

# Representation of topography by the thin-wall approximation in a height coordinate

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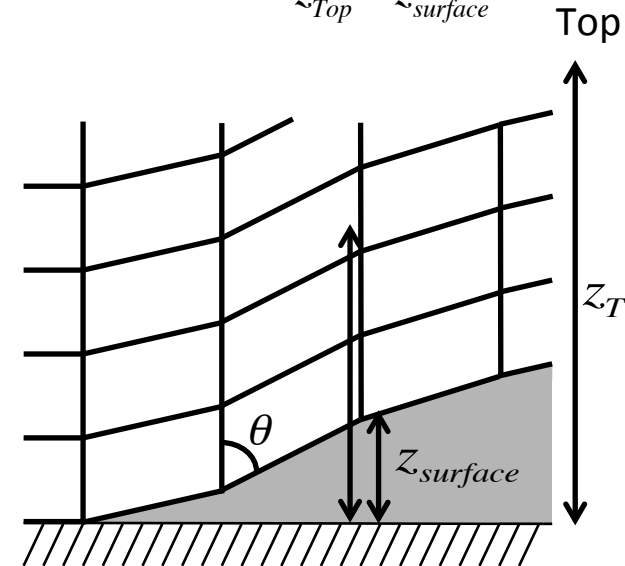
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2. Model description
3. Thin-wall approximation
4. Mountain wave experiments
  - A. The height of mountain top is 10m
  - B. The height of mountain top is 400m
5. Summary

# 1. Background

- ✓ In higher resolution models ( $\leq 10\text{km}$ ), the detailed topographical data is required.
- ✓ In terrain-following approach, only the upper and lower boundary conditions are imposed.
- ✓ This approach shows a relatively decent performance over gentler slopes.
- ✓ Over steeper slopes, this approach induces large truncation errors and tends to be numerically unstable.

Basic terrain-following

$$z^* = z_{Top} \frac{z - z_{surface}}{z_{Top} - z_{surface}}$$



The terrain-following coordinate representation of a topography

**➔ We focus on the alternatives to the terrain-following approach.**

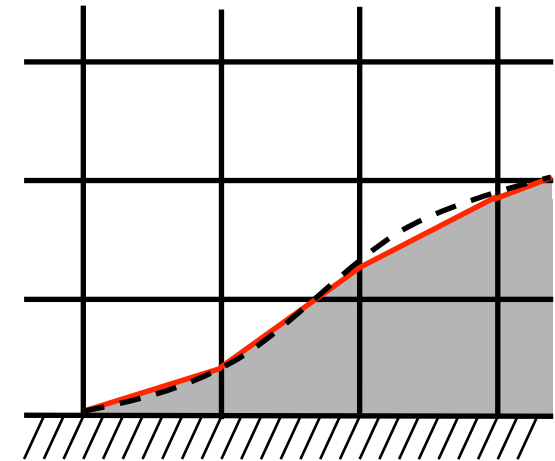
# Other representations

## ✓ Cut cell method

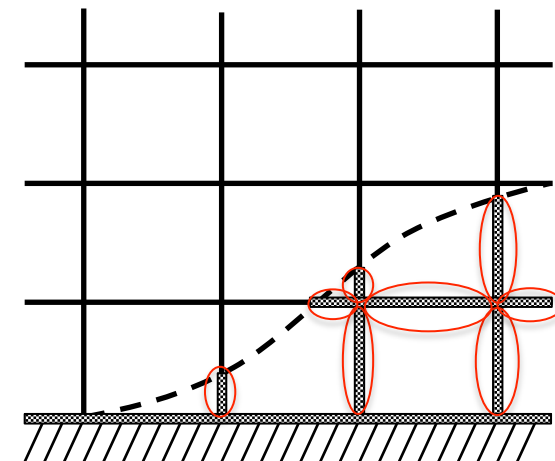
- This method satisfies a conservation law using a finite-volume method.
- Small cell problem occurs.

## ✓ Thin-wall approximation

- The assumption that volume of cells intersected by the surface remains a full atmospheric cell.
- The parts under topography is represented by thin walls.
- Advection-form equations are used in pervious works such as  
Steppeler et al. (2002, 2006, 2011),  
Lock (2008), Lock et al. (2012).



Cut cell method



Thin-wall approximation

# Purposes

- ✓ To implement the representation of topography by the thin-wall approximation to fully compressible flux-form equations.
- ✓ To confirm the conservation of momentum flux.

	Steppeler et al. (2002)	Our approach
	<b>Advection-form</b>	<b>Flux-form</b>
Equations	$\frac{\partial T}{\partial t} = -u \frac{\partial T}{\partial x} - w \frac{\partial T}{\partial z} - \frac{p}{\rho C_v} \left( \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} \right)$ $\frac{\partial u}{\partial t} = -u \frac{\partial u}{\partial x} - w \frac{\partial u}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial x}$ $\frac{\partial w}{\partial t} = -u \frac{\partial w}{\partial x} - w \frac{\partial w}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial z} - g$ $\frac{\partial p}{\partial t} = -u \frac{\partial p'}{\partial x} - w \frac{\partial p'}{\partial z} + g \rho_0 w - \frac{C_p}{C_v} p \left( \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} \right)$	$\frac{\partial \rho'}{\partial t} = -\frac{\partial \rho u}{\partial x} - \frac{\partial \rho w}{\partial z}$ $\frac{\partial \rho u}{\partial t} = -\frac{\partial \rho u u}{\partial x} - \frac{\partial \rho w u}{\partial z} - \frac{\partial p'}{\partial x}$ $\frac{\partial \rho w}{\partial t} = -\frac{\partial \rho u w}{\partial x} - \frac{\partial \rho w w}{\partial z} - \frac{\partial p'}{\partial z} - \rho' g$ $\frac{\partial \rho e}{\partial t} = -\frac{\partial \rho u h}{\partial x} - \frac{\partial \rho w h}{\partial z} + u \frac{\partial p'}{\partial x} + w \frac{\partial p'}{\partial z} + w \frac{\partial p_s}{\partial z}$
Boundary conditions	Upwind difference	Velocities is set to zero at sides of a scalar cell.

# 2. Model description

- Equations (Sato 2002)

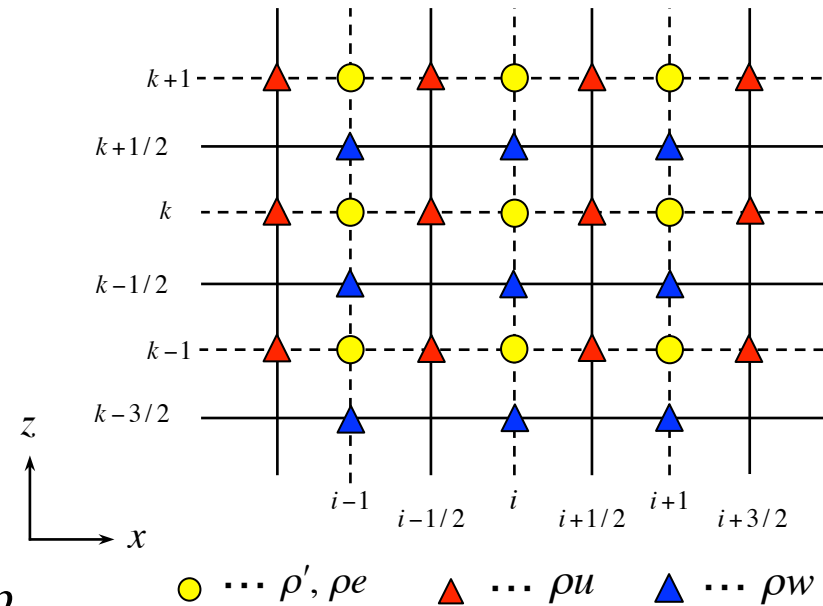
$$\frac{\partial \rho'}{\partial t} = -\frac{\partial \rho u}{\partial x} - \frac{\partial \rho w}{\partial z}$$

$$\frac{\partial \rho u}{\partial t} = -\frac{\partial \rho u u}{\partial x} - \frac{\partial \rho w u}{\partial z} - \frac{\partial p'}{\partial x}$$

$$\frac{\partial \rho w}{\partial t} = -\frac{\partial \rho u w}{\partial x} - \frac{\partial \rho w w}{\partial z} - \frac{\partial p'}{\partial z} - \rho' g$$

$$\frac{\partial \rho e}{\partial t} = -\frac{\partial \rho u h}{\partial x} - \frac{\partial \rho w h}{\partial z} + u \frac{\partial p'}{\partial x} + w \frac{\partial p'}{\partial z} + w \frac{\partial p_s}{\partial z}$$

Here,  $h = e + \frac{p}{\rho}$ ,  $p' = p - p_s$ ,  $\rho' = \rho - \rho_s$



- Discretization

Time integration	RK3 (Williamson 1980)
Spatial difference	Second order central difference scheme
Grid system	C-grid / Lorentz-grid

# 3. Thin-wall approximation

$$F_z \equiv \frac{[dz': \text{the part of grid that appears above the surface}]}{[dz : \text{total vertical grid interval}]}$$

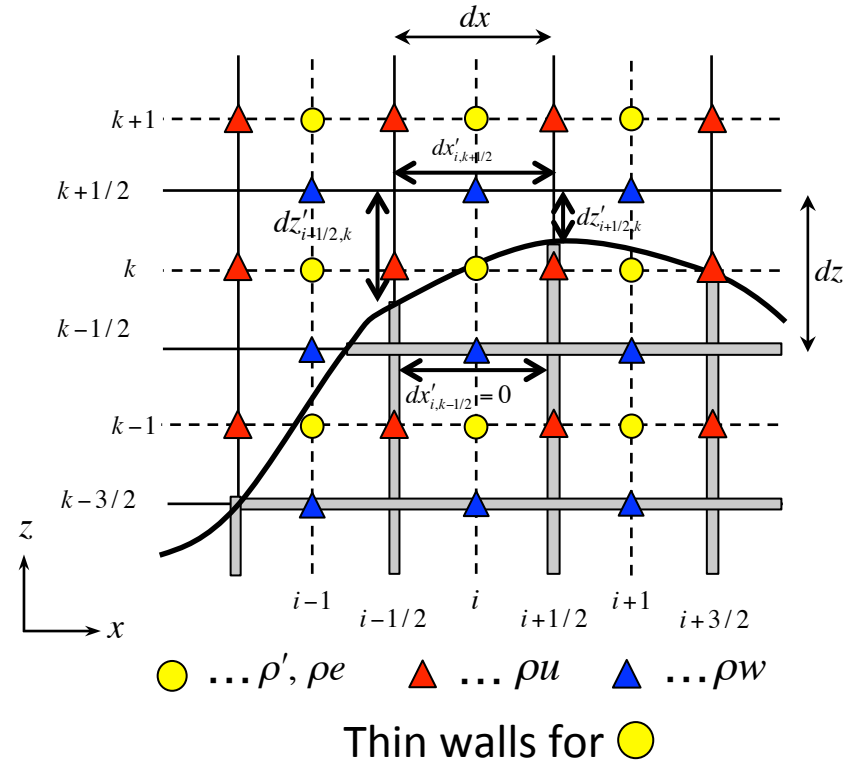
$$F_x \equiv \frac{[dx': \text{the part of grid that appears above the surface}]}{[dx : \text{total horizontal grid interval}]}$$

$$\left(\frac{\partial \rho'}{\partial t}\right)_{i,k} = -\delta_x(\underline{F_z} \rho u) - \delta_z(\underline{F_x} \rho w)$$

$$\left(\frac{\partial \rho u}{\partial t}\right)_{i-1/2,k} = -\delta_x(\underline{F_z} \overline{\rho u}^x \overline{u}^x)_{i-1/2,k} - \delta_z(\underline{F_x} \overline{\rho w}^x \overline{u}^z)_{i-1/2,k} - \delta_x(p')_{i-1/2,k}$$

$$\left(\frac{\partial \rho w}{\partial t}\right)_{i,k-1/2} = -\delta_x(\underline{F_z} \overline{\rho u}^z \overline{w}^x)_{i,k-1/2} - \delta_z(\underline{F_x} \overline{\rho w}^z \overline{w}^z)_{i,k-1/2} - \delta_z(p')_{i,k-1/2} - \overline{\rho'}^z_{i,k-1/2} g$$

$$\left(\frac{\partial \rho e}{\partial t}\right)_{i,k} = -\delta_z(\underline{F_z} \rho u \overline{h}^x)_{i,k} - \delta_z(\underline{F_x} \rho w \overline{h}^z)_{i,k} + \overline{u}^x_{i,k} \delta_x(\overline{p'}^x)_{i,k} + \overline{w}^z_{i,k} \delta_z(\overline{p'}^z)_{i,k} + \overline{w}^z_{i,k} \delta_z(\overline{p}_s^z)_{i,k}$$



# Boundary conditions

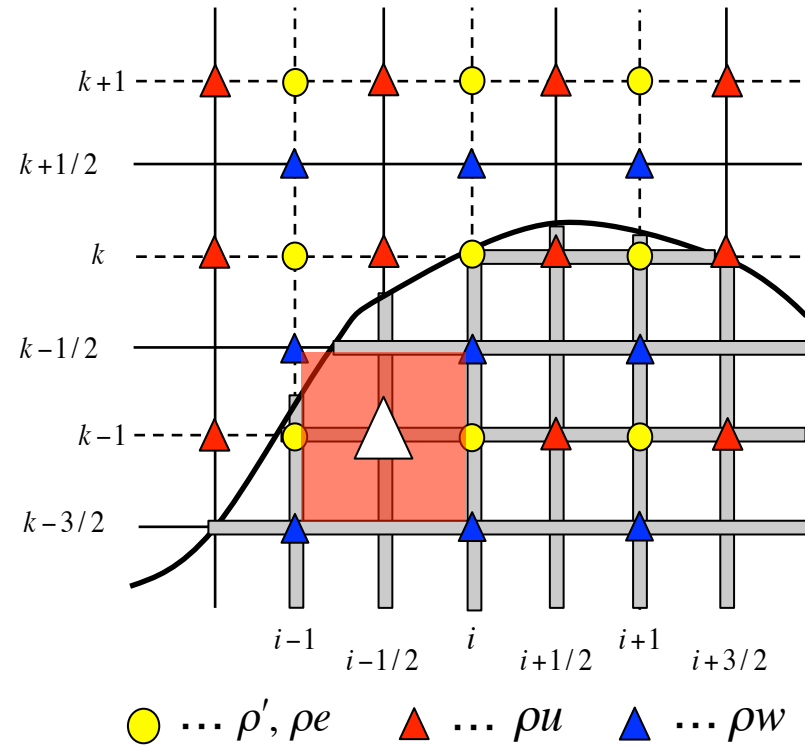
✓ Thin walls are defined at side of a cell for each variable.

→ It is necessary to handle all thin walls depending on a location relative to the surface.

The following conditions are imposed.

$$u_{i-1/2,k} = 0 \quad \text{if} \quad (F_z)_{i-1/2,k} = \frac{(dz')_{i-1/2,k}}{dz} = 0$$

$$w_{i,k-1/2} = 0 \quad \text{if} \quad (F_x)_{i,k-1/2} = \frac{(dx')_{i,k-1/2}}{dx} = 0$$



The velocity is set to zero if the side face of a cell defined scalar quantity is consists of thin wall only.



# Boundary conditions

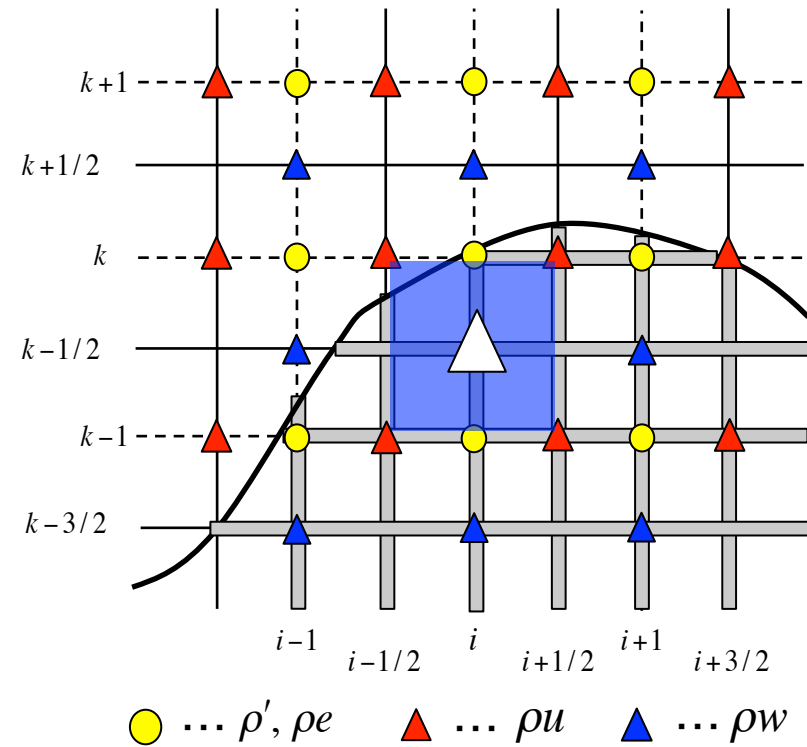
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# Boundary conditions

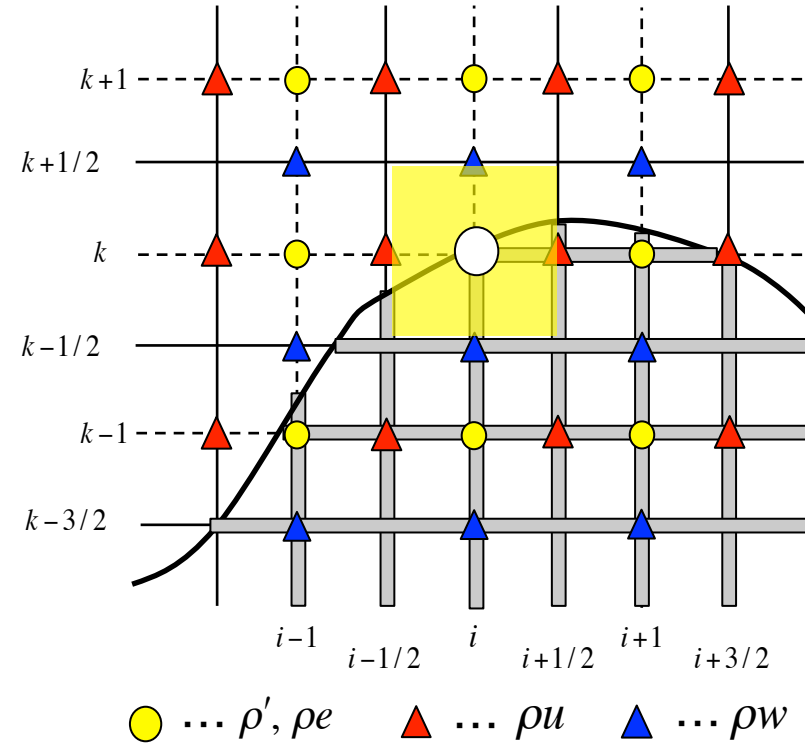
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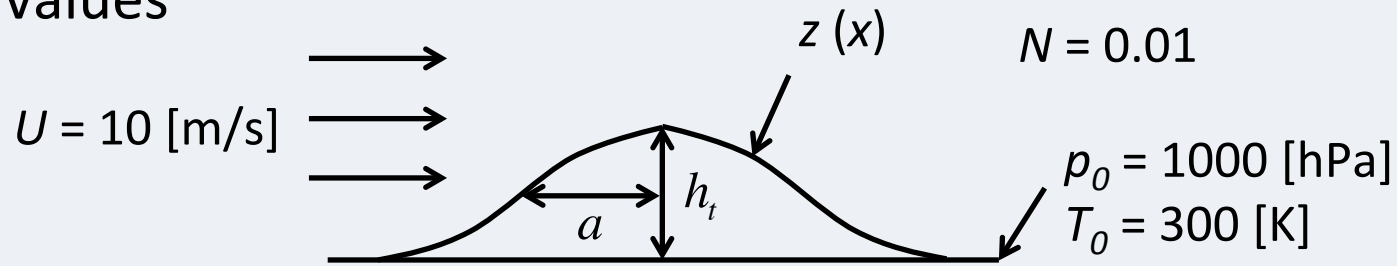
The velocity is set to zero if the side face of a cell defined scalar quantity is consists of thin wall only.

# 4. Mountain wave experiments

## Setup

Domain	4000 [km] × 20 [km]
Resolution	2 [km] × 100 [m]
Time step	$\Delta t = 0.25$ [s]
Boundary condition	Free slip / Periodic

## Initial values



$$z(x) = \frac{h_t a}{x^2 + a^2}$$

$a$  : Half width of the mountain (= 10 [km])  
 $h_t$  : Height of the mountain

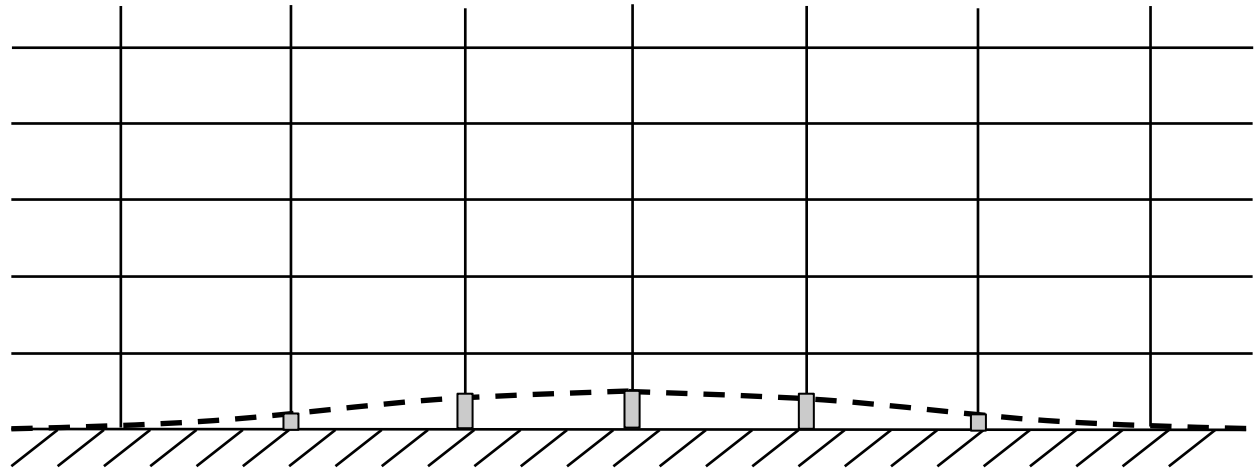
- Sponge layer above 15 [km] height
- 4<sup>th</sup> order numerical diffusion

# The mountain image created from a thin-wall approximation

$\frac{Nh_t}{U}$  : Scorer number ( The index of nonlinearity of the mountain waves )

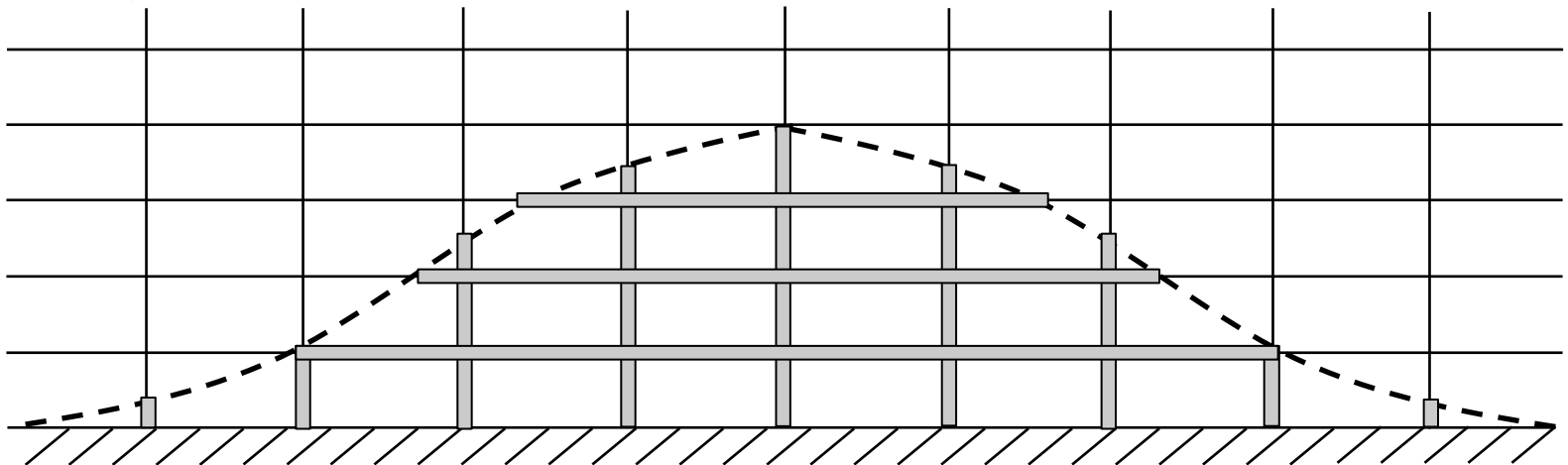
**case A: The height of mountain top is 10m**

$$\frac{Nh_t}{U} = 0.01$$



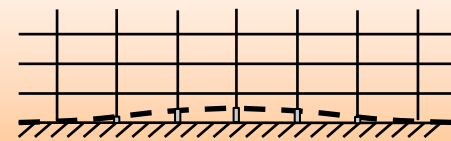
**case B: the height of mountain top is 400m**

$$\frac{Nh_t}{U} = 0.4$$

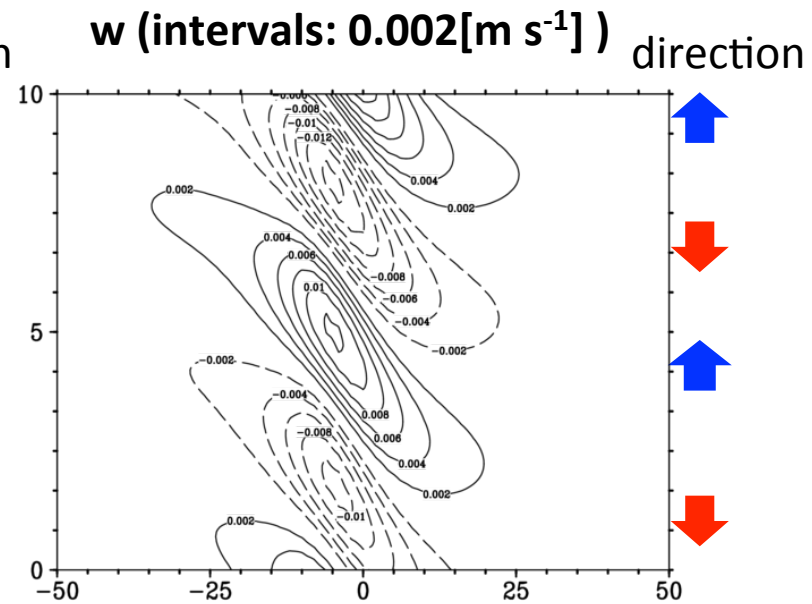
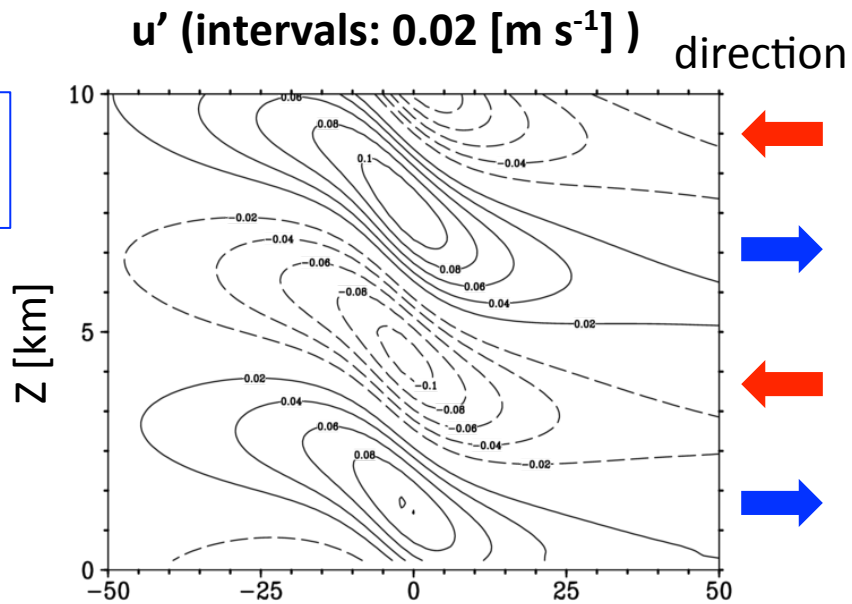


# A: 10m mountain

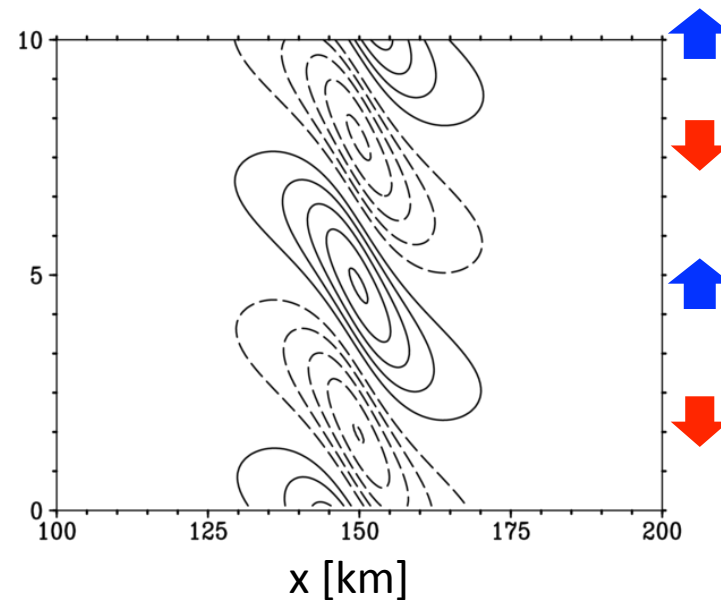
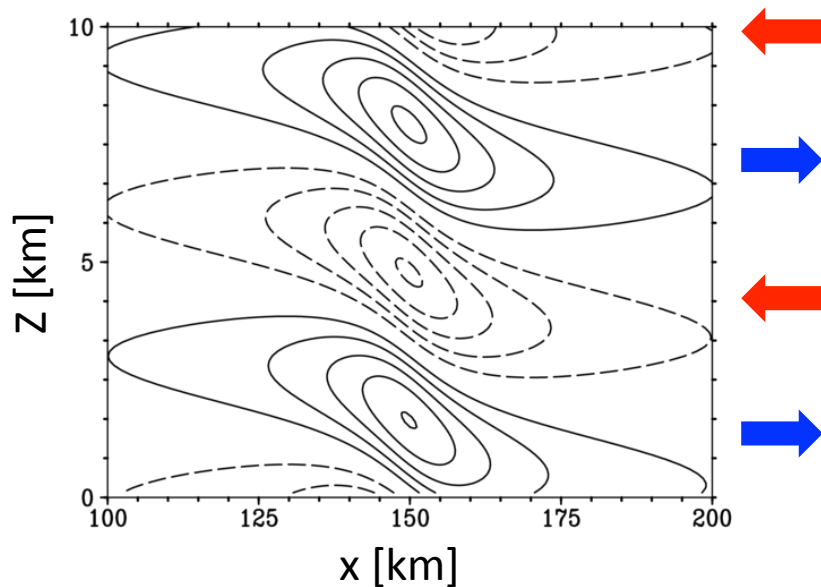
$$\frac{Nh_t}{U} = 0.01$$



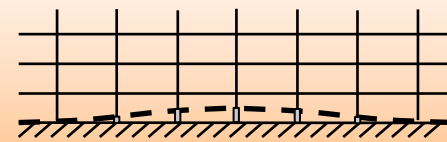
Our model  
After 12 h



Linear  
theory



# A: 10m mountain

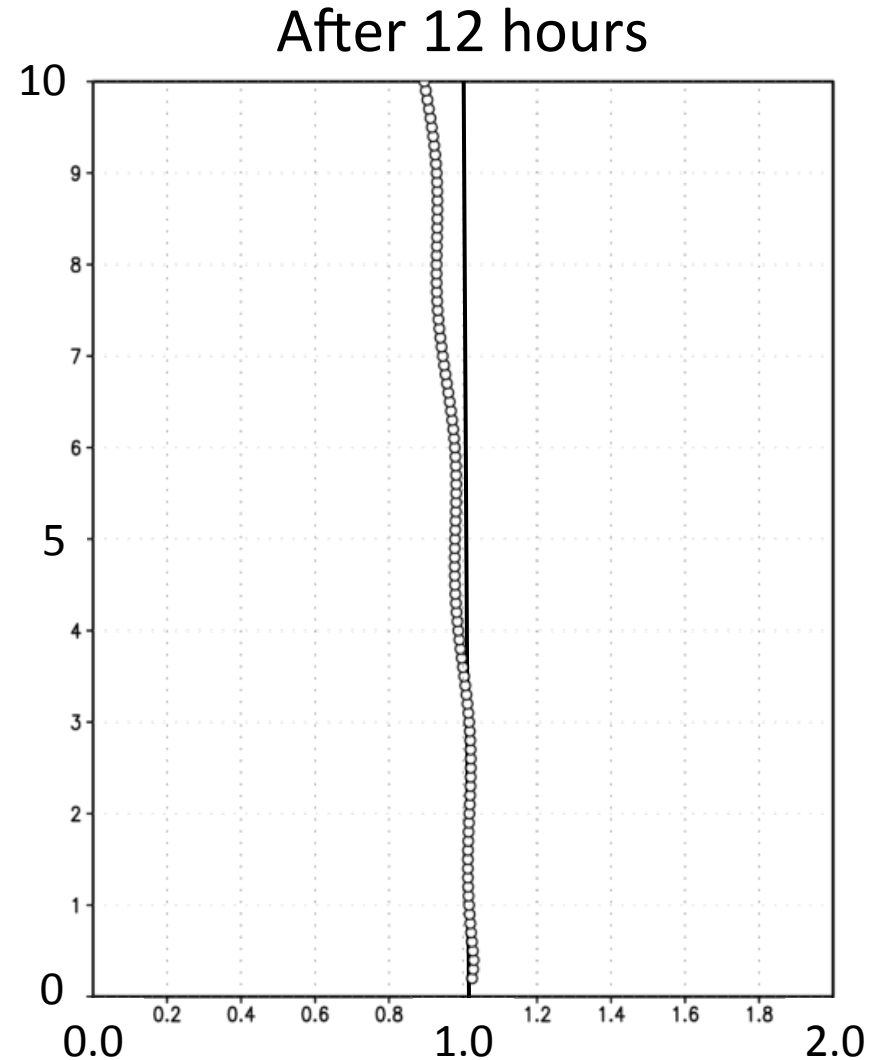


Vertical transport of horizontal momentum flux

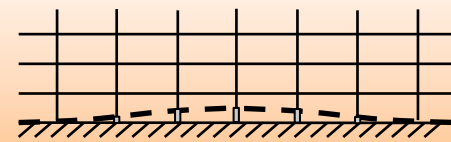
$$MODEL: \rho(z) \sum u'w' \Delta x$$

$$Linear\ theory: \frac{\pi}{4} \rho_0 N U h$$

- ✓ The momentum flux in our model is nearly unity.
- ✓ It agrees well with that of the linear theoretical value



# A: 10m mountain



## Horizontal momentum flux budget analysis

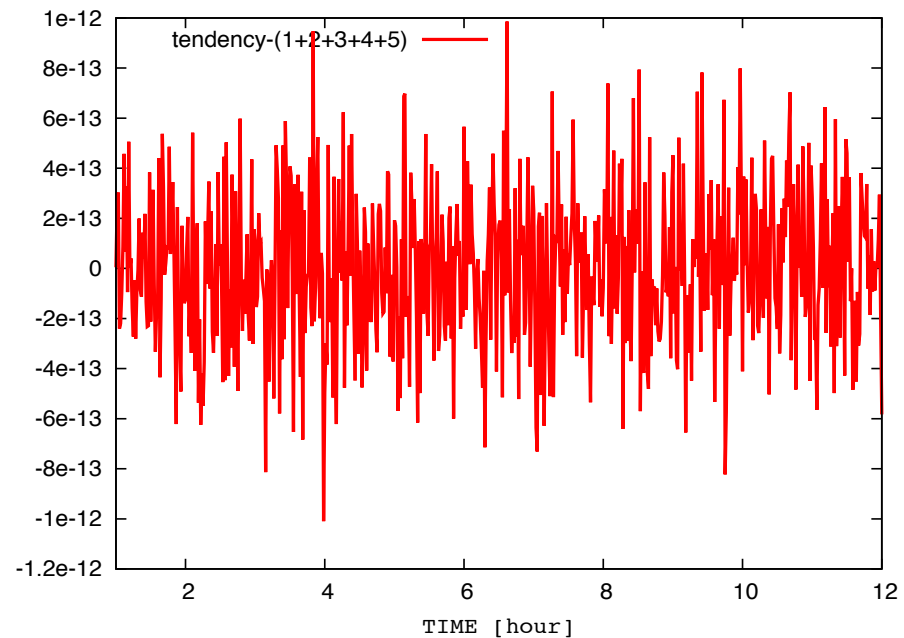
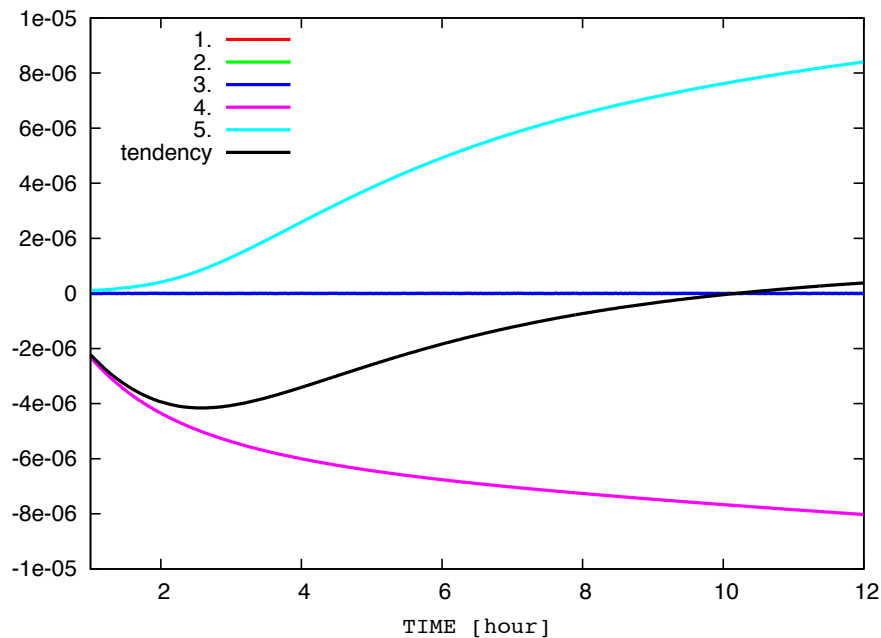
$$\frac{\partial \rho u}{\partial t} = - \frac{\partial F \rho u u}{\partial x} - \frac{\partial F \rho w u}{\partial z} - \frac{\partial p'}{\partial x} + \text{Diff.} + \text{Spong.}$$

tendency  
 1  
 2  
 3  
 4  
 5

tendency

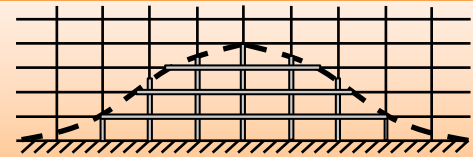
$$- ( \text{1} + \text{2} + \text{3} + \text{4} + \text{5} )$$

$\sim 10^{-13}$



# B: 400m mountain

$$\frac{Nh_t}{U} = 0.4$$

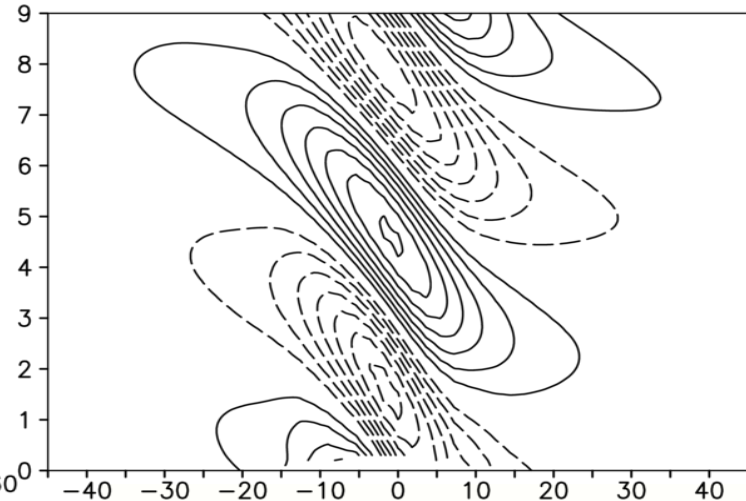
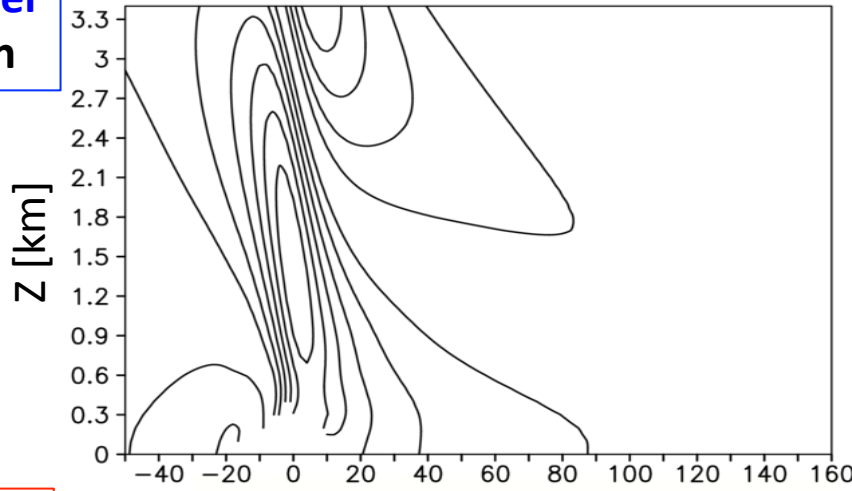


**u (intervals: 0.6 [m s<sup>-1</sup>])**

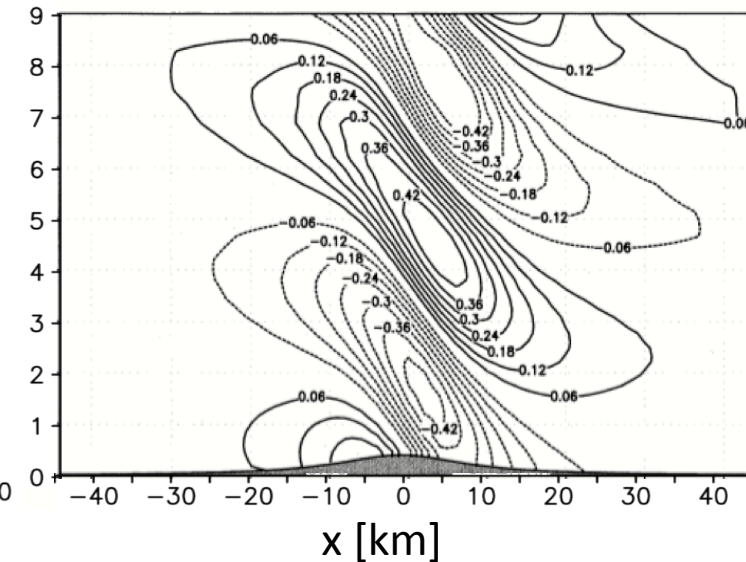
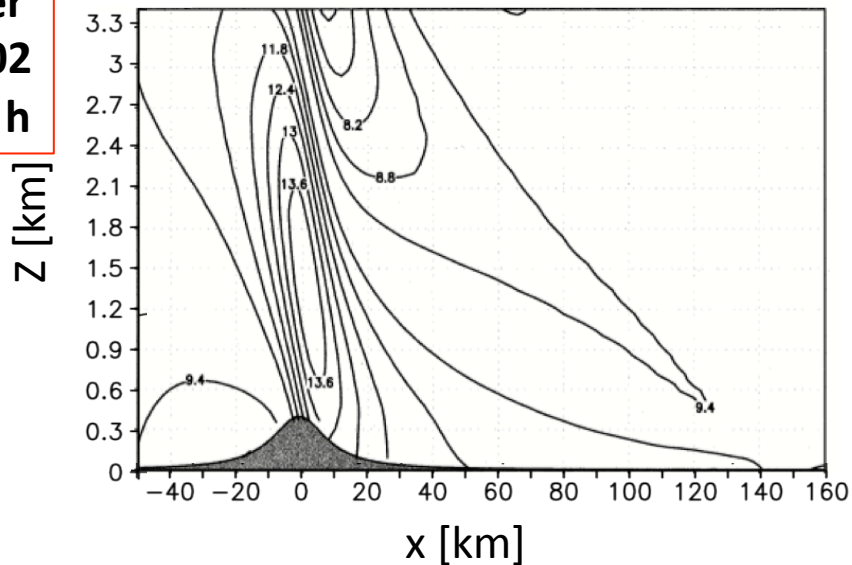
**w (intervals: 0.06 [m s<sup>-1</sup>])**

direction

**Our model  
After 5 h**

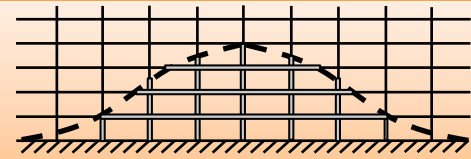


**Steppeler  
et al. 2002  
after 2.5 h**





# B: 400m mountain

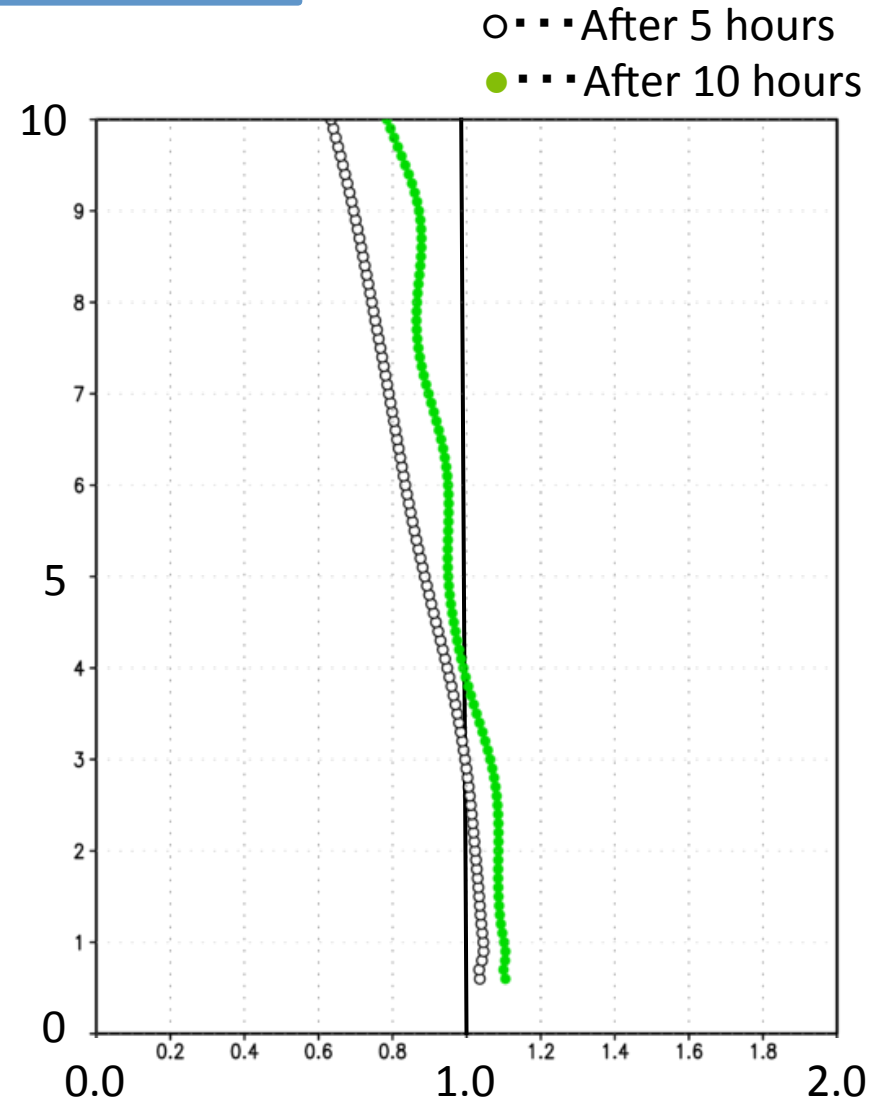


## Vertical transport of horizontal momentum flux

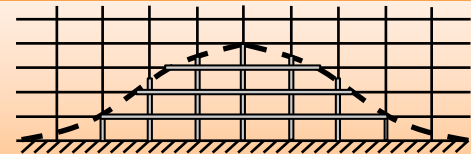
$$MODEL: \rho(z) \sum u'w' \Delta x$$

$$Linear\ theory: \frac{\pi}{4} \rho_0 N U h$$

- ✓ Nonlinear behavior appears for the result after 10 hours.
- ✓ The momentum fluxes are transported toward the upper layer.



# B: 400m mountain



## Horizontal momentum flux budget analysis

$$\frac{\partial \rho u}{\partial t} = - \frac{\partial F \rho u u}{\partial x} - \frac{\partial F \rho w u}{\partial z} - \frac{\partial p'}{\partial x} + \text{Diff.} + \text{Spong.}$$

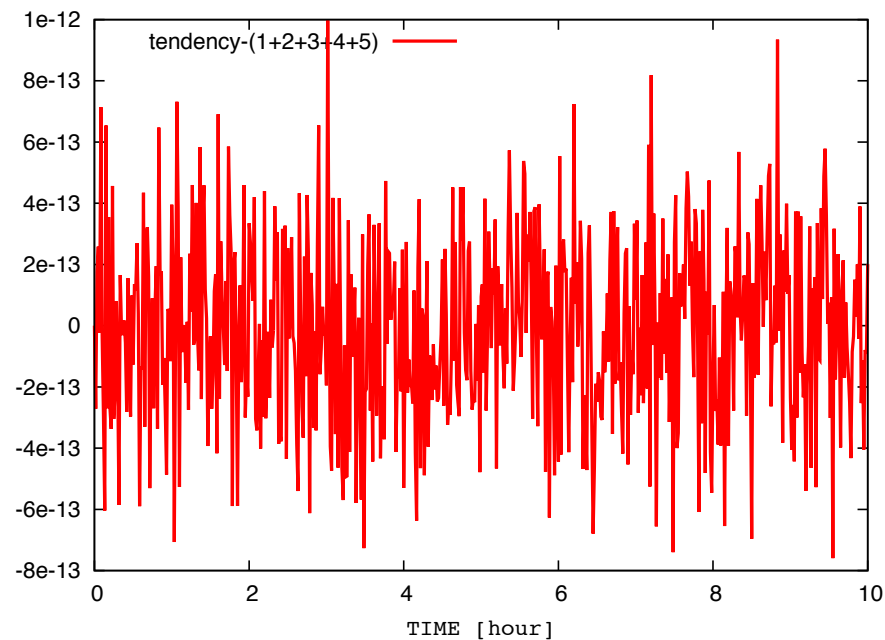
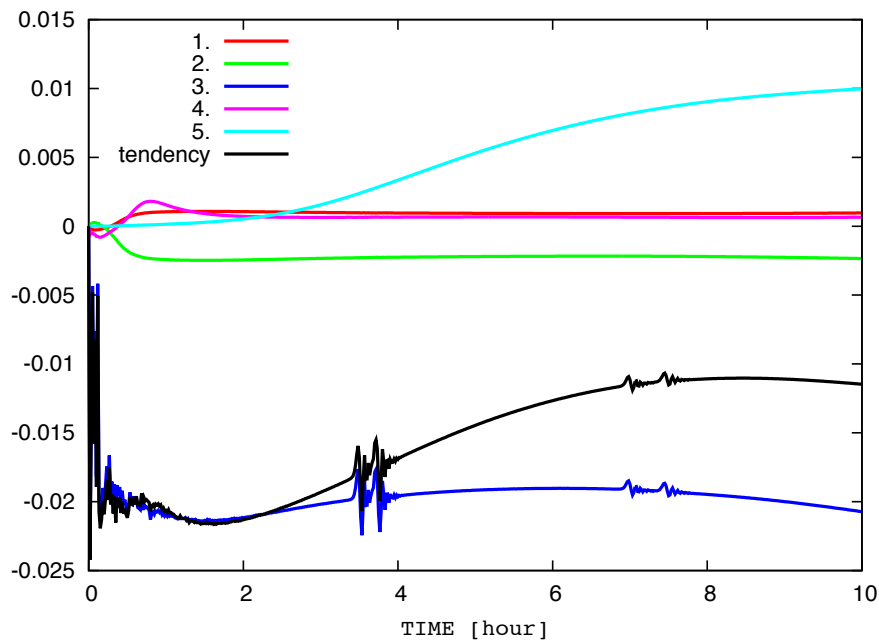
tendency   
 1   
 2   
 3   
 4   
 5

tendency

$$- ( \text{1} + \text{2} + \text{3} + \text{4} + \text{5} )$$
  

$$\sim 10^{-13}$$



# 5. Summary

- ✓ The representation of topography by a thin-wall approximation is implemented to fully compressible flux-form equations.
- ✓ This method addresses the effect of the mountain which height is less than a vertical grid interval.
- ✓ The momentum fluxes are transported toward the upper.
- ✓ The conservation of horizontal momentum flux is confirmed.
- ✓ The future work is to implement a turbulence scheme to this model.