

# *Ensemble Forecasting at the Meteorological Service of Canada: Status, Research, and Plans*

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# Talk Outline

- ◆ **Currently operational at the global scale**
  - *Ensemble data assimilation (EnKF)*
  - *Medium range ensemble forecasting*
  - *Improvements in the EnKF and global forecast system*
- ◆ **Collaboration with NCEP**
  - *North American super-ensemble (NAEFS)*
- ◆ **Research and plans**
  - *Short range ensemble forecasting*



# *Ensemble Data Assimilation*

- ◆ *The ensemble Kalman filter has been operational since January 2005*
  - *2x48 members (we use two ensembles)*
  - *Impact of (perturbed) observations is localized to 2800 km in the horizontal, and to ~15 km in the vertical*
  - *Data are supposed valid at the synoptic times*



# The Ensemble Kalman Filter

$$\begin{aligned}\mathbf{X}_a^{\alpha,i} &= \mathbf{X}_b^{\alpha,i} + \mathbf{K}^\beta (y^{\alpha,i} - \mathbf{H}\mathbf{X}_b^{\alpha,i}) \\ \mathbf{K}^\beta &= \rho \circ (\mathbf{P}^\beta \mathbf{H}^T) (\rho \circ (\mathbf{H}\mathbf{P}^\beta \mathbf{H}^T) + \mathbf{R})^{-1} \\ \mathbf{P}^\beta \mathbf{H}^T &= \frac{1}{N-1} \sum_{i=1}^N (\mathbf{X}_b^{\beta,i} - \overline{\mathbf{X}}_b^\beta) (\mathbf{H}\mathbf{X}_b^{\beta,i} - \mathbf{H}\overline{\mathbf{X}}_b^\beta)^T \\ \overline{\mathbf{X}}_b^\beta &= \frac{1}{N} \sum_{i=1}^N \mathbf{X}_b^{\beta,i}\end{aligned}$$

$\rho$  is the localization covariance matrix

$\mathbf{X}_a^{\alpha,i}$  is one analysis in ensemble  $\alpha$

$\mathbf{X}_b^{\alpha,i}$  is one perturbed background field in ensemble  $\alpha$

$y^{\alpha,i}$  is one perturbed observation in ensemble  $\alpha$

$\mathbf{R}$  is observational error covariance matrix

$N$  is the number of members per ensemble

## ***The numerical model used for background:***

- *Global Environmental Multiscale (GEM) model (Côté et al., 1998)*
- *Grid point model*
- *Very similar to model used for deterministic medium range weather forecasts*
- *300x150 horizontal grid points*
- *28 vertical levels with top at 10 hPa*
- *The background fields are obtained from adding a 6 hour model prediction and a model error term (to be changed)*



## ***The “model error” component:***

- *Hypothesis: the model error is similar in structure to the forecast error used in our centre's 4D-VAR*
- **$P(t+6h) = M P_a M^T + 0.25 P_{4D-VAR}$**
- *Isotropic random error statistics for each member*
- *Currently the model error term includes:*
  - *A balanced component for wind, temperature and surface pressure*
  - *An unbalanced temperature component significant near the surface, in the tropics and near the top*

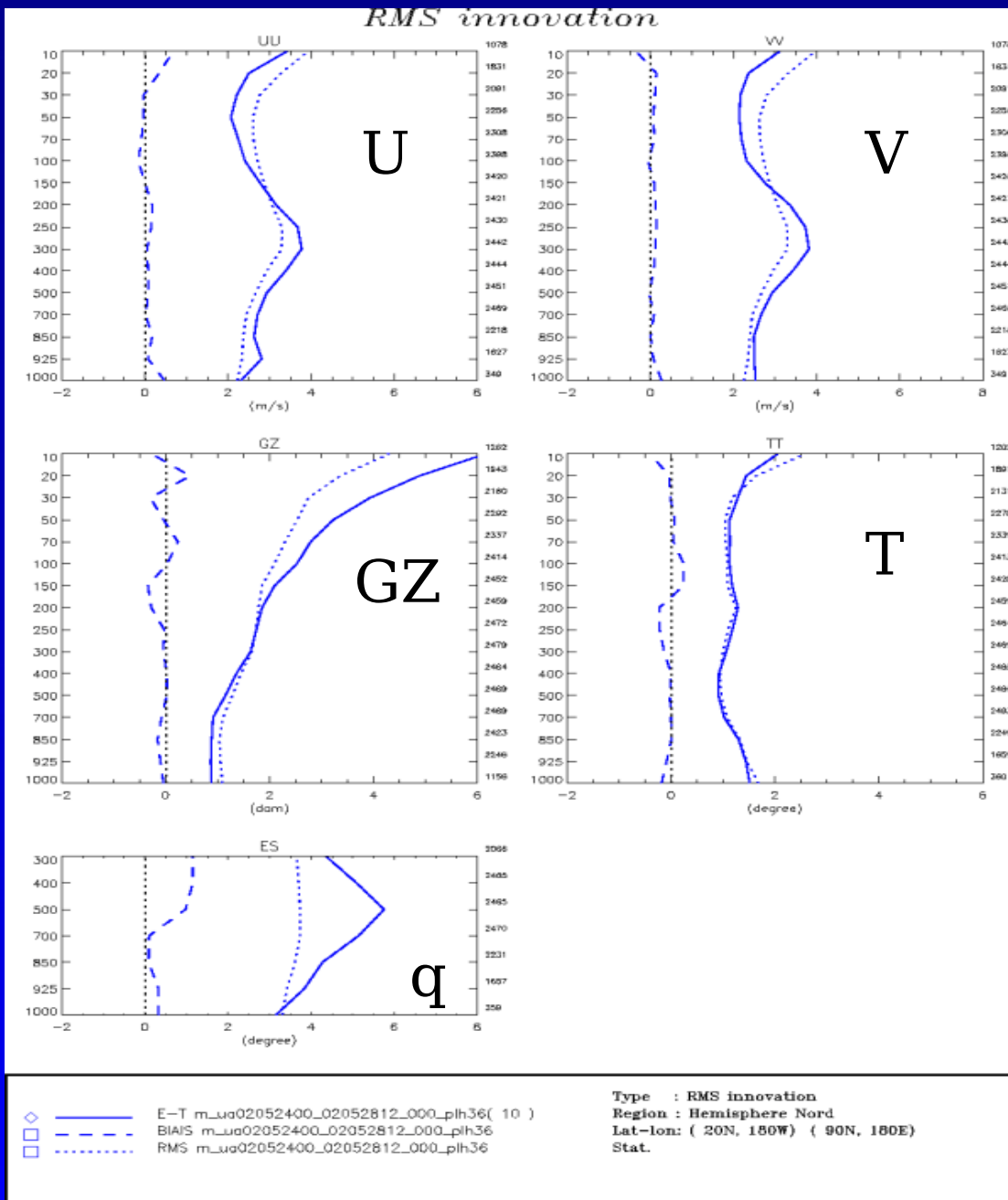


# *The observations:*

- *Try to assimilate same data as 4D-VAR*
- *Benefit from operational background check and variational quality control*
- *Same error statistic for matrix  $R$  as in 4D-VAR*
- *Currently, we assimilate:*
  - *radiosondes:  $u$ ,  $v$ ,  $T$ ,  $q$ , and surface pressure*
  - *aircrafts:  $u$ ,  $v$ , and  $T$*
  - *satellites: cloud track winds  $u$ ,  $v$ , and AMSU-A radiances*
  - *surface observations:  $T$ , and surface pressure*
- *Surface humidity not yet assimilated*



# Quality of error statistics

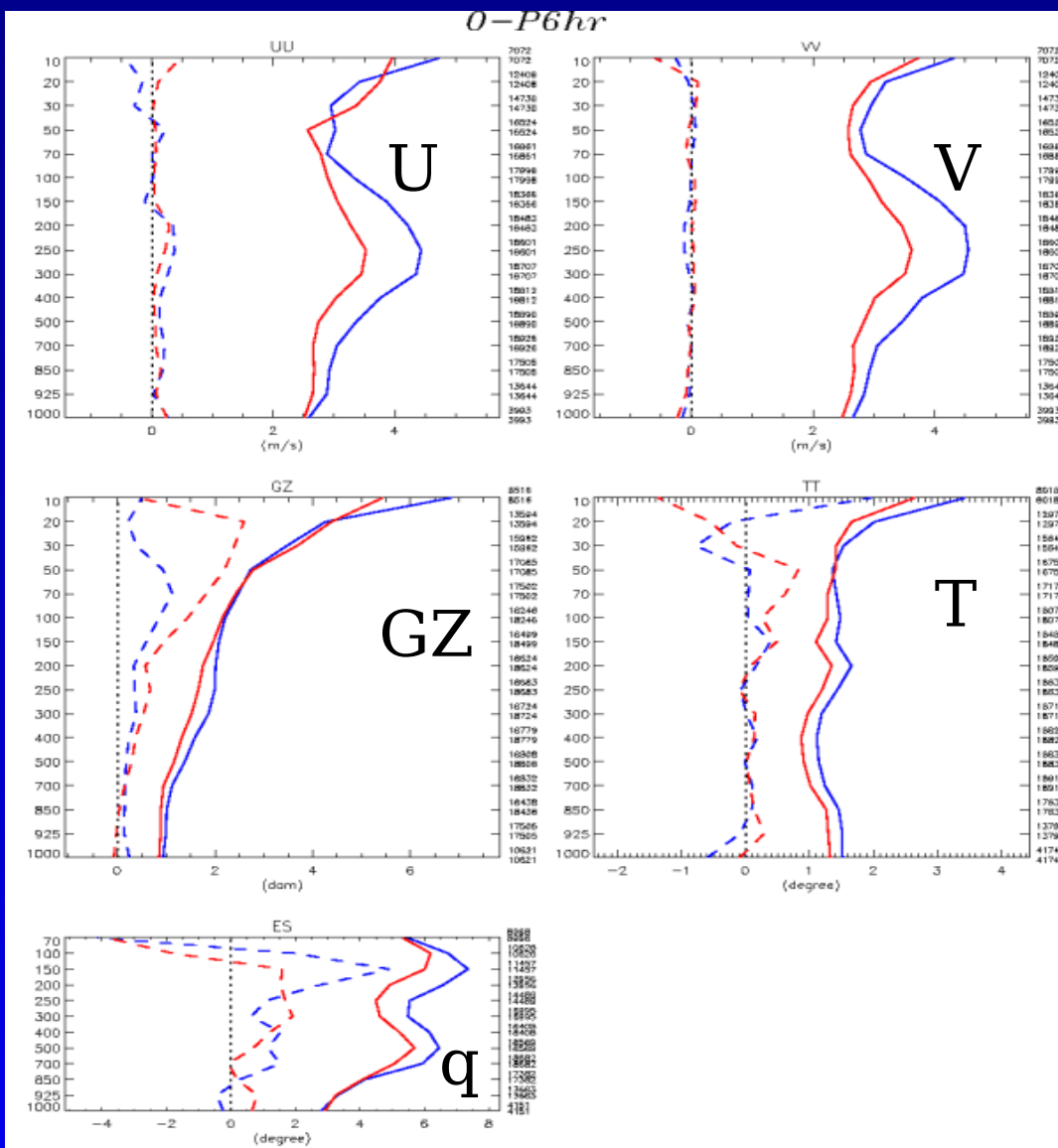


- The solid line is the rms amplitude of the innovations corresponding with radiosondes.
- The dashed line is the ensemble based prediction of the innovation amplitude. It is the root of the sum of observational variance and ensemble spread.
- There is excellent agreement for the temperature. For winds the ensemble spread is too large near the model top. The spread is too small for humidity.

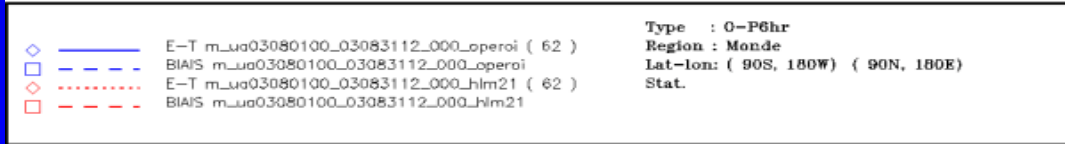




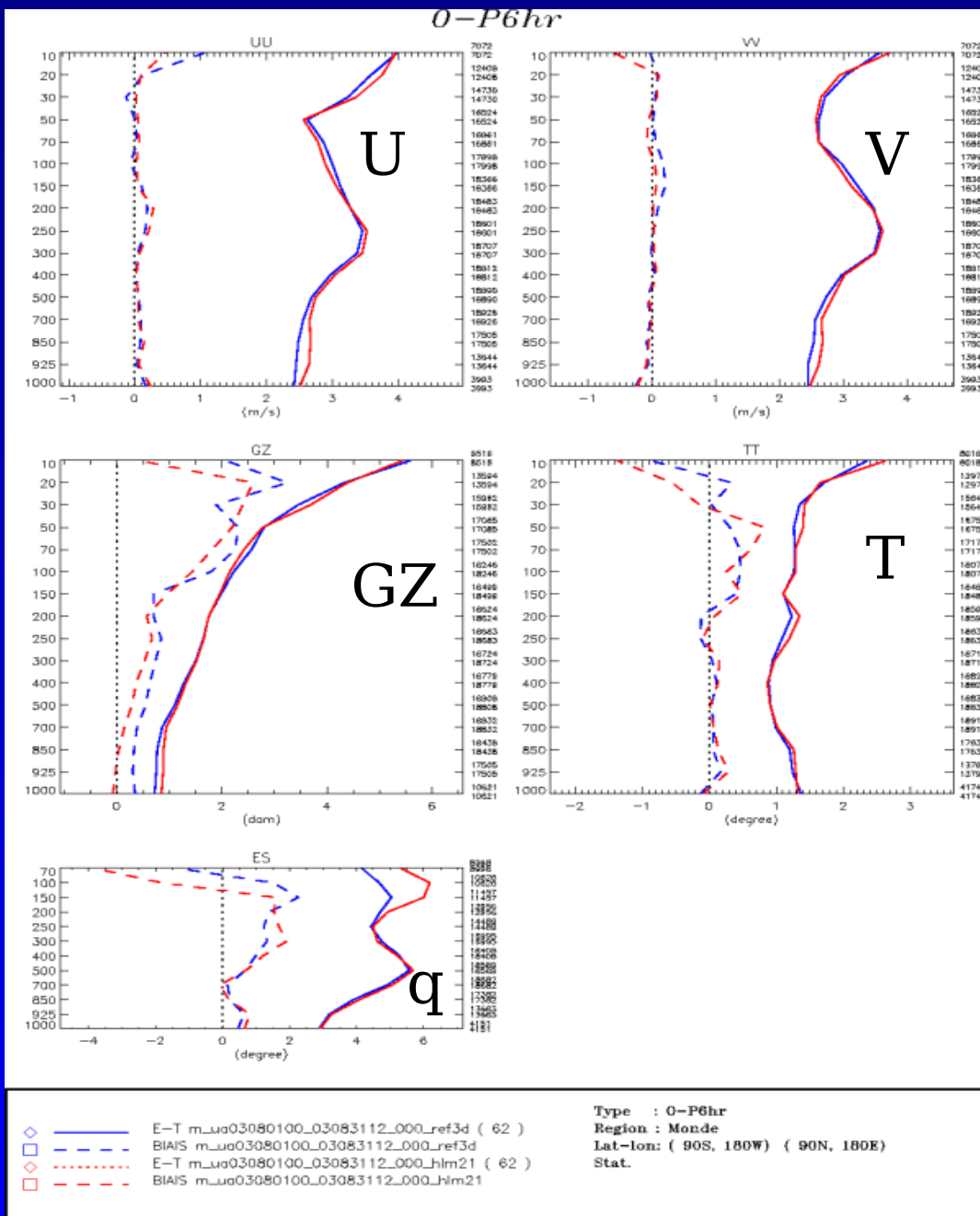
# Comparison with optimal interpolation



- The solid line is the rms amplitude of the innovations corresponding with radiosondes.
- The dashed line is the bias
- Red: EnKF
- Blue: Optimal Interpolation
- Scores are for summer



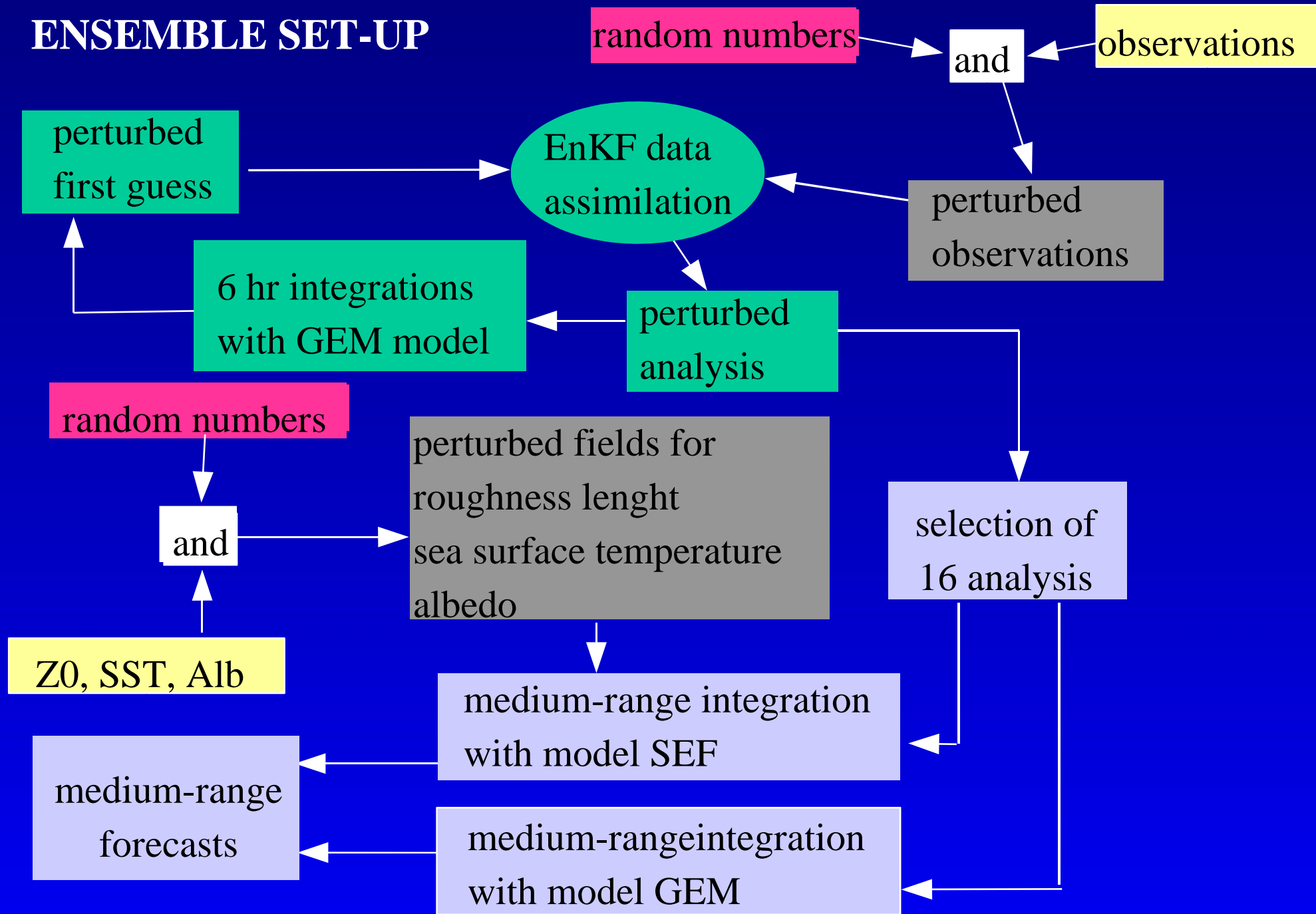
# Comparison with 3D-VAR



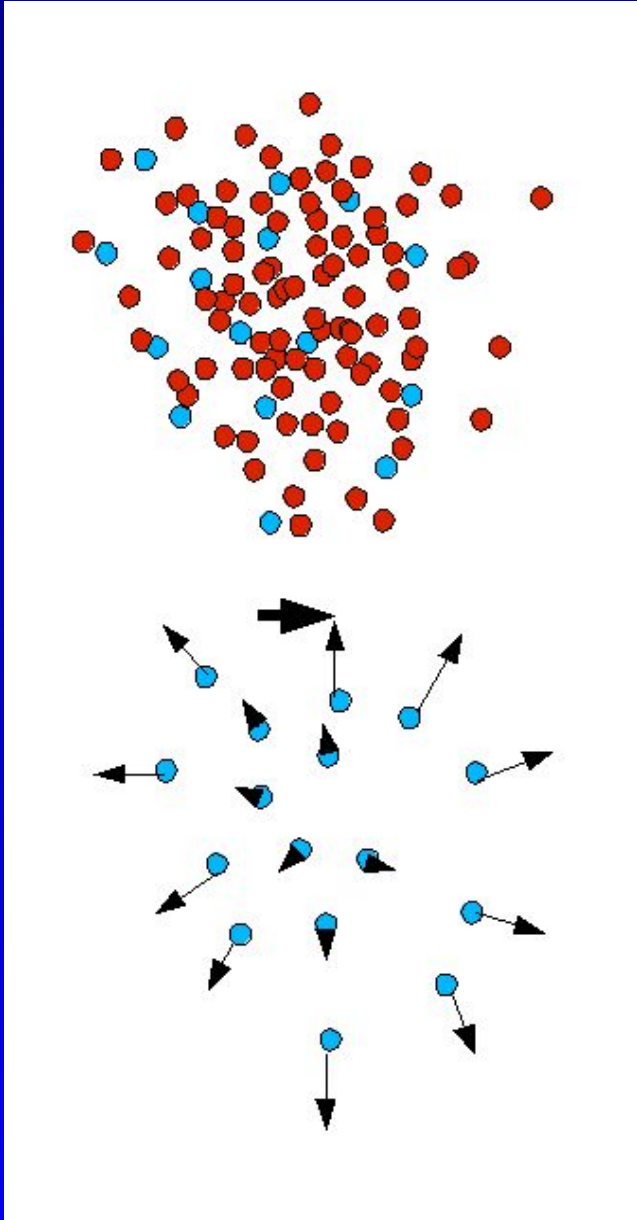
- The solid line is the rms amplitude of the innovations corresponding with radiosondes.
- The dashed line is the bias
- Red: EnKF
- Blue: 3D-VAR
- Scores are for summer



# ENSEMBLE SET-UP



# From an Ensemble of 96 Initial Conditions to an Ensemble of 16 10-Day Forecasts



- Choose randomly 16 members out of 96, preserving the ensemble mean.
- Inflate the ensemble standard deviation by a factor of 1.5 for  $u$ ,  $v$ ,  $T$ ,  $q$ , and  $p_{surf}$
- Correct  $q$  to avoid supersaturation and negative specific humidity



# *Medium Range Ensemble Forecasting at CMC*

- ◆ *Use of multi-model multi-parameterization approach*
  - *This is our current way of representing the “model error” component of the 10-day forecasts*
  - *The initial condition uncertainties are provided by the EnKF*
- ◆ *8 members from the GEM model (grid point) at 300x150*
- ◆ *8 members from the SEF (spectral finite element) at T149*

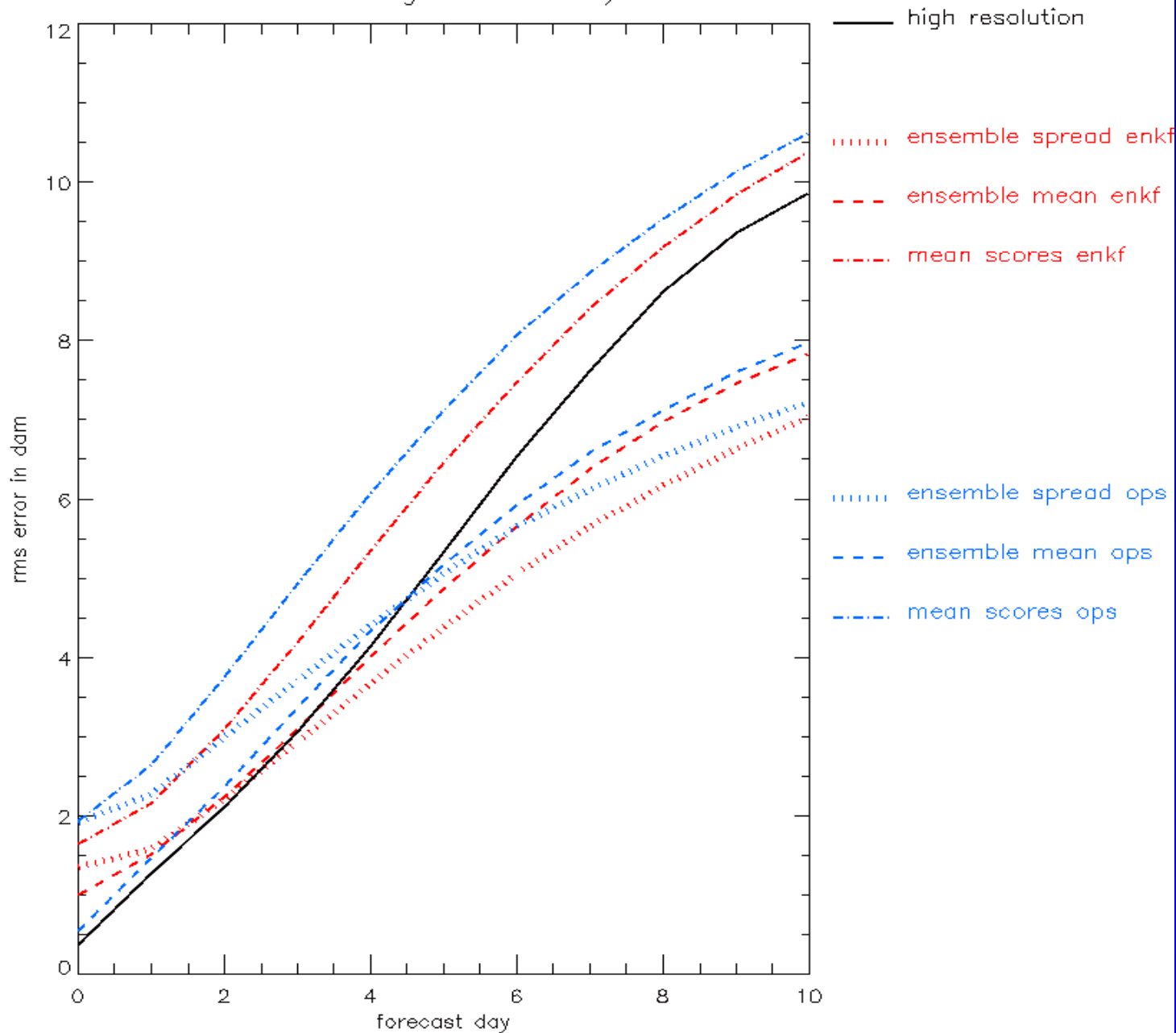


# Description of the different models

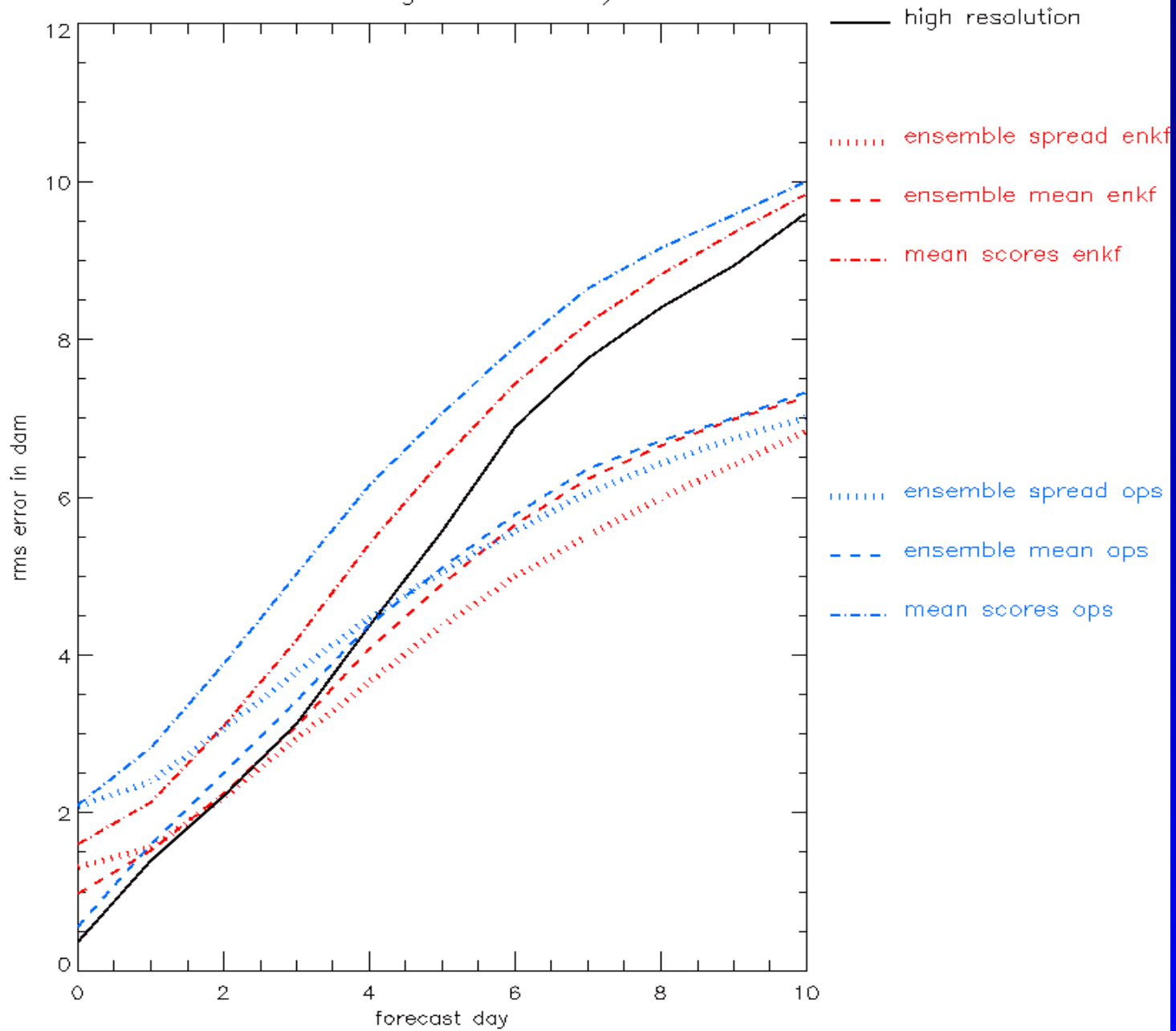
SEF (T149)	Radiation scheme	Convection deep	Schemes shallow	Surface scheme	Number of levels	Time level
Control	Garand	Kuo	conres	Fcrest	27	3
1	Garand	Kuo	conres	ISBA	27	3
2	Garand	Ras	ktrsnt	Fcrest	27	3
3	Garand	Kuo	conres	Fcrest	27	3
4	Garand	Ras	ktrsnt	ISBA	27	3
5	Garand	Ras	ktrsnt	Fcrest	27	2
6	Garand	Kuo	conres	ISBA	27	2
7	Garand	Ras	ktrsnt	ISBA	27	2
8	Garand	Kuo	conres	Fcrest	27	2
GEM (1.2 <sup>o</sup> )	Radiation Scheme	Convection deep	Schemes shallow	Surface scheme	Number of levels	Time level
9	Garand	Kuosym	ktrsnt	Fcrest	28	2
10	Garand	Ras	conres	ISBA	28	2
11	Garand	Ras	conres	Fcrest	28	2
12	Garand	Kuosym	ktrsnt	ISBA	28	2
13	Garand	Kuostd	ktrsnt	Fcrest	28	2
14	Garand	Kuostd	ktrsnt	ISBA	28	2
15	Garand	Kuosym	conres	ISBA	28	2
16	Garand	Kuo	conres	Fcrest	28	2



quality of the ensemble forecast  
ops\_enkf\_JAN 2004 sef\_gem  
global area 500.000 mb  
validation against the analysis



quality of the ensemble forecast  
ops\_enkf\_AOUT 2003 sef\_gem  
global area 500.000 mb  
validation against the analysis





# *In Development*

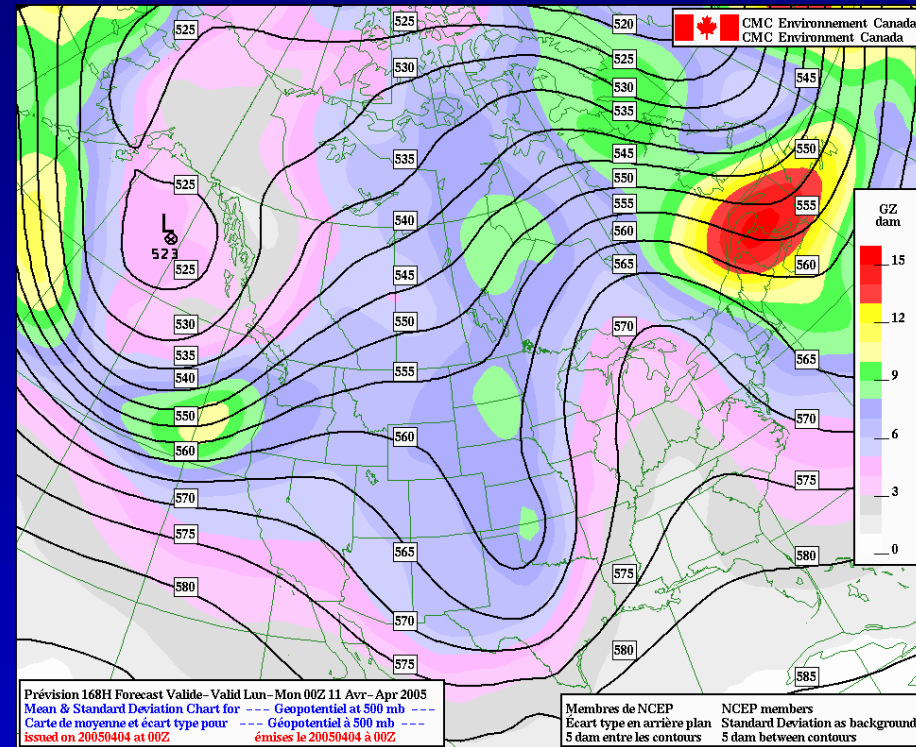
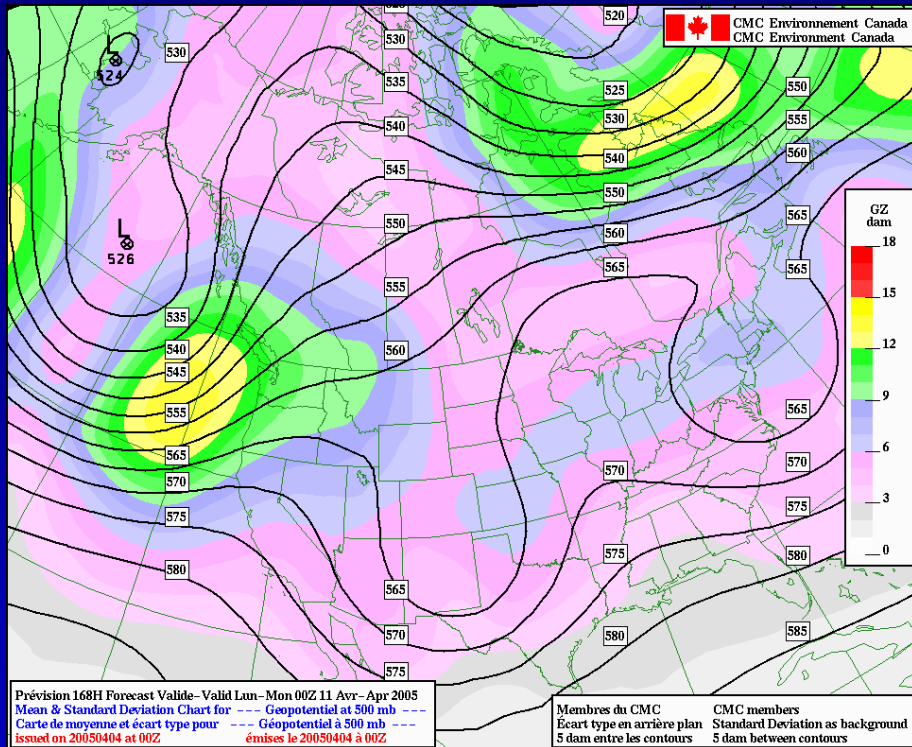
- ◆ *EnKF*
  - *4 ensemble configuration (allow weaker localization)*
  - *Later stage, assimilate data at non-synoptic times*
- ◆ *Forecast models*
  - *Test stochastic backscatter scheme based on Shutts*
  - *Reduce number of parameterizations*
  - *Extend forecasts to 15 days twice daily*



# *The North-American Ensemble Forecast System (NAEFS)*

- ◆ *Participants: MSC (Canada), NWS (USA), and NMSM (Mexico)*
- ◆ *High level agreement: Feb. 2003 (Mexico became involved in Oct. 2004)*
- ◆ *Product generation made routinely at MSC: early 2005 (in development mode, still not operational)*
- ◆ *Major tasks:*
  - *Exchange ensemble data between two centers (MSC and NWS)*
  - *Bias correction of each set of ensemble*
  - *Develop products based on joint ensemble (high impact weather?)*
  - *Verify joint product suite, evaluate added value*





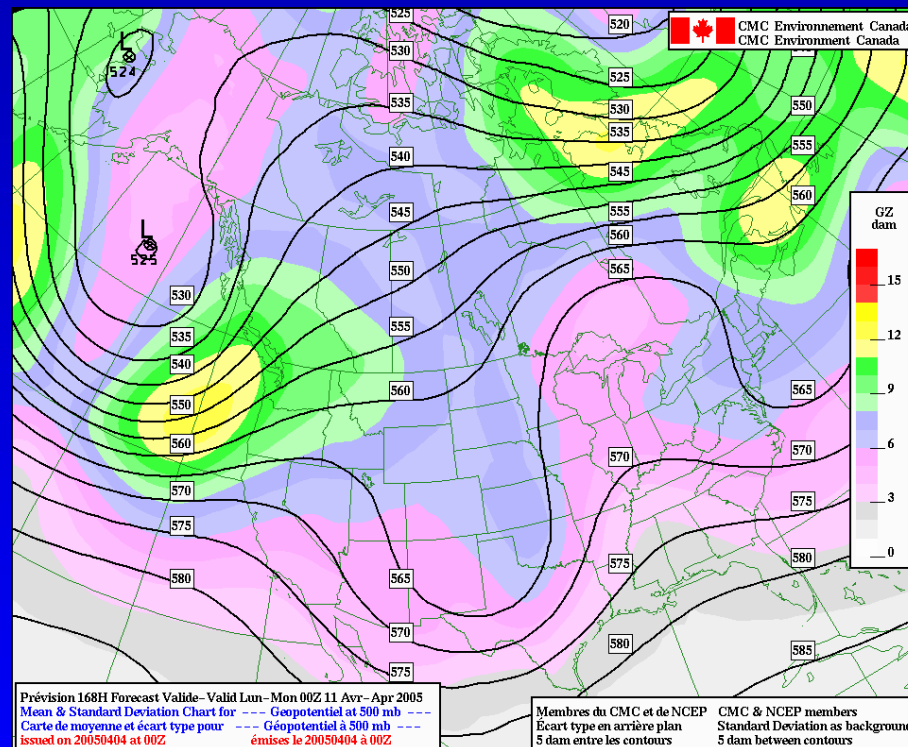
MSC

NWS

GZ at 500 hPa  
ensemble mean  
(black lines)

7-day forecast over  
North America valid  
April 11 2005

Ensemble standard  
deviation (color code)



Joint



# *Development of a Regional EPS*

*M. Charron (MSC), L. Spacek (MSC), Li Xiaoli (McGill)*

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- *Regional EPS based on targeted singular vectors*
  - *A version at 28 km resolution with 20 members over North America (LAM)*
  - *A version at 15 km resolution with 16 members over Eastern Canada (LAM)*



# *The 15 km REPS at MSC-McGill*

- ◆ *8 singular vectors are calculated on a low resolution global grid (240x120, or about 150 km)*
- ◆ *Initial norm is global; final norm is located over a domain covering Eastern Canada (will be adapted to be over Beijing)*
- ◆ *Optimisation period is 24h and singular vector calculation includes*
  - *Vertical diffusion*
  - *Gravity wave drag*
  - *Deep Convection (Kuo)*
  - *Stratiform precipitation*
- ◆ *SVs are interpolated to the resolution of the pilot model (100 km res.)*
- ◆ *SVs are used to perturb the pilot runs producing lateral boundary and initial conditions of 16 LAM integrations*



# Physics perturbations with Markov processes

- Physical parameters/tendencies can be perturbed by a function  $F(\lambda, \varphi, \eta, t)$  given by:

$$f(\lambda, \varphi, \eta, t) = \sum_{l=0}^L \sum_{m=-l}^l \sum_{k=0}^K a_{lmk}(t) Y_{lm}(\lambda, \varphi) e^{ik\eta}$$

$$a_{lmk}(t) = e^{-\Delta t/\tau} a_{lmk}(t - \Delta t) + R(t)$$

$$F(\lambda, \varphi, \eta, t) = S f(\lambda, \varphi, \eta, t)$$



# *Perturbation of CAPE in the Kane-Fritsch convection scheme*

- ◆ *Only the LAMs are perturbed with Markov chains*
- ◆ *CAPE perturbation similar to Lin and Neelin (GRL 2000), except*
  - ◆ *CAPE becomes  $CAPE * F(\lambda, \phi, t)$*
- ◆ *Decorrelation time scale: 12 and 6 hours*
- ◆ *Truncation of the perturbed field: T7 and T14*

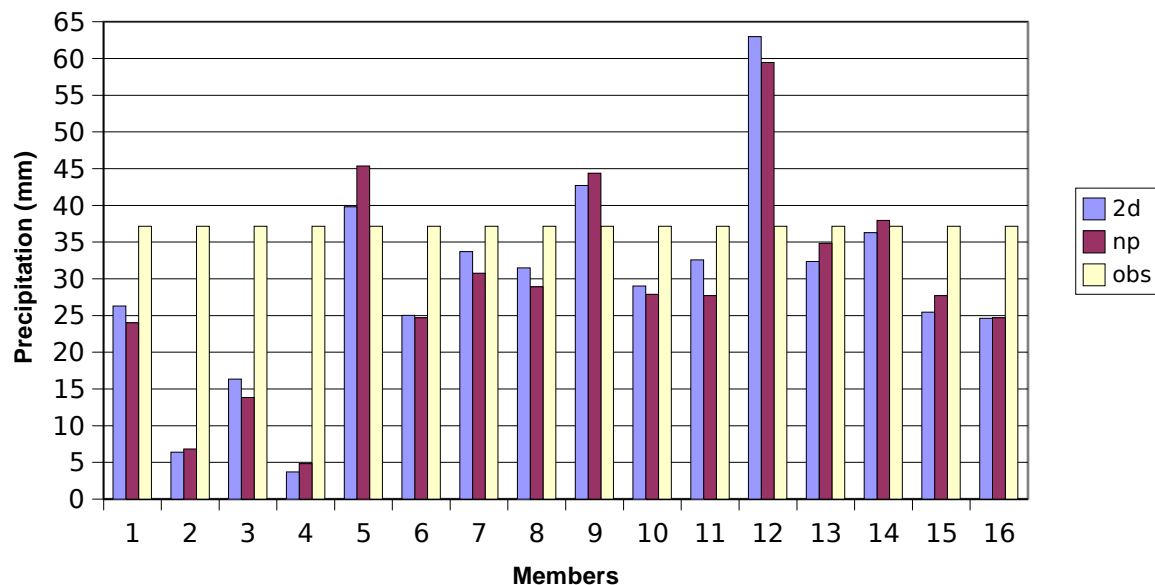


# Impact of perturbing CAPE on precipitation

→ Perturbing the ICs with SVs has more impact on precip than perturbing CAPE

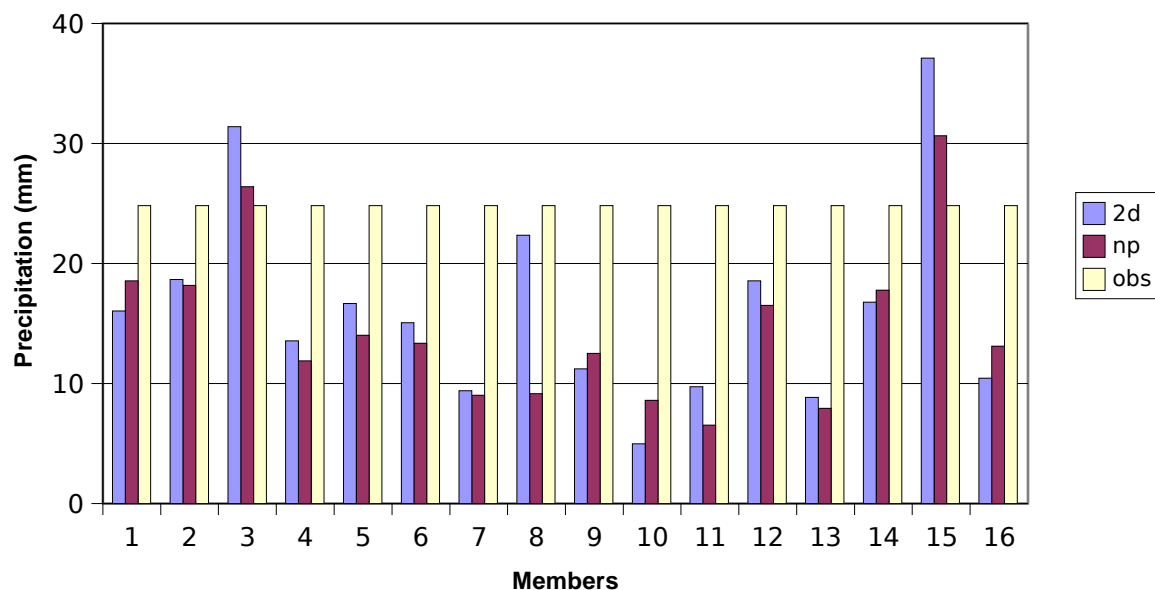
Comparison of accumulated 24h precipitation at grid (105, 88)

2003-08-05 00h

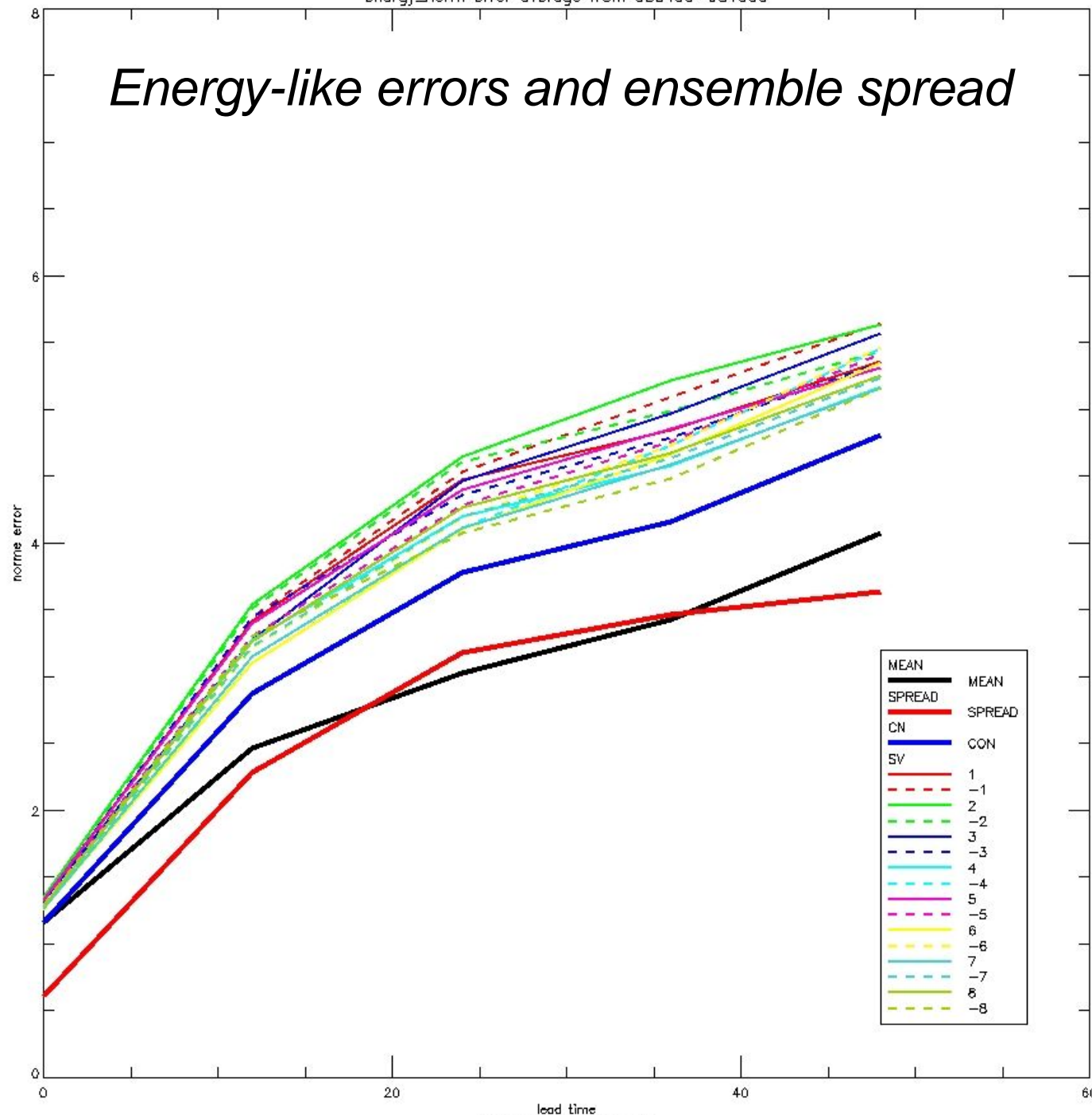


Comparison of accumulated 24h at grid (105, 88)

2003-08-06 00h



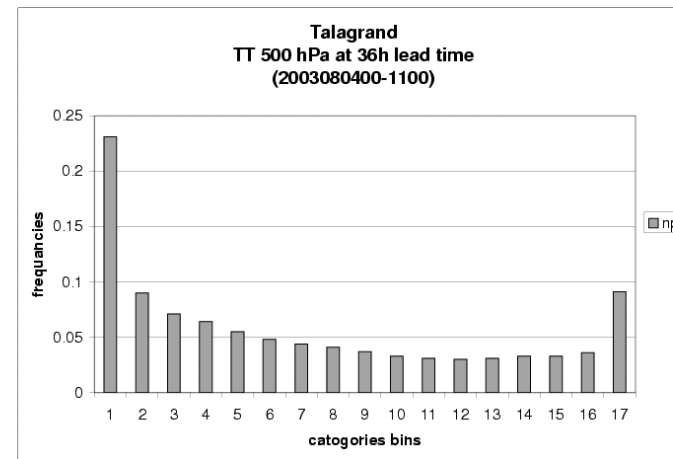
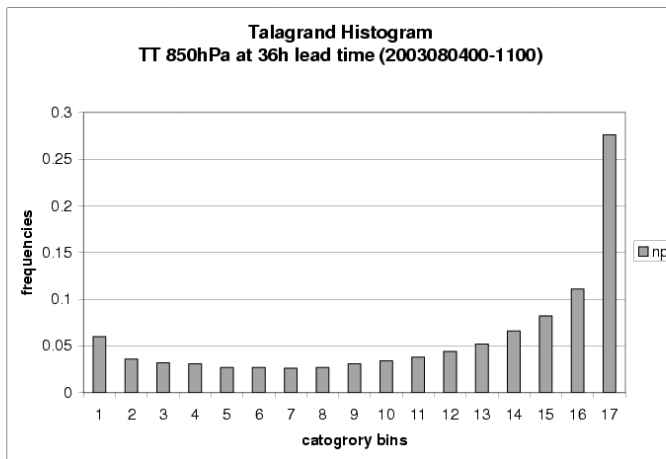
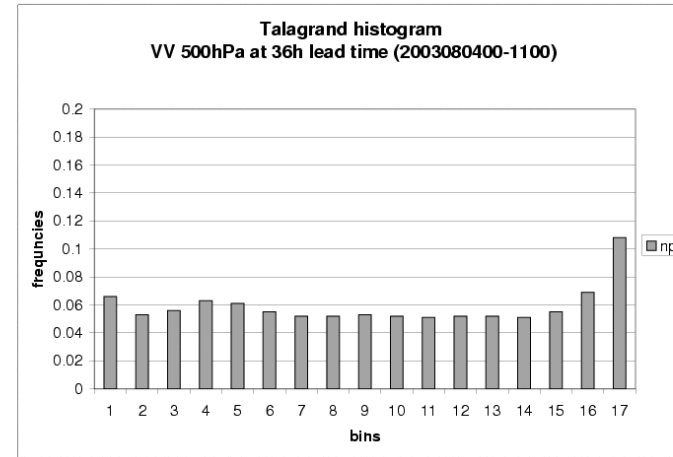
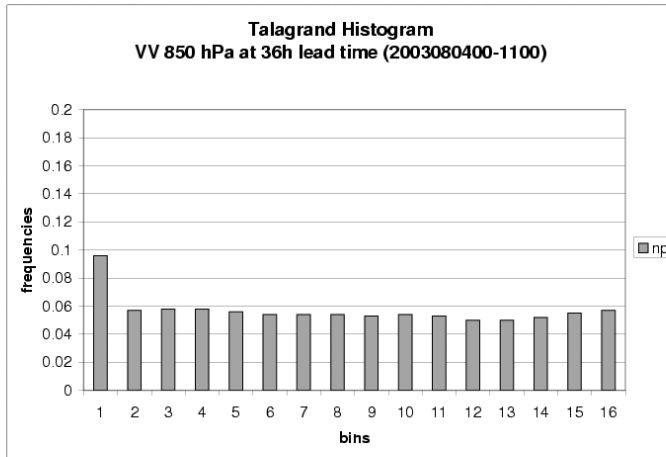


*Energy-like errors and ensemble spread**Blue: Unperturbed**Black: Ens. Mean**Red: Ens. Std Dev.*

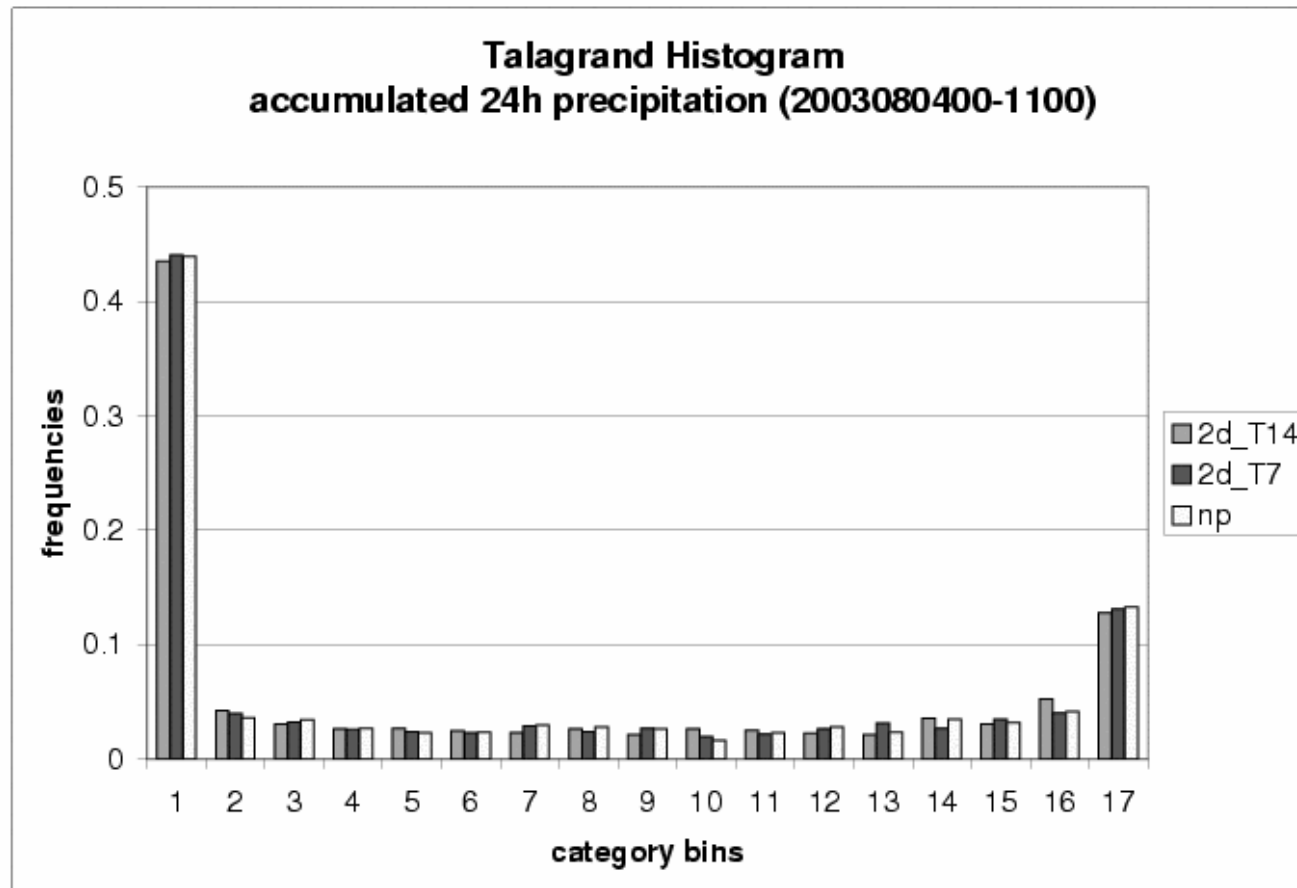
Wed Mar 16 11:52:48 2005



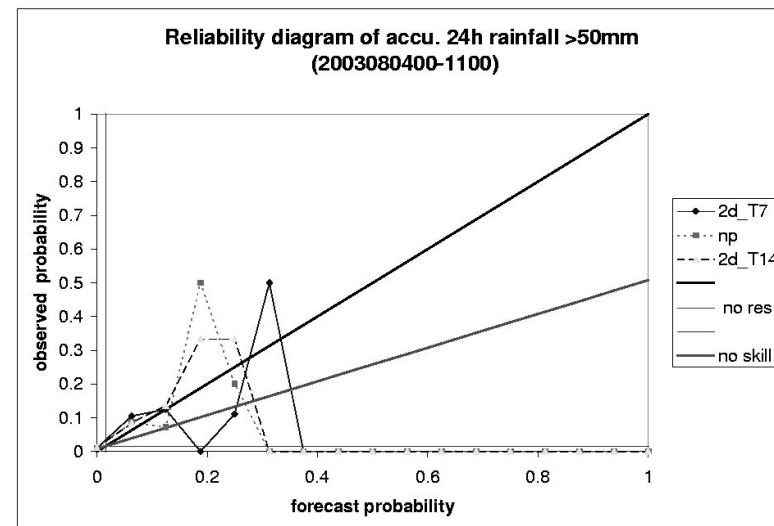
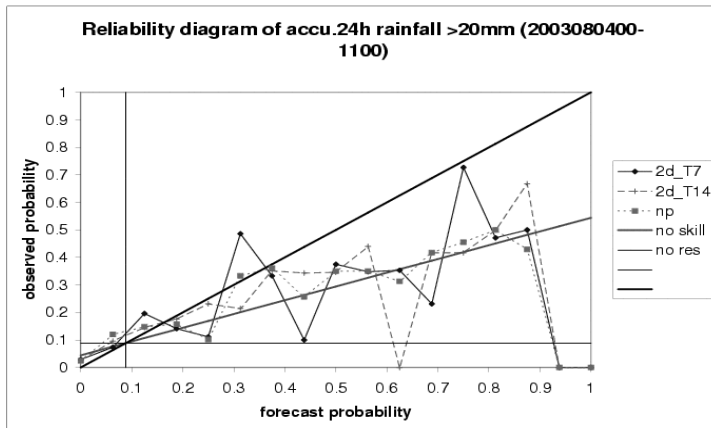
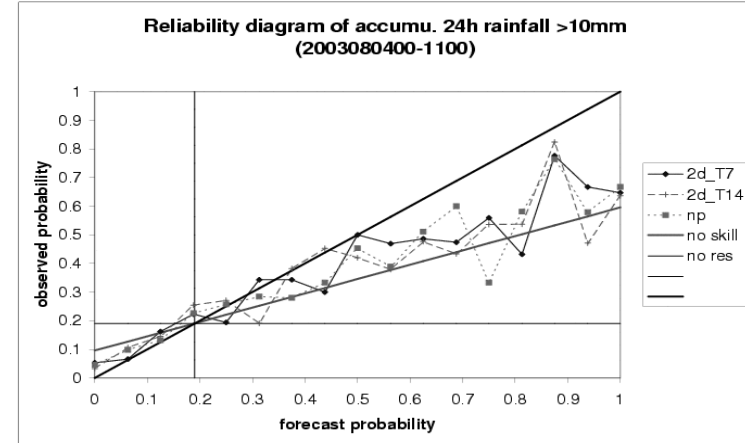
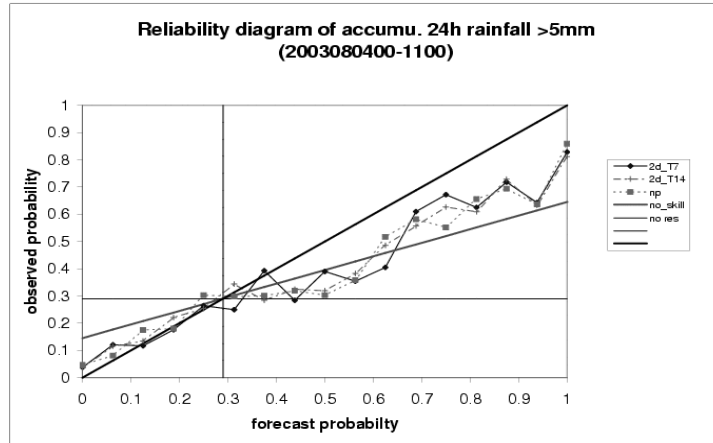
# Talagrand Diagrams (August 4 to 11, 2003)



# Talagrand Diagrams (August 4 to 11, 2003)



# Reliability Diagrams for Precipitation



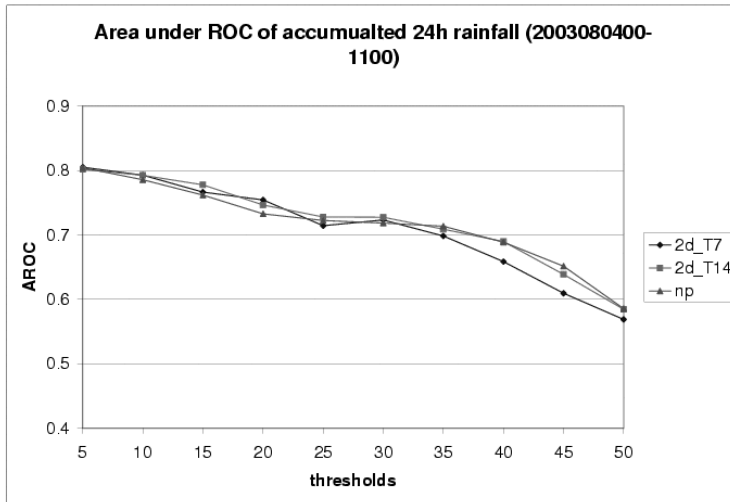
# *Relative Operating Characteristics (ROC) and Brier Skill Scores (BSS)*

- *For precipitation:*
  - *Binary event: 24-hour accumulation (lead times from 12 to 36 hours) is greater than some specified thresholds*
  - *Dataset: 300 rain gauges over Québec*
- *For temperature:*
  - *Binary event: temperature is lower than mean temperature minus one standard deviation (different at each grid point and calculated over the studied period)*
  - *Dataset: 3D-VAR analyses at 15 km resolution*

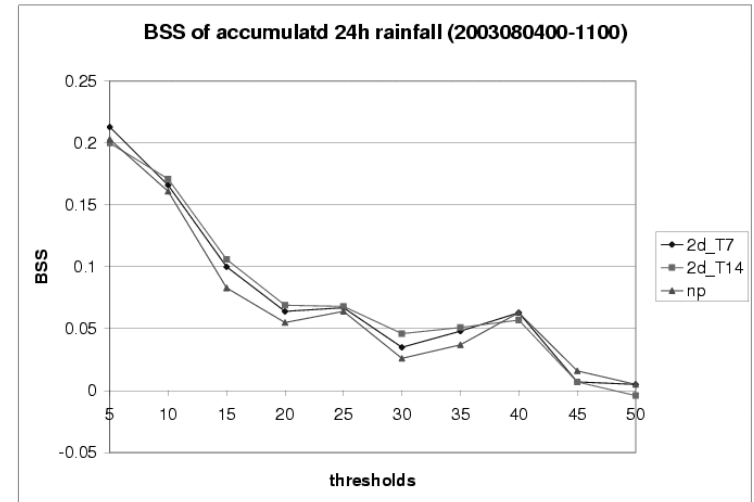


Precip. 24-h accum

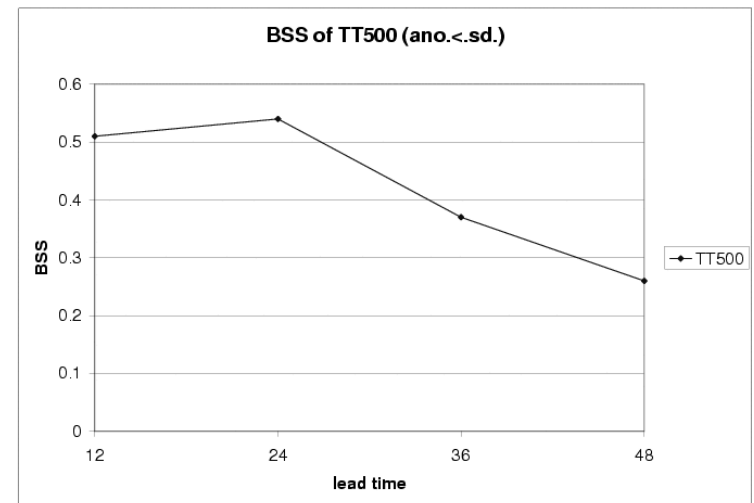
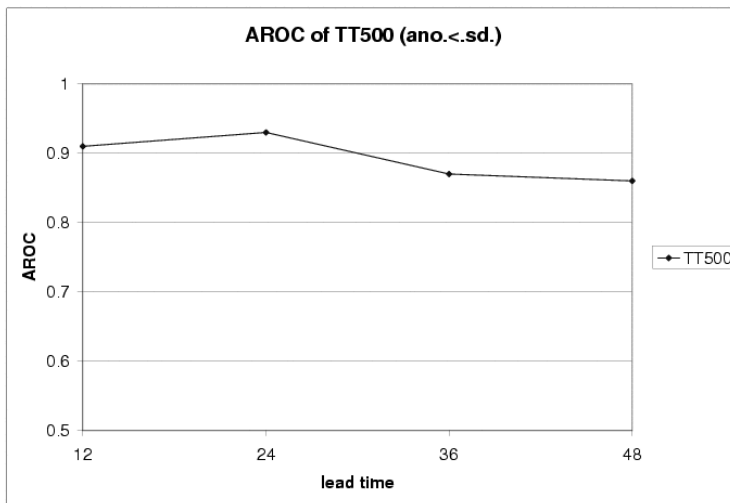
# Area under ROC



# Brier Skill Score



Temperature



# *Long term objectives*

- *Find a better way to account for uncertainties of the model, perhaps by introducing parameterizations that are inherently stochastic*
- *Develop a regional ensemble Kalman filter (stretched grid or limited area model)*
- *Compare the singular vector approach and a (still to be built) regional EnKF for regional ensemble predictions*

