Model for Prediction Across Scales: MPAS



Atmosphere



Global modeling system for unstructured centroidal Voronoi (hexagonal) meshes using C-grid staggering and selective grid refinement

Jointly developed, primarily by NCAR and Los Alamos National Laboratory (LANL), for weather, regional climate, and climate applications

MPAS infrastructure - NCAR, LANL, others. MPAS - <u>A</u>tmosphere (NCAR) MPAS - <u>O</u>cean (LANL) MPAS - <u>I</u>ce, etc.

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Conforming, Variable-Resolution Voronoi Meshes



A conformal mesh is a mesh with no hanging nodes.







C-grid staggering

Conjecture: Smooth refinement on conformal meshes should mitigate many refinement problems.

Why a C-grid staggering?

- Provides good accuracy for the fast (gravity-wave) modes
- Avoids the parasitic mode inherent in an A grid
- Proper reconstruction of tangential velocity ensures stationary geostrophic modes (Thuburn et al, JCP 2009)

Nonhydrostatic MPAS Formulation

Equations:

- Prognostic equations in conservative (flux) form: $(U, V, W, \Theta, Q_j) = \rho_d \cdot (u, v, w, \theta, q_j)$
- Continuity equation for dry air mass
- Terrain-following height-based coordinate ζ
- Horizontal momentum equation in vectorinvariant form.

Integration Scheme:

- Finite-volume (conservative) spatial discretization.
- Split-explicit Runge-Kutta (3rd order), as in Advanced Research WRF
- Higher order WRF transport scheme extended to unstructured polygonal meshes (Skamarock and Gassmann, MWR 2011)

Prognostic Equations:

$$\begin{split} \frac{\partial \mathbf{V}_{H}}{\partial t} &= -\frac{\rho_{d}}{\rho_{m}} \left[\mathbf{\nabla}_{\zeta} \left(\frac{p}{\zeta_{z}} \right) - \frac{\partial \mathbf{z}_{H} p}{\partial \zeta} \right] - \eta \, \mathbf{k} \times \mathbf{V}_{H} \\ &- \mathbf{v}_{H} \mathbf{\nabla}_{\zeta} \cdot \mathbf{V} - \frac{\partial \Omega \mathbf{v}_{H}}{\partial \zeta} - \rho_{d} \mathbf{\nabla}_{\zeta} K - eW \cos \alpha_{r} - \frac{uW}{r_{e}} + \mathbf{F}_{V_{H}}, \\ \frac{\partial W}{\partial t} &= -\frac{\rho_{d}}{\rho_{m}} \left[\frac{\partial p}{\partial \zeta} + g \tilde{\rho}_{m} \right] - \left(\mathbf{\nabla} \cdot \mathbf{v} W \right)_{\zeta} \\ &+ \frac{uU + vV}{r_{e}} + e \left(U \cos \alpha_{r} - V \sin \alpha_{r} \right) + F_{W}, \\ \frac{\partial \Theta_{m}}{\partial t} &= - \left(\mathbf{\nabla} \cdot \mathbf{V} \, \theta_{m} \right)_{\zeta} + F_{\Theta_{m}}, \\ \frac{\partial \tilde{\rho}_{d}}{\partial t} &= - \left(\mathbf{\nabla} \cdot \mathbf{V} \, \theta_{j} \right)_{\zeta} + \rho_{d} S_{j} + F_{Q_{j}}, \end{split}$$

Diagnostics and Definitions:

$$p = p_0 \left(\frac{R_d \zeta_z \Theta_m}{p_0}\right)^{\gamma} \qquad \begin{array}{l} \theta_m = \theta \left[1 + (R_v/R_d)q_v\right] \\ \\ \frac{\rho_m}{\rho_d} = 1 + q_v + q_c + q_r + \dots \end{array}$$



Smoothed Terrain-Following (STF) hybrid Coordinate

$$z(x, y, \zeta) = \zeta + A(\zeta)h_s(x, y, \zeta)$$

Progressively smooths coordinate surfaces while transitioning to a height coordinate

$$A(\zeta) = 1 - \frac{\zeta}{z_t}, \quad h_s(x, y, \zeta) = h(x, y) \quad \Rightarrow \quad \text{BTF coordinate}$$

 $h_s(x, y, \zeta) = h(x, y) \quad \Rightarrow \quad \text{HTF coordinate}$

 $A(\zeta) = 0 \quad \Rightarrow \quad \text{Pure height coordinate}$

Multiple passes of simple Laplacian smoother at each ζ level:

$$h_{s}^{(n)} = h_{s}^{(n-1)} + \beta(\zeta) d^{2} \nabla_{\zeta}^{2} h_{s}^{(n-1)}$$



Resting Atmosphere Simulation - Real Terrain



2-D Mountain Waves - Schar Test Case





(Schar et al. MWR 2002, Klemp et al. MWR 2003)

Density-Current Simulation

Potential Temperature, fixed physical viscosity = 75 m²/s Test case configuration: Straka et al (1993)

WRF simulation

MPAS, t = 900 s



Nonhydrostatic Squall-Line Tests

Low-level shear (0-2.5 km), Weisman-Klemp sounding Warm-bubble perturbation, results at 3 hours





(from Max Menchaca)

Supercell Simulations, MPAS & Reference Cloud Model

- Full MPAS model code used for idealized simulations
- Grid generated on flat plane with periodic boundaries





Vertical velocity contours at 1, 5, and 10 km (c.i. = 3 m/s) 30 m/s vertical velocity surface shaded in red Rainwater surfaces shaded as transparent shells Perturbation surface temperature shaded on baseplane



500 m Rectangular Grid



~500 m MPAS

Supercell Simulations, MPAS & Reference Cloud Model



MPAS Nonhydrostatic NWP Testing

500 hPa temperature (K), heights (m), cinc = 100 m 90N 5000 280 60N 270 30N 260 5800 0 250 30S 240 5800 60S 230 5200 90S 180 301 30E 180 150W 120W 90W 60W C 60E 90F 120E 150E 90N 5000 60N 30N 5800 0 30S5800 60S 5200 9 0 90S 180 150W 901 301 (30E 60E 90E 120E 150E 180 601

5 day forecastValid 00Z 26 January 201160 km uniform mesh

GFS analysis Valid 0Z 26 January 2011



MPAS Nonhydrostatic NWP Testing

5 day forecast Valid 00Z 26 January 2011 60 km uniform mesh





MPAS Nonhydrostatic NWP Testing

MPAS Kinetic Energy Spectra, 60 km mesh 5 day forecast valid 00z 26 January2011





MPAS Development - Summary

Current Status

- Hydrostatic MPAS 3D SVCT solver
 - Implemented as CAM core in the CESM.
 - Aqua-planet simulations within CAM confirm robust behavior.
- Nonhydrostatic MPAS 3D SVCT solver
 - Configurable for the sphere and for 2D and 3D Cartesian domains.
 - Accurate results for idealized test nonhydrostatic test cases (including moisture).
 - Initial full-physics NWP simulations are encouraging.

Future Development

- Testing for NWP and regional climate applications on uniform and variable-resolution meshes.
- Scale-aware physics on variable resolution meshes.
- Nonhydrostatic core to be implemented as CAM core later this year.
- First MPAS release to friendly users anticipated about the first of next year.





