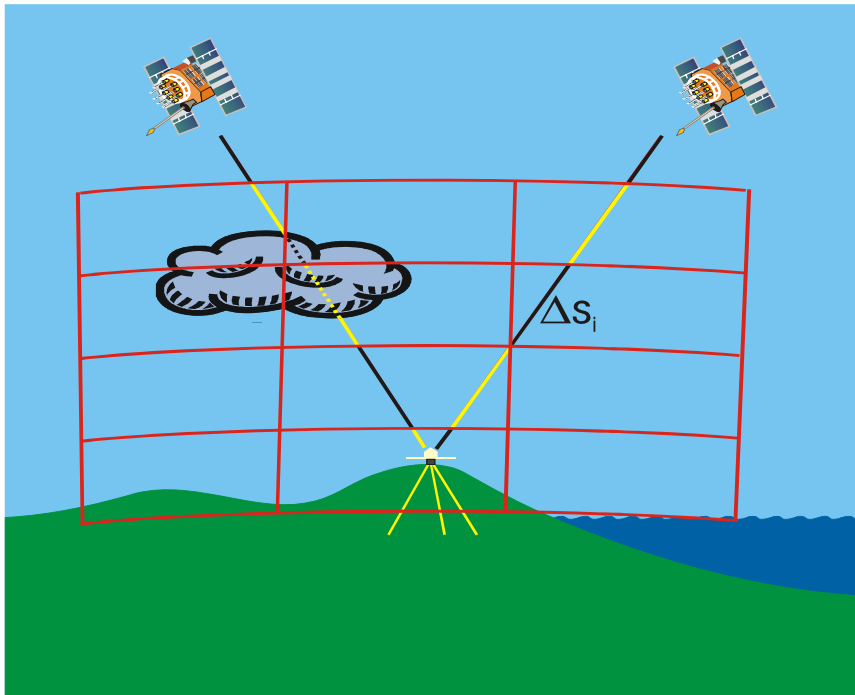
GPS Tomography - Motivation

- Atmospheric moisture important for QPF
- Highly variable in time and space
- Currently: very sparse observations
 - Radiosondes (200km x 12h)
 - Surface stations (50km x 6h for SYNOP, locally higher), representativity problems
 - Satellites: problems over land, lower atmosphere and in cloudy regions
- => Large uncertainty in NWP humidity



GPS Tomography - Method

- New method to retrieve humidity **profiles** from GPS
- High-resolution **in time and space**



Distance between satellite and receiver:

$$\rho = \int_{receiver}^{satellite} n \cdot ds$$

ρ : length of signal path
 $n = c/v$: refractivity index

Making use of a voxel model:

$$\rho = \sum_{i=1}^k n_i \cdot \Delta s_i$$

n_i : constant refractivity index inside voxel i
 Δs_i : path in voxel i
 k : number of voxels



Comparison with Temps and COSMO-7

- Wet refractivity from Payerne radiosonde

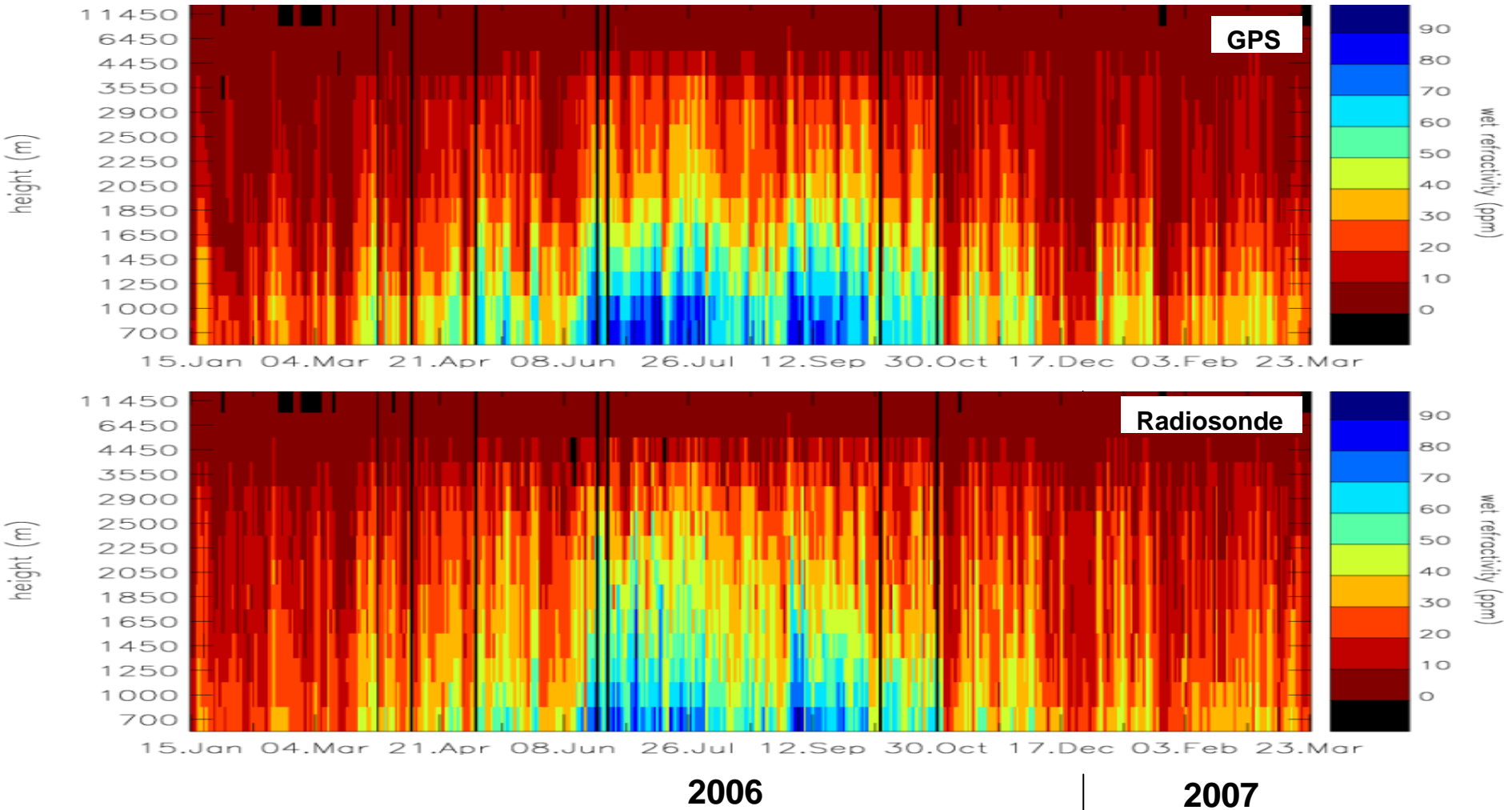
$$N_{wet} = k_2 \frac{e}{T} + k_3 \frac{e}{T^2} \quad \varepsilon = R_d/R_v, \\ k_2 = 64.8 \text{ K/hPa}, \quad k_3 = 3.776e5 \text{ K}^2/\text{hPa}$$

- Wet refractivity from COSMO-7 analyses and forecasts

$$N_{wet} = \frac{q_v P}{T(\varepsilon + q_v(\varepsilon - 1))} \left(k_2 + \frac{k_3}{T} \right)$$

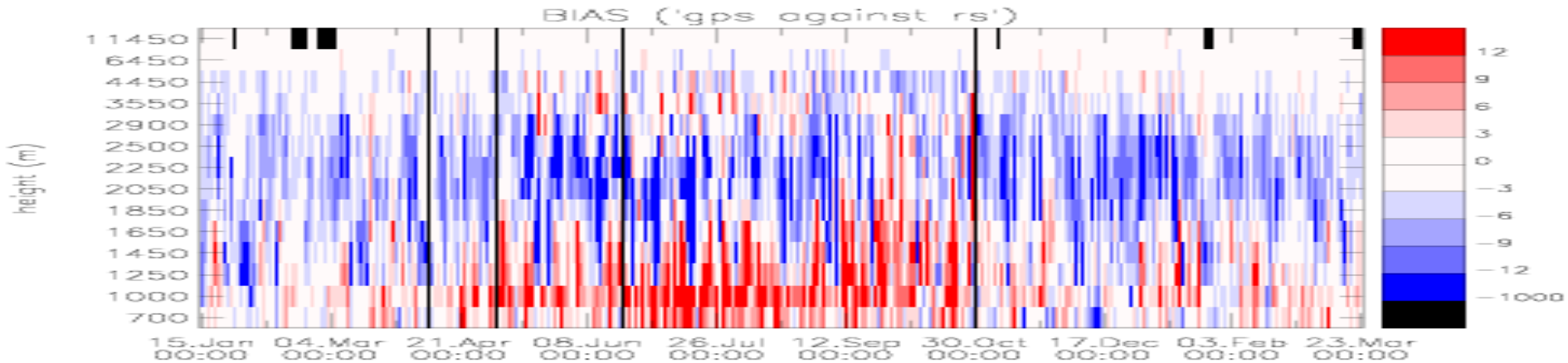
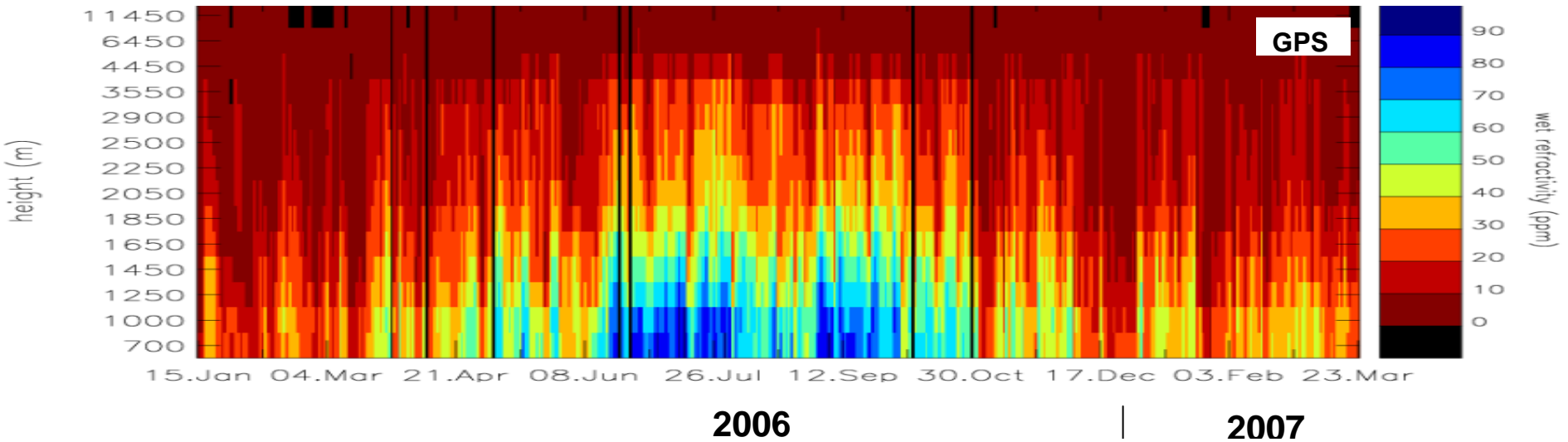


Yearly Humidity Distribution



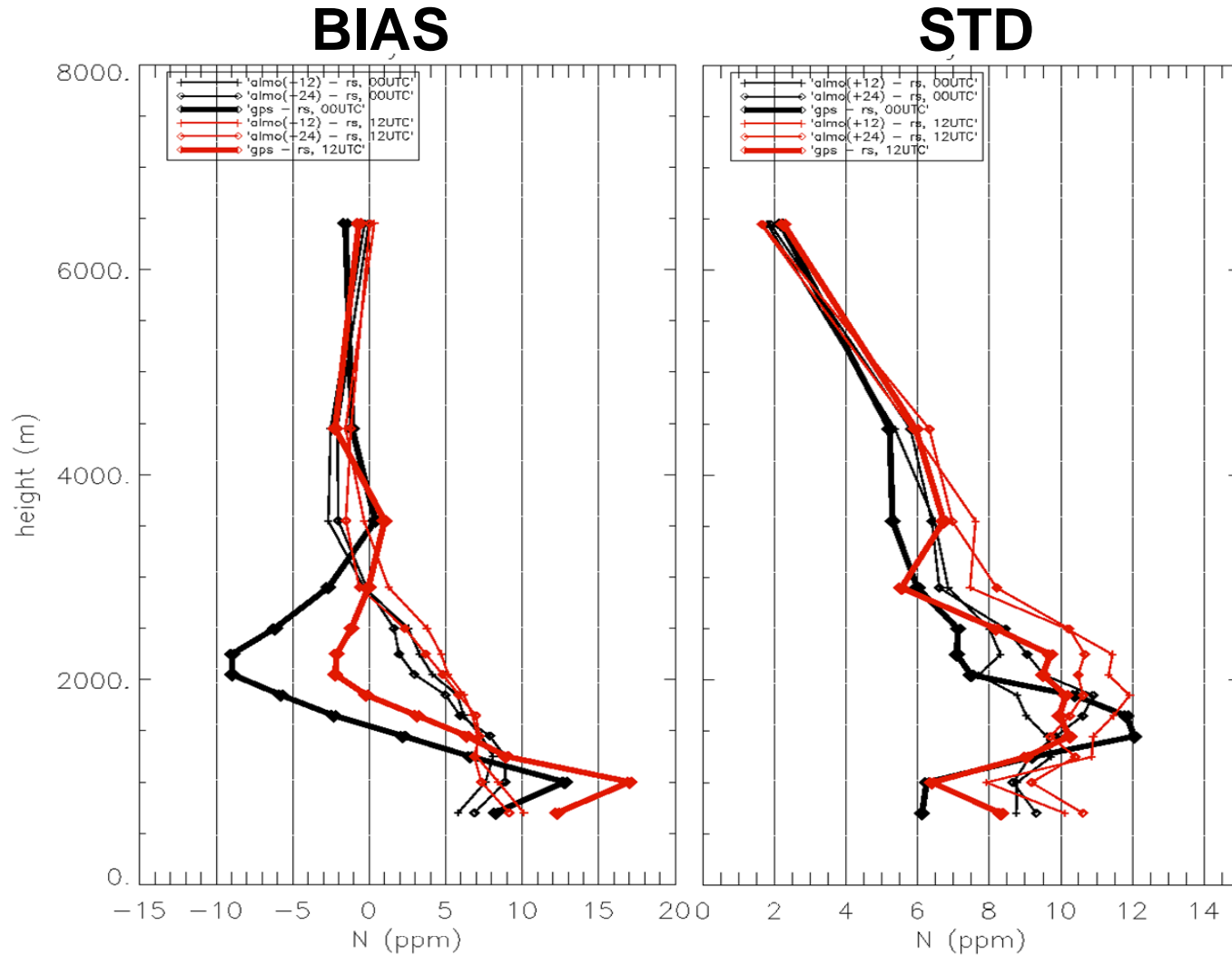


Yearly Humidity Distribution



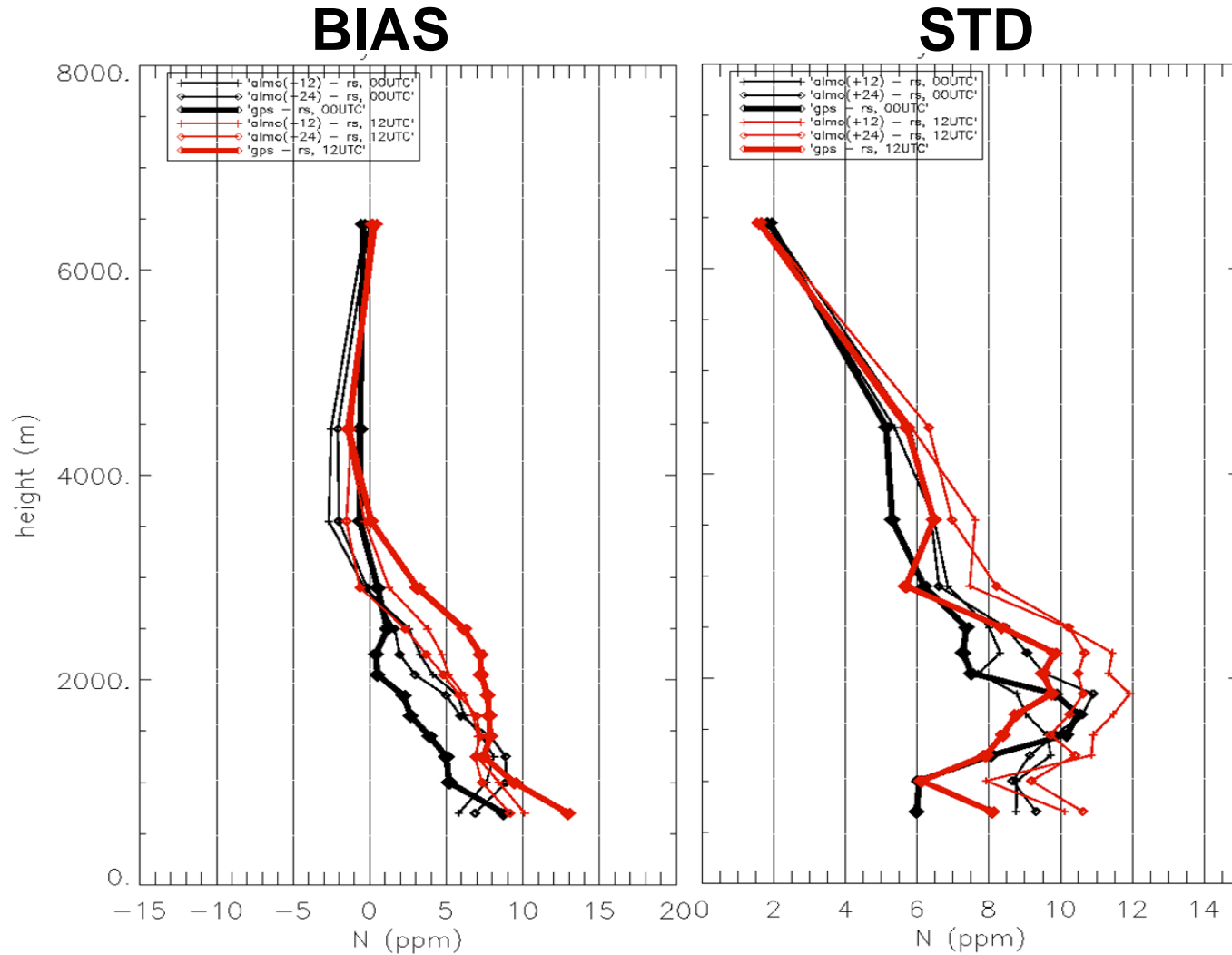


Statistics of July/August 2006





Statistics with Bias Correction





Summary GPS Tomography

- Potentially valuable src of humidity information
- Currently, the quality is insufficient for assimilation
- Problem: equation system is under-determined
 - Lower BC (interpolation of sfc stations)
 - Spatial and temporal neighbour constraints
- GLONASS and GALILEO should help
- Efforts for improvements at ETH Zürich



Outlook

- Parallel LHN test suite continues into winter
- Introduce LHN in COSMO-2 (Q1 2008)
- Add more foreign radar stations
- Improve GPS Tomography retrieval
- Assimilate humidity profiles



Thank you for your attention !