



# Developing the high resolution sea ice forecasting system HAMMER based on regional atmosphere, sea ice and ocean models

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Supported by:



on the basis of a decision  
by the German Bundestag

## IRO-2: Project team and funding

- 6+1 Project partner
- Team @UHH: MI + IfM
- BMWi 2011-09 / 2014-09
- National Masterplan for Maritime Technologies

*FastOpt*

**HSVA**

**O.A.Sys**   
Ocean Atmosphere Systems

 **Universität Hamburg**  
DER FORSCHUNG | DER LEHRE | DER BILDUNG

**AWI** 

 **Universität Bremen**

  
**BUNDESAMT FÜR  
SEESCHIFFFAHRT  
UND  
HYDROGRAPHIE**



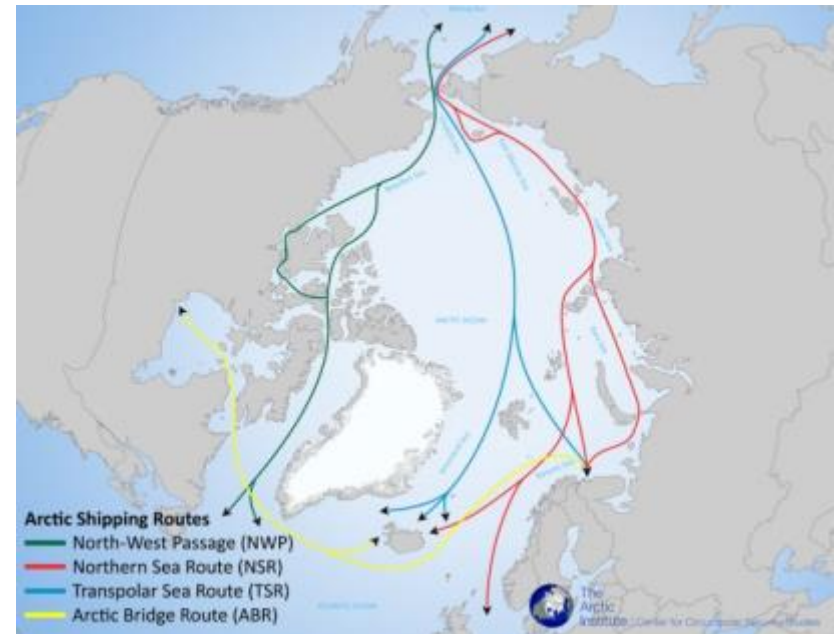
## IRO-2: Mission statement

### ■ Goals

- Safe and economic Arctic shipping  
=> Ship routing based on current and forecasted sea ice conditions
- Responsible operation of platforms  
=> Forecasts for offshore industry
- Arctic engineering and product design  
=> Virtual reality for ship design, classification, insurance ...

### ■ Methods

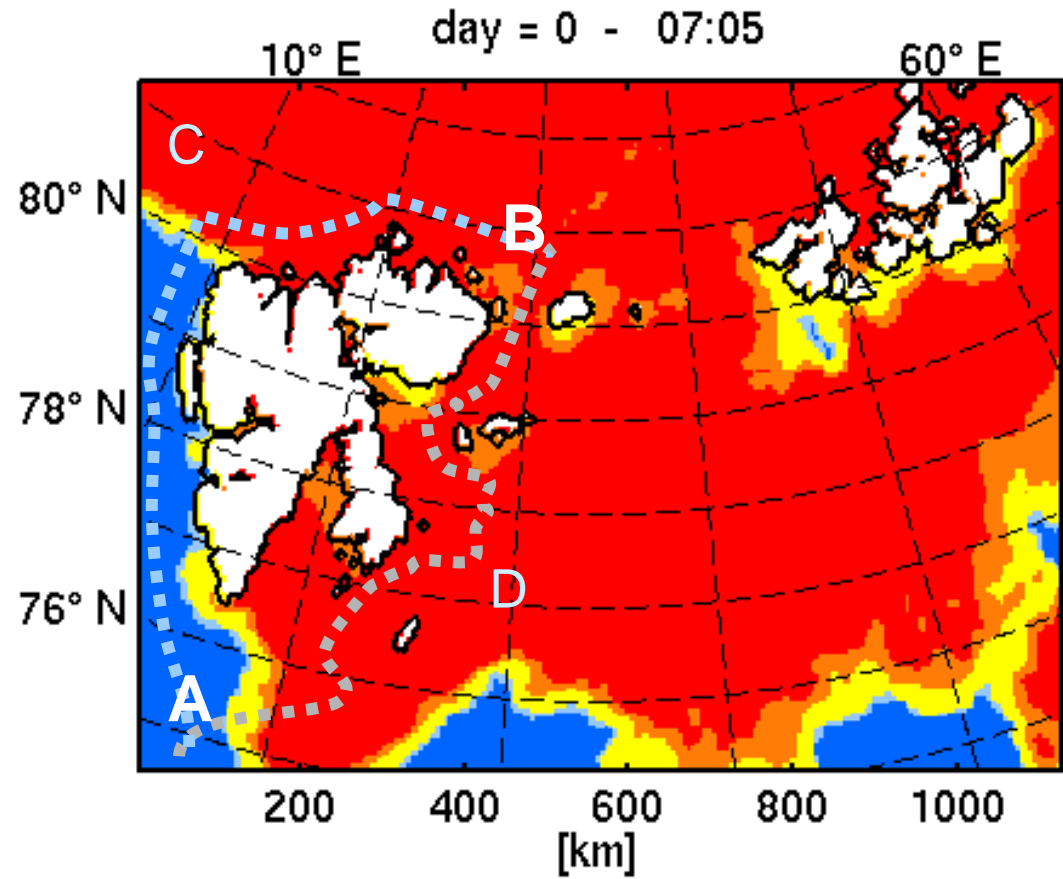
- Remote sensing of sea ice
- Atmosphere/sea-ice/ocean - models
- Ship speed impact model

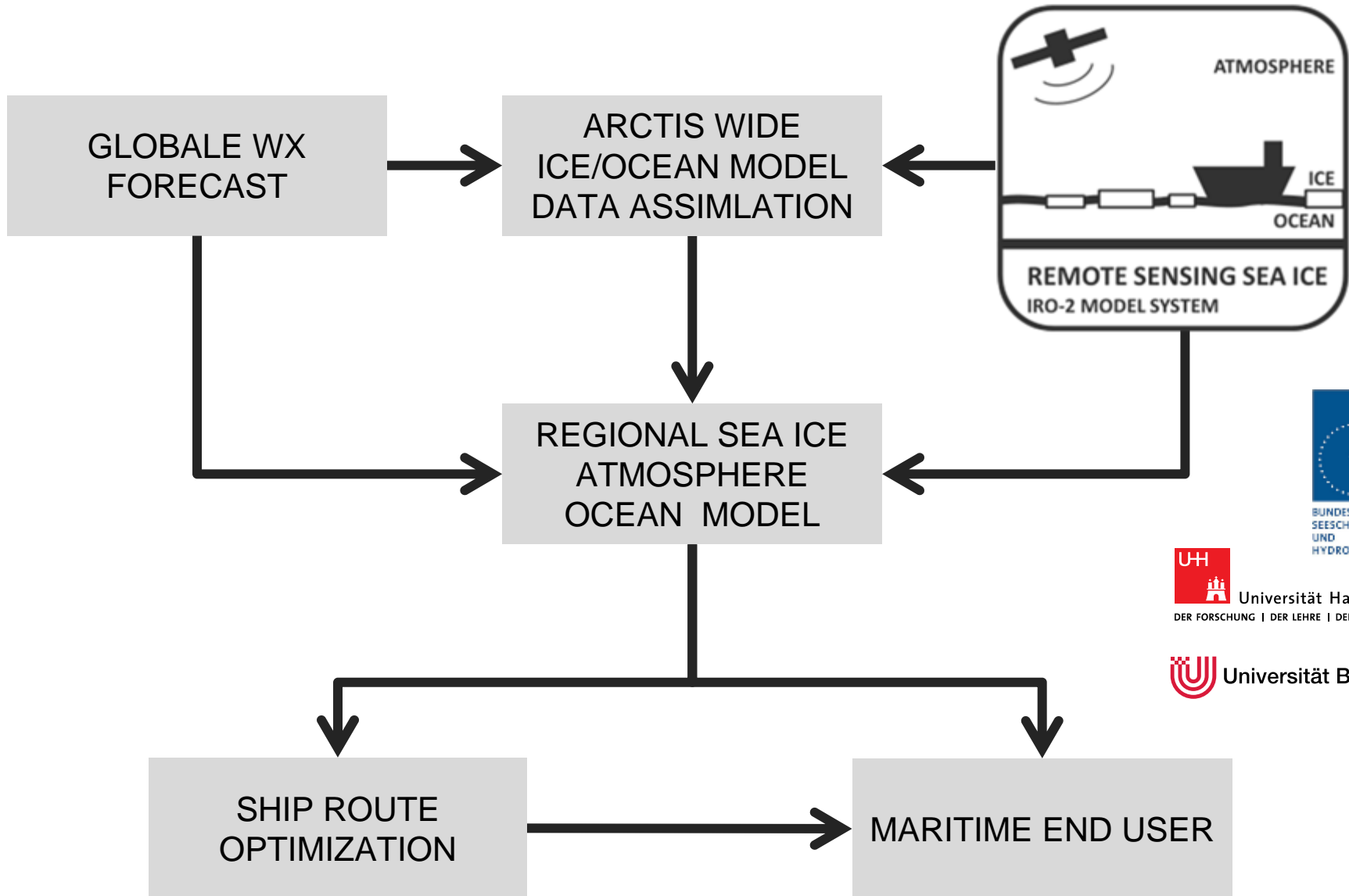


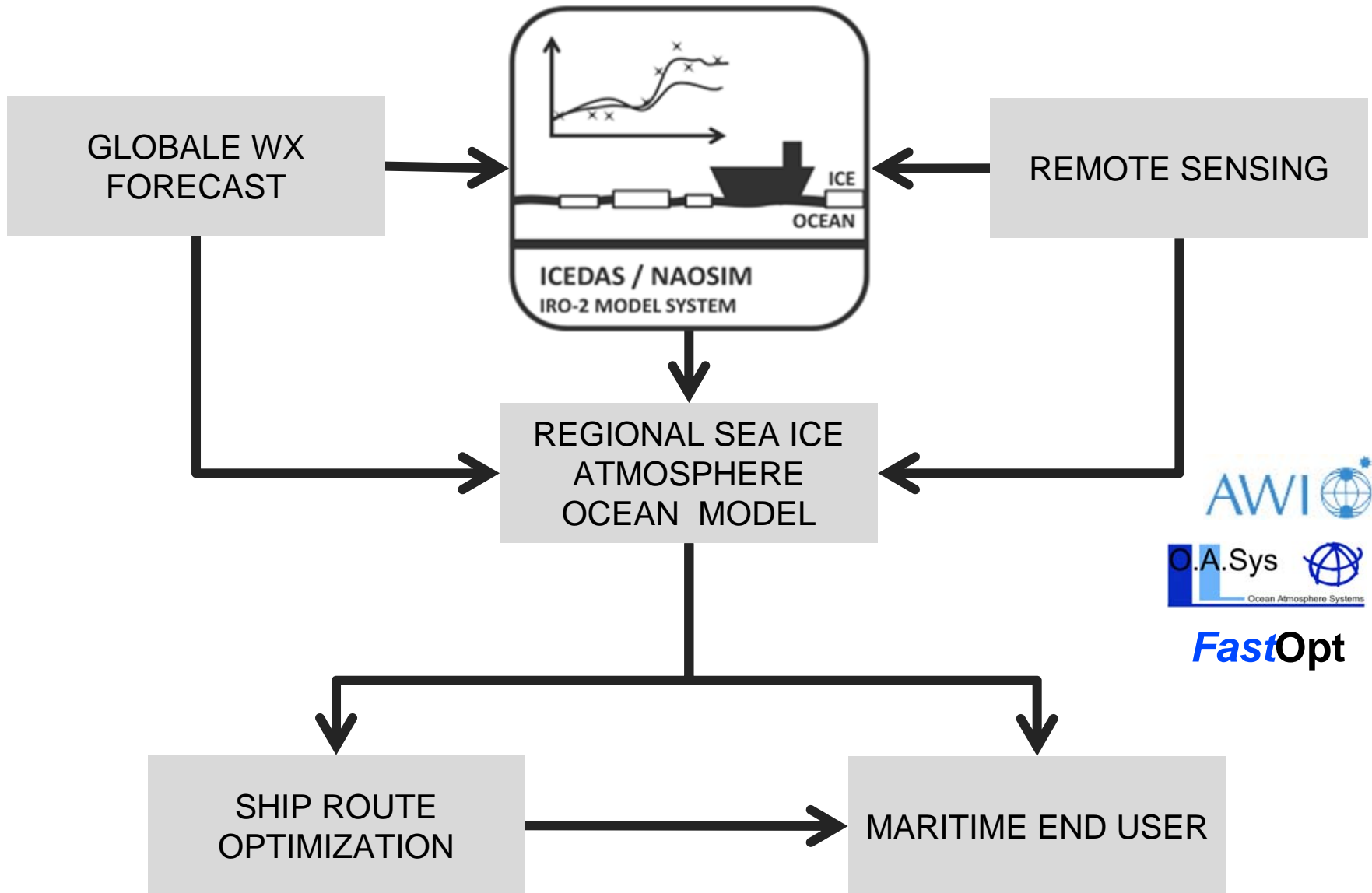
**Humpert, M. and Raspotnik, A. (2012):** The future of Arctic shipping. The Arctic Institute. <http://goo.gl/9Bja3>

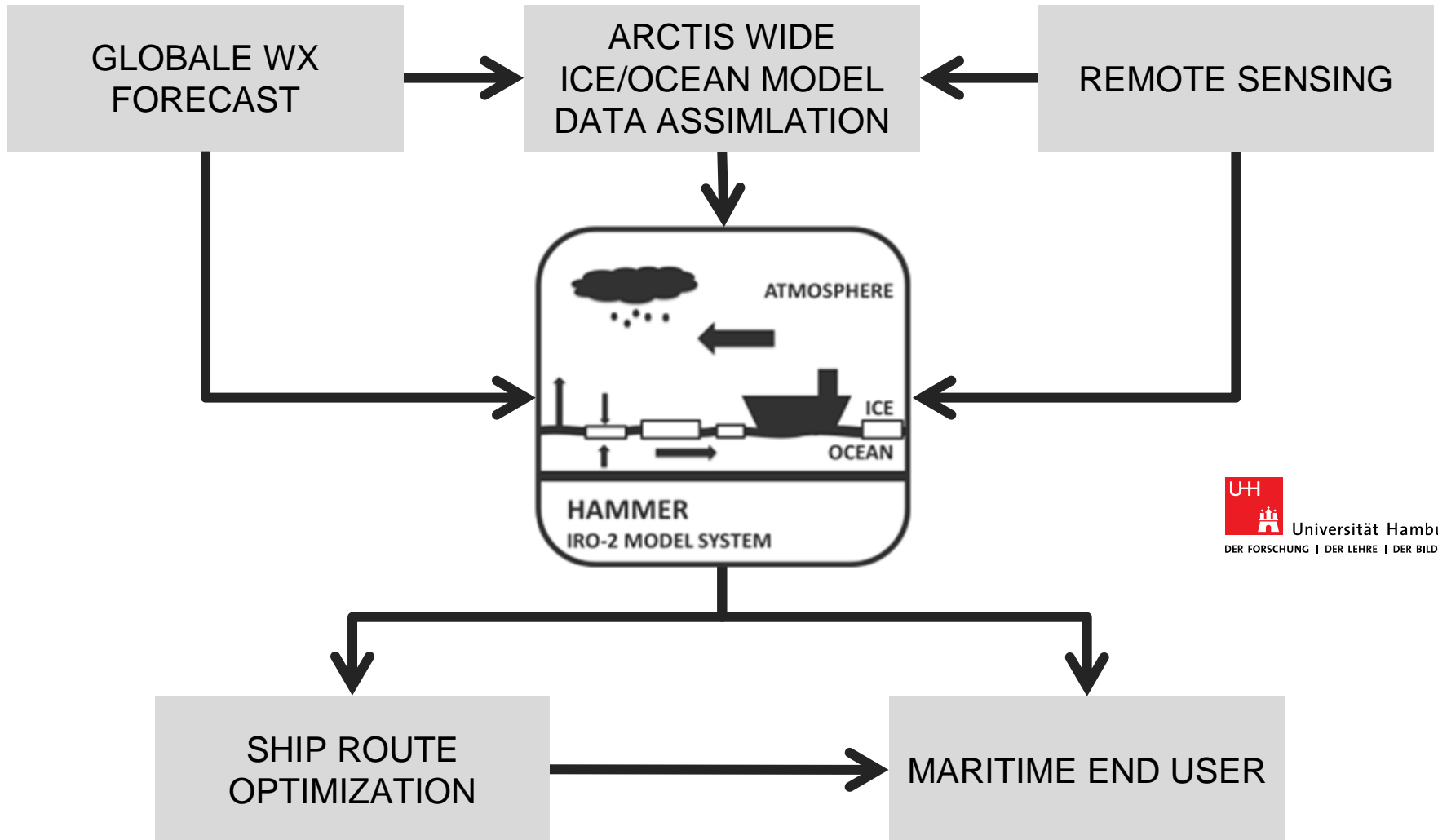
## IRO-2: Practical questions of end users

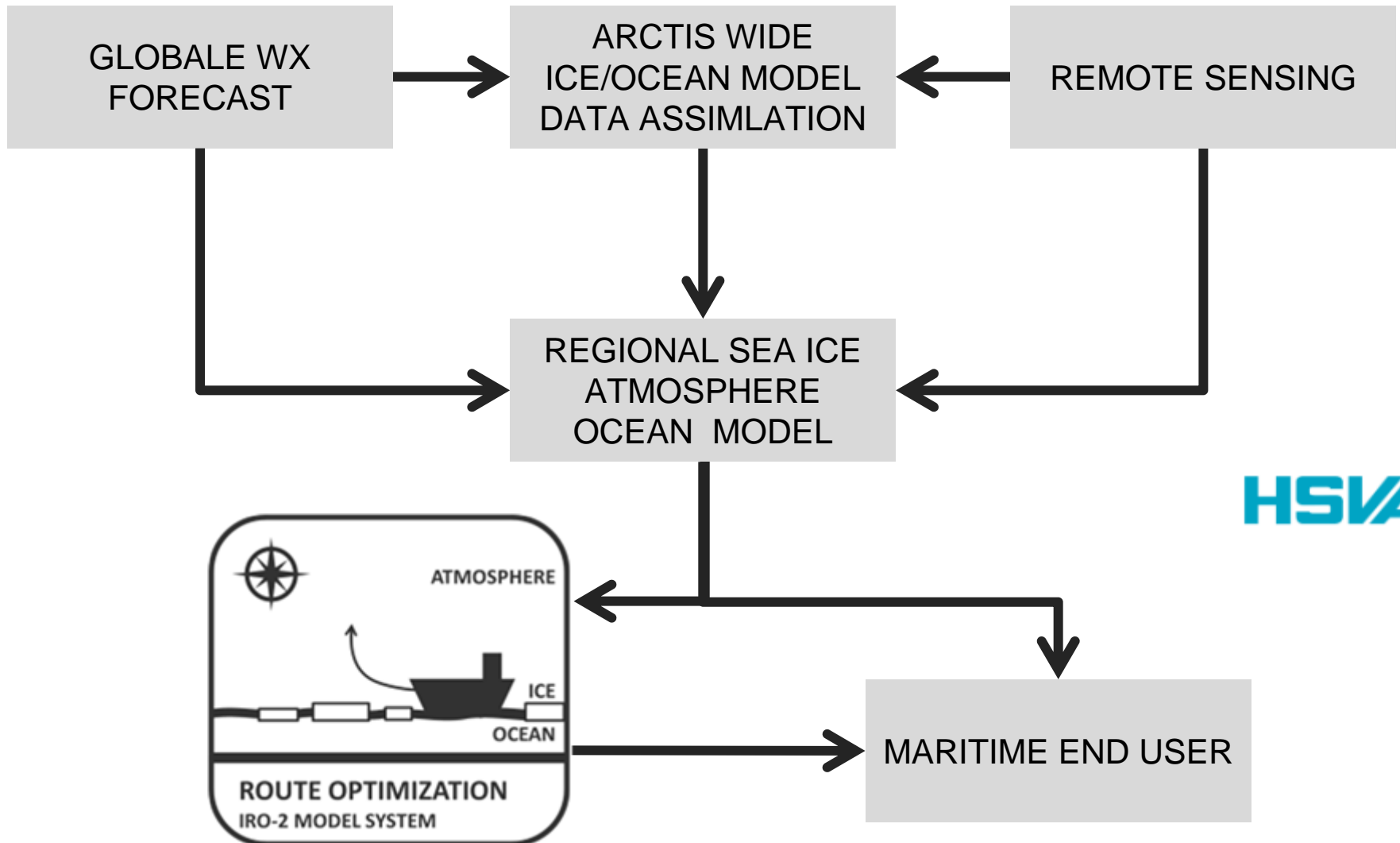
- Best route from A to B?
- Required ice class of ship?
- Estimated travel speed and fuel consumption?
- Risks for crews, charter schedule, environment?



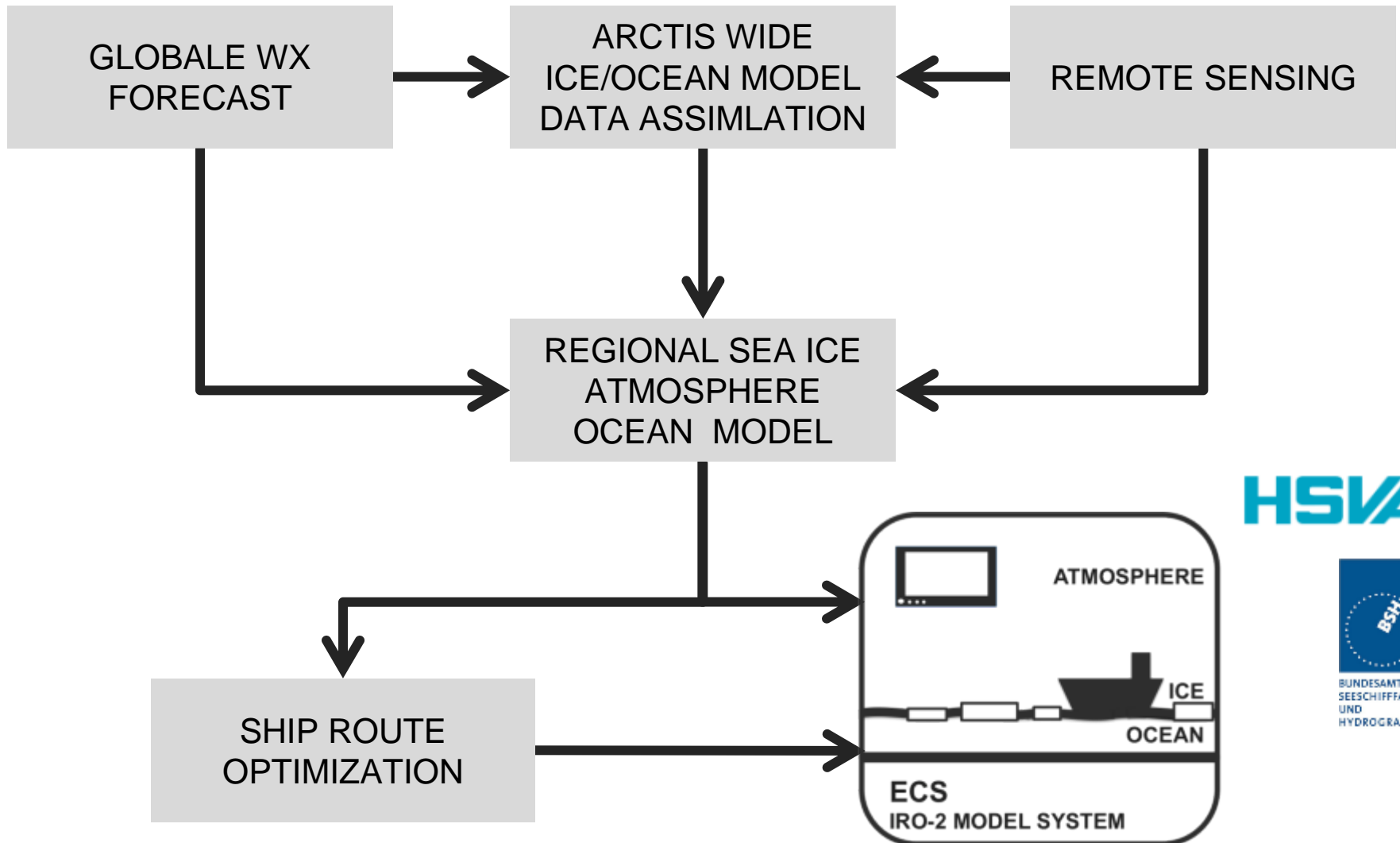








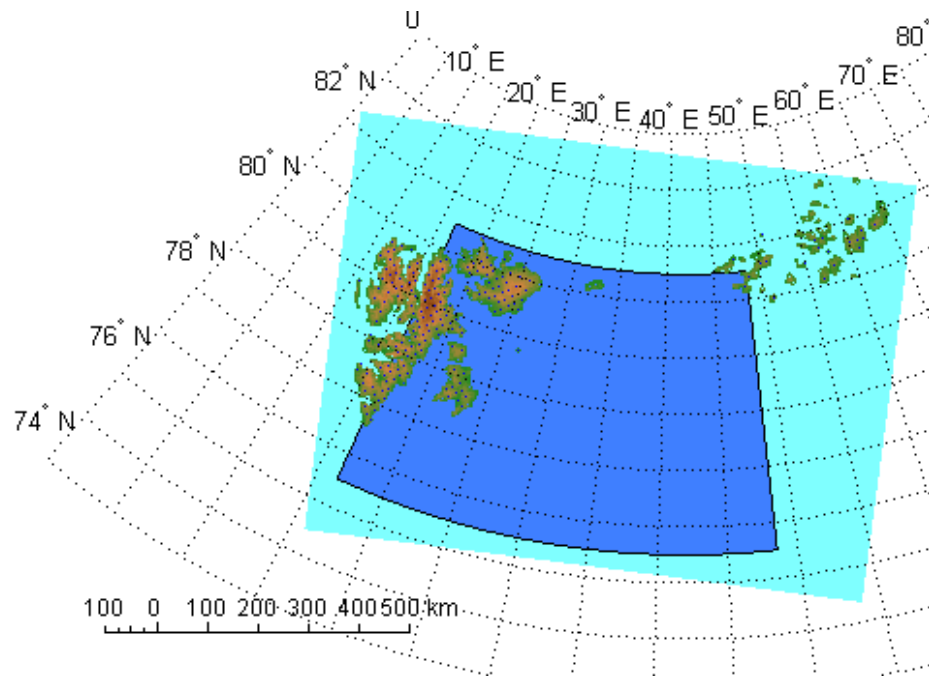




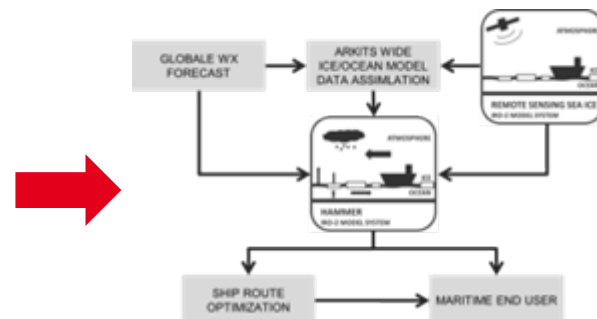
# Modelling @ UHH

## ■ Regional IRO-2 model setup in short

- Test region Barents sea
- 8.300 x 11.250 km
- dx = 5 km
- Few days forecasts
- Running on one IBM Power 6 node
- Atmospheric forcing ECMWF HRES
- Sea ice initial conditions from satellite
- Additional boundary conditions from ICEDAS/NAOSIM
- Coupling regional models for sea ice - atmosphere - ocean

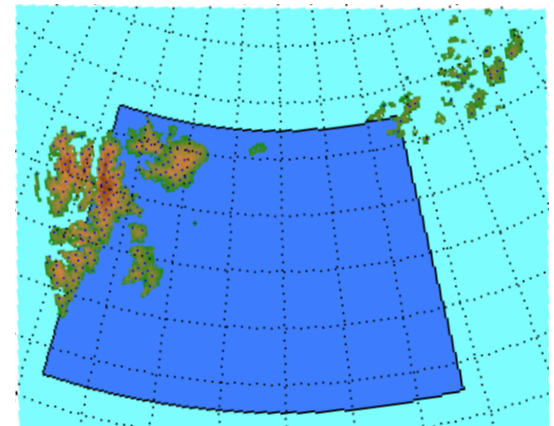
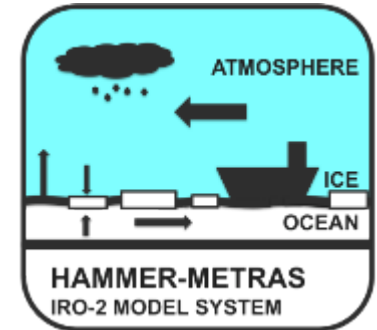


**HAMMER: “Hamburger System für mesoskalige Eisvorhersage zur Routenoptimierung”**



# HAMMER MODEL COMPONENTS

- METRAS - atmosphere
  - Anelastic, Boussinesq approximated non hydrostatic atmospheric model
  - Terrain following coordinates
  - Subgrid scale land use
  - Developed at MI UHH based on Schlünzen (1988)
  
- MESIM – sea ice
  - ...
  
- HAMSOM – ocean
  - ....



# HAMMER MODEL COMPONENTS

- METRAS - atmosphere

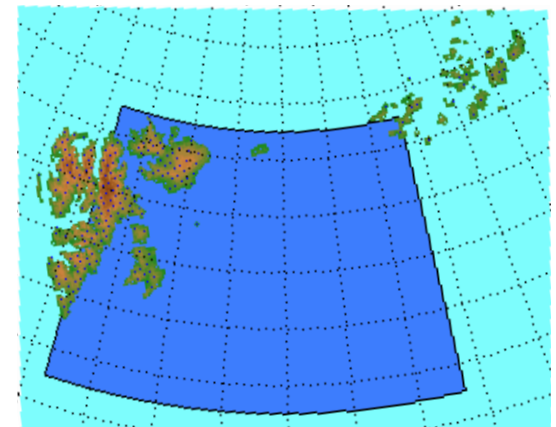
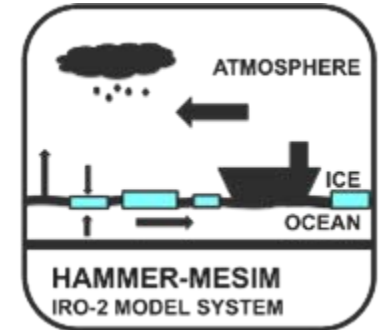
- ...

- MESIM – sea ice

- Multiclass sea ice physics
- Multilayer thermodynamics
- Advection scheme with low diffusion
- Directly coupled to atmospheric model METRAS
- Originally ported from an AWI sea ice model (Birnbaum, 1988), since then under development at MI UHH

- HAMSOM - ocean

- ...



# HAMMER MODEL COMPONENTS

## ■ METRAS – atmosphere

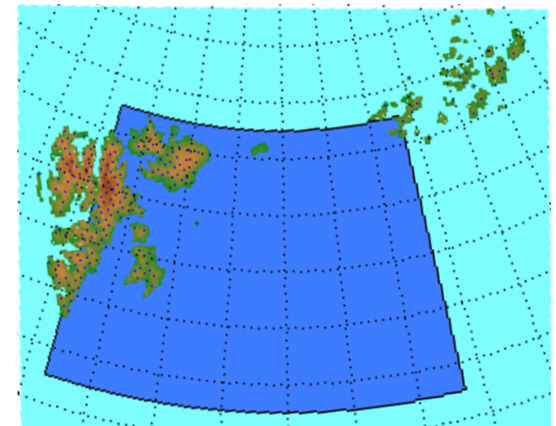
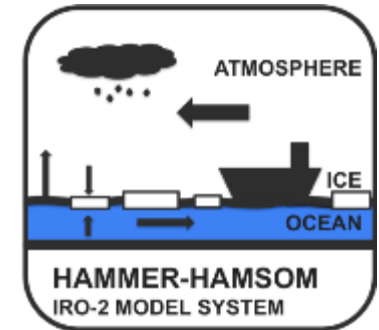
- ...

## ■ MESIM – sea ice

- ...

## ■ HAMSOM – ocean

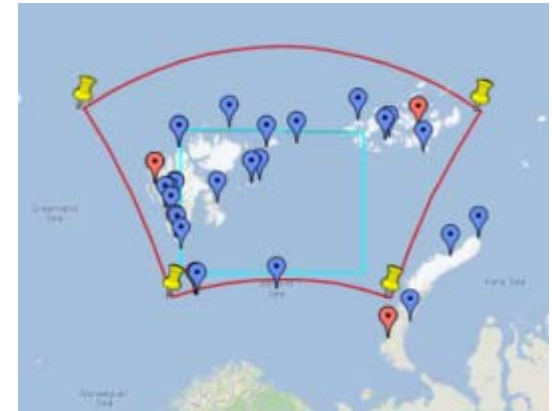
- Shelf ocean model based on primitive equations
- Free surface including equations for temperature and salinity (Pohlmann, 1996)
- Z coordinates, regular lon/lat grid
- Developed at IfM UHH based on Backhaus (1985)



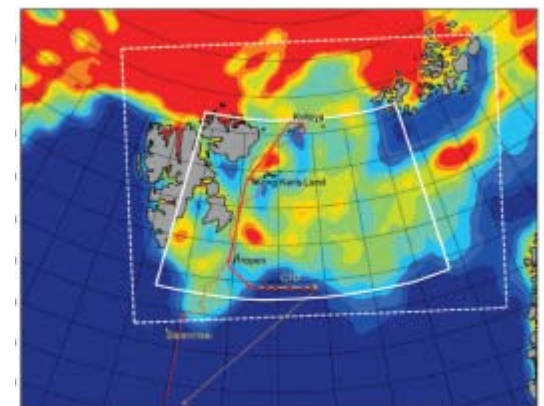
## IRO-2 Validation Experiment - 2014-03

- Ship based measurements
  - 10 days test of forecast and routing system on board of an ICE-1A ship in first year ice
  - Collecting ice, ocean, atmosphere and ship data
  
- Buoy based measurements (CliSAP funding)
  - Approx. 16 buoys to measure ice drift
  - Airplane based deployment in target region
  
- Forecast experiment
  - Operational forecast of sea ice and route conditions
  - Broadcasting to ship including back communication of route planning

Observation 1970-2011  
[www.ncdc.noaa.gov/cdo-web](http://www.ncdc.noaa.gov/cdo-web)



SMOS 2011-04-01



# Development of regional model HAMMER

## ■ Reviewed and improved physics

- Improved use of remote sensing data
- Coupling to ocean (e.g. to get tide influence)
- Checking sensitivity / required processes



## ■ Faster numerics

- ...

## ■ Technology and model system

- ...





# Development of regional model HAMMER

## ■ Reviewed and improved physics

■ ...

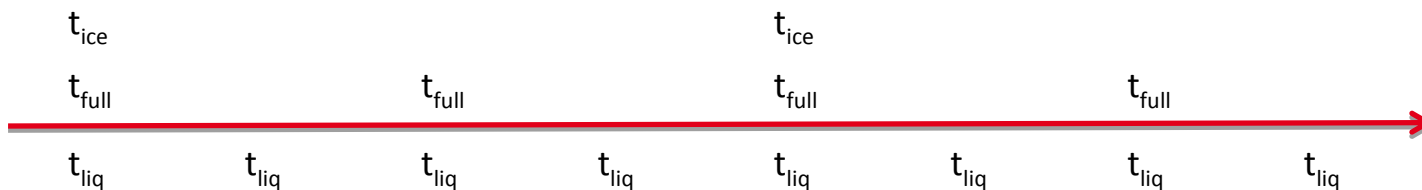
## ■ Faster numerics

■ Pressure solver rewritten by DKRZ

■ Process time-split (cloud physics, sea ice, turbulence)

## ■ Technology and model system

■ ...





# Development of regional model HAMMER

- Reviewed and improved physics

- ...

- Faster numerics

- ...

- Technology and model system

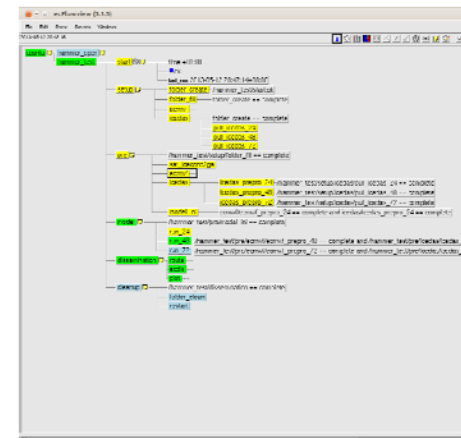
- Embedding in IRO-2 Dataflow

- Development of new operational run suite, useful:

- <https://software.ecmwf.int/ecflow>

- Increase model speed, useful: ScalesTimer Lib

- <https://redmine.dkrz.de/doc/sct/html/>



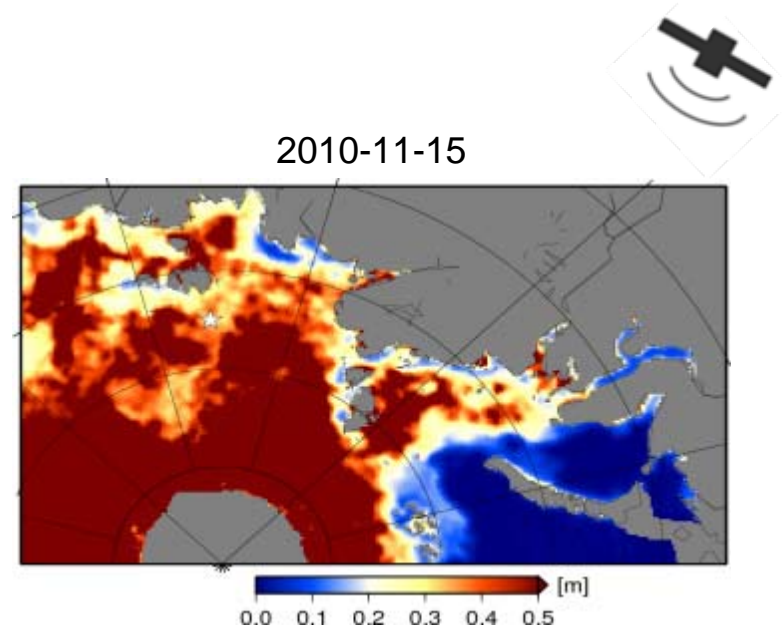
## Model setup: Sea ice initialization

### ■ Sea ice thickness – SMOS

- 1.4 GHz allows to detect the ocean-ice interface for not too thick ice
- Brightness temperature related to sea ice thickness up to 0.5 m
- Daily coverage with 35 km resolution
- Number of interference sources decreasing
- Data at <http://icdc.zmaw.de/smosice.html>

### ■ Sea ice Concentration – AMSR2

- Current re-forecast tests with SSMIS (dx = 12 km)
- Updating to AMSR2 / AMSR-E (dx = 3.125 km, 4-5 km footprint)



**Kaleschke, et al. (2012):** Sea ice thickness retrieval from SMOS brightness temperatures during the Arctic freeze-up period, Geophys. Res. Lett. <http://doi.org/mgv>

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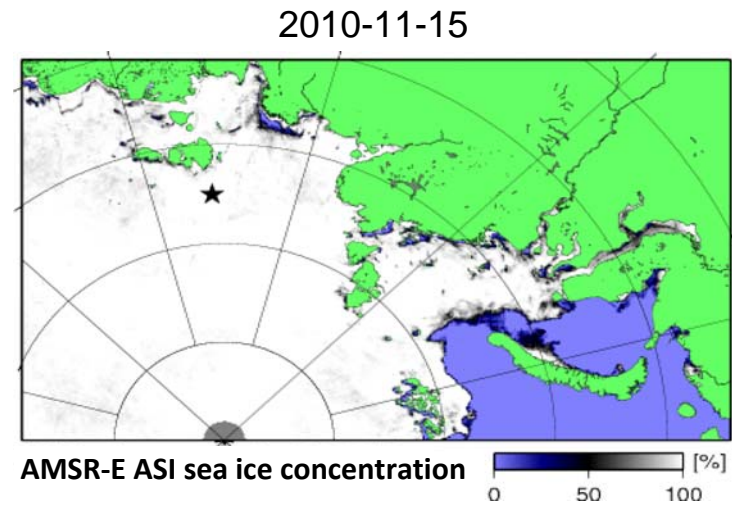


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Spren, G., L. Kaleschke, and G. Heygster (2008): Sea ice remote sensing using AMSR-E 89-GHz channels, J. Geophys. Res., 113, C02S03, <http://doi.org/cgfzk8>

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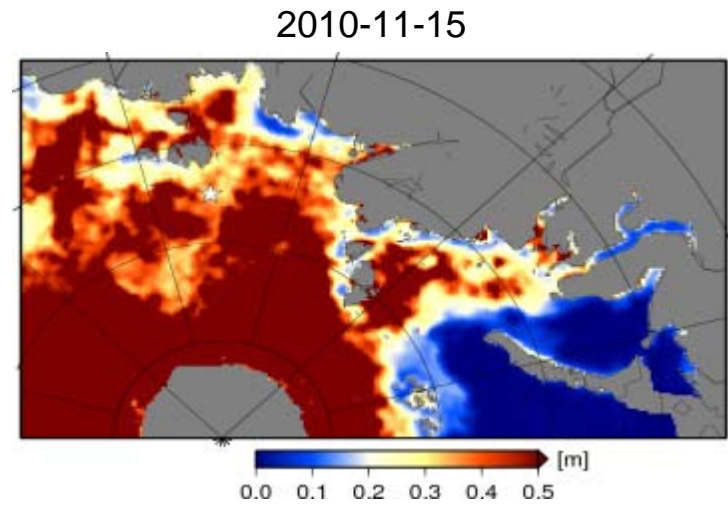


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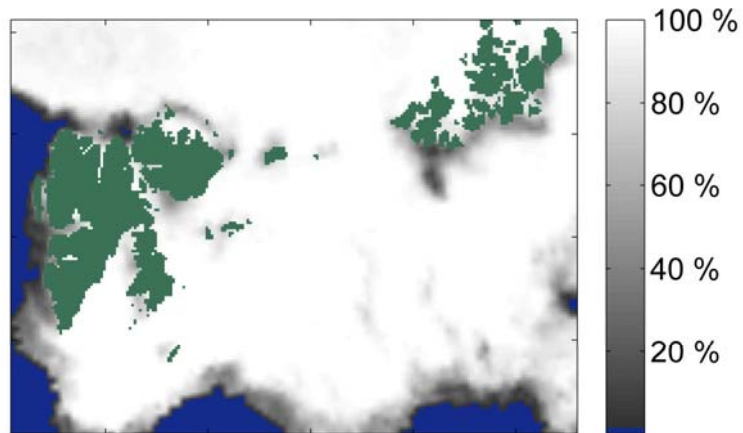


**Kaleschke, et al. (2012):** Sea ice thickness retrieval from SMOS brightness temperatures during the Arctic freeze-up period, *Geophys. Res. Lett.* <http://doi.org/mgv>

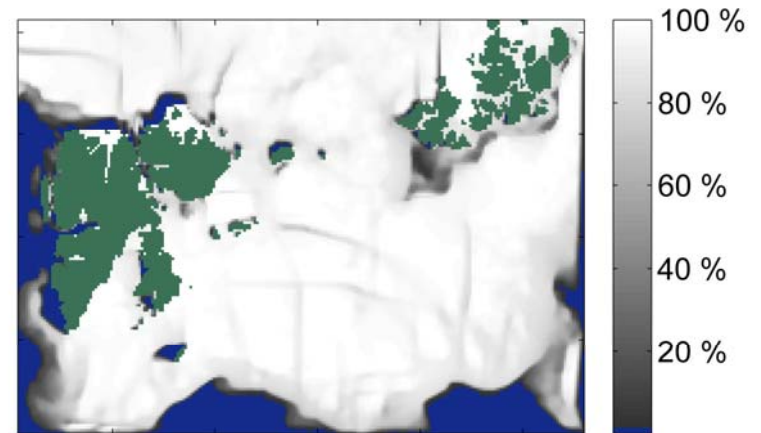


# Sea ice concentration: simulation vs. observation

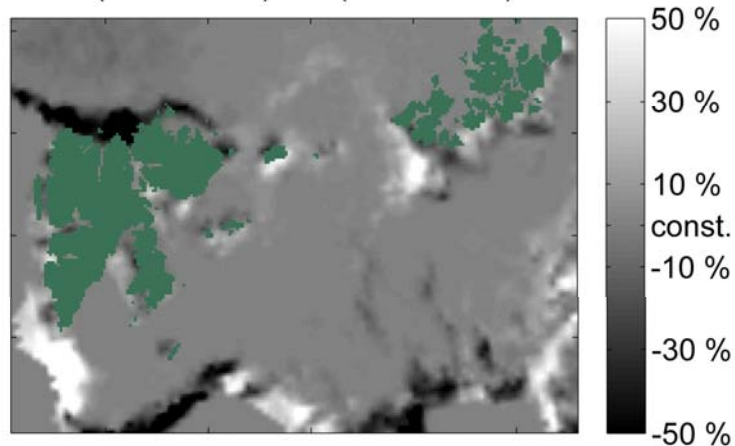
Satellite 2011-04-03



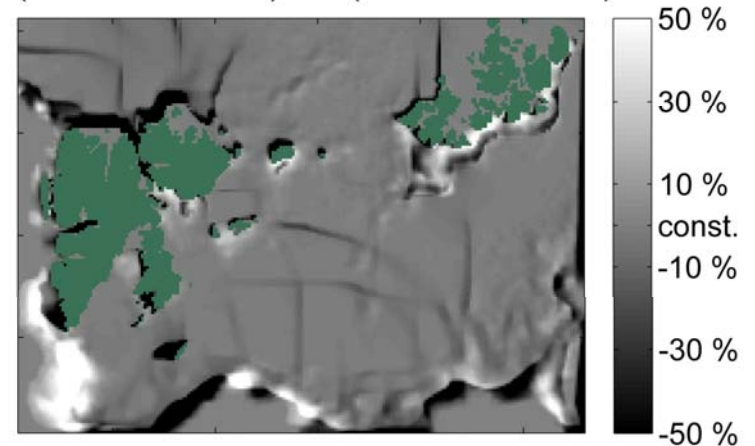
Model 2011-04-03 08:00



S(2011-04-03) - S(2011-04-01)

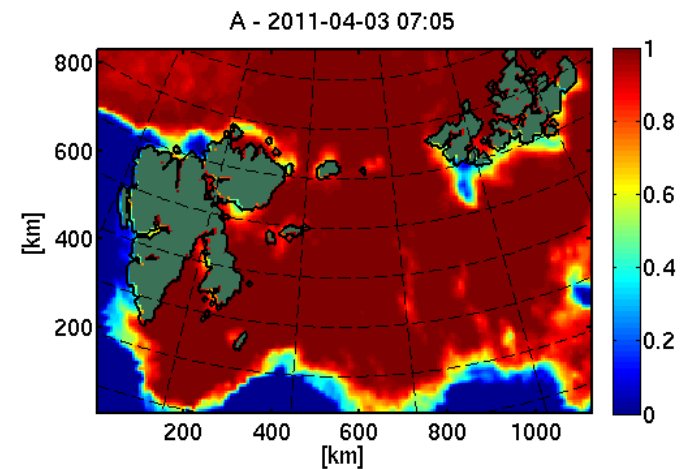
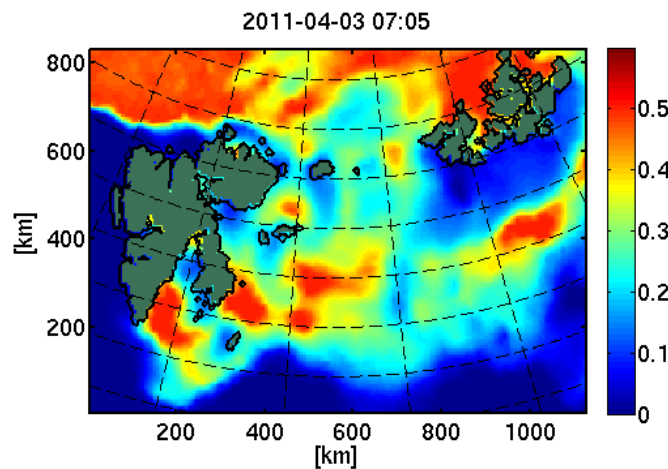
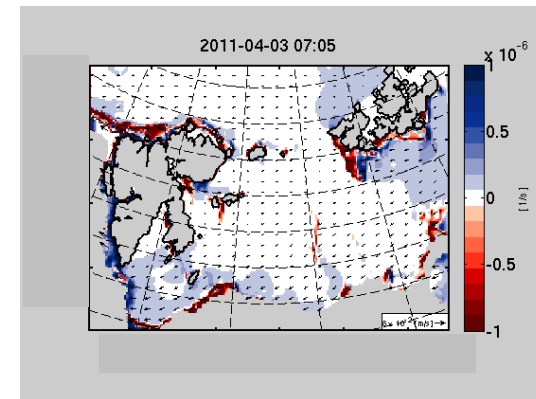


M(2011-04-03 08:00) - M(2011-04-01 08:00)



# Motion of vessels in ice covered waters

- Data needed from models
  - Weather conditions
  - Sea ice thickness
  - Sea ice concentration
  - Ridges and Leads (sub grid scale)
  - Near surface currents



## Known challenges and limits

- Challenges we try to target ourselves
  - Speed to improve possible resolution / domain size / forecast length
  - Robustness and validation of model system
  - Improvement of physical features
  
- Limitations currently out of our control
  - Limited band width for data transfer to high latitudes
  - Only few observations in the Arctic
  - Dependence on driving models



## Summary

- Development HAMMER
  - Regional model based on METRAS, MESIM & HAMSOM
  - Prototype as component for maritime decision support system
  - Main focus on system development by including
  
- IRO-2
  - Remote sensing of sea ice
  - Arctic wide sea ice / ocean data assimilation
  - Regional atmosphere / sea ice / ocean modeling
  - Ship specific impact model
  - Validation experiment in 2014-03



# Discussion on regional sea ice / atmosphere modelling

- Ideas
- Comments
- Questions

